

1. The reduced column echelon form of the matrix whose columns are the spanning vectors of \mathbf{U}_1 is

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -5 & 6 & 0 \\ -7 & 9 & 0 \end{pmatrix},$$

and its first two nonzero columns can be taken as a basis.

The reduced column echelon form of the matrix whose columns are the spanning vectors of \mathbf{U}_2 is

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\frac{16}{5} & \frac{17}{5} & -\frac{4}{5} & 0 \end{pmatrix},$$

and its first three nonzero columns can be taken as a basis.

2. The intersection is described by the system of equations

$$\mathbf{a}_1\mathbf{g}_1 + \mathbf{a}_2\mathbf{g}_2 - \mathbf{b}_1\mathbf{h}_1 - \mathbf{b}_2\mathbf{h}_2 - \mathbf{b}_3\mathbf{h}_3 = \mathbf{0},$$

where we denote by $\mathbf{g}_1, \mathbf{g}_2$ the basis of \mathbf{U}_1 we found, and by $\mathbf{h}_1, \mathbf{h}_2, \mathbf{h}_3$ the basis of \mathbf{U}_2 . The matrix of this system of equations is

$$\begin{pmatrix} 1 & 0 & -1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ -5 & 6 & 0 & 0 & -1 \\ -7 & 9 & \frac{16}{5} & -\frac{17}{5} & \frac{4}{5} \end{pmatrix}$$

and its reduced row echelon form is

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 & \frac{3}{2} \\ 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 1 & \frac{3}{2} \end{pmatrix}$$

so \mathbf{b}_3 is a free variable. Setting $\mathbf{b}_3 = t$, we obtain $\mathbf{a}_1 = -2t$, $\mathbf{a}_2 = -\frac{3}{2}t$. The corresponding basis

vector $\mathbf{a}_1\mathbf{g}_1 + \mathbf{a}_2\mathbf{g}_2$ is $\begin{pmatrix} -2 \\ -\frac{3}{2} \\ 1 \\ \frac{1}{2} \end{pmatrix}$.

3. Reducing the basis vectors of \mathbf{U}_1 using the basis vector we just found, we obtain the matrix

$$\begin{pmatrix} 0 & 0 \\ -\frac{3}{4} & 1 \\ -\frac{7}{2} & 6 \\ -\frac{27}{4} & 9 \end{pmatrix},$$

and the reduced column echelon form of this matrix is easily seen to be

$$\begin{pmatrix} 0 & 0 \\ 1 & 0 \\ 6 & 0 \\ 9 & 0 \end{pmatrix},$$

so the vector $\begin{pmatrix} 0 \\ 1 \\ 6 \\ 9 \end{pmatrix}$ can be taken as the relative basis vector.

4. Reducing the basis vectors of \mathbf{U}_2 using the basis vector we found, we obtain the matrix

$$\begin{pmatrix} 0 & 0 & 0 \\ -\frac{3}{4} & 1 & 0 \\ \frac{1}{2} & 0 & 1 \\ -\frac{59}{20} & \frac{17}{5} & -\frac{4}{5} \end{pmatrix},$$

and the reduced column echelon form of this matrix is manifestly

$$\begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ \frac{17}{5} & -\frac{4}{5} & 0 \end{pmatrix},$$

so its two nonzero columns can be taken as the relative basis.

5. For $\mathbf{U} = \text{span}(\mathbf{v}_1, \mathbf{v}_2)$ to be invariant, it is necessary and sufficient to have $\varphi(\mathbf{v}_1), \varphi(\mathbf{v}_2) \in \mathbf{U}$. Indeed, this condition is necessary because we must have $\varphi(\mathbf{U}) \subset \mathbf{U}$, and it is sufficient because each vector of \mathbf{U} is a linear combination of \mathbf{v}_1 and \mathbf{v}_2 .

We have $\varphi(\mathbf{v}_1) = A\mathbf{v}_1 = \begin{pmatrix} -5 \\ 10 \\ -13 \end{pmatrix}$ and $\varphi(\mathbf{v}_2) = A\mathbf{v}_2 = \begin{pmatrix} -1 \\ 2 \\ 0 \end{pmatrix}$. It just remains to see if there are

scalars x, y such that $\varphi(\mathbf{v}_1) = x\mathbf{v}_1 + y\mathbf{v}_2$ and scalars z, t such that $\varphi(\mathbf{v}_2) = z\mathbf{v}_1 + t\mathbf{v}_2$. Solving the corresponding systems of linear equations, we see that there are solutions: $\varphi(\mathbf{v}_1) = 2\mathbf{v}_1 - 3\mathbf{v}_2$ and $\varphi(\mathbf{v}_2) = 3\mathbf{v}_1 + 2\mathbf{v}_2$. Therefore, this subspace is invariant.