

MA 1111/1212: Linear Algebra  
Tutorial problems, December 4, 2014

**1. (a)** Let us compute the images of the basis vectors:  $1 \mapsto (3 - 7i) \cdot 1 = 3 - 7i$ ,  $i \mapsto (3 - 7i) \cdot i = 7 + 3i$ . This instantly leads to the matrix  $\begin{pmatrix} 3 & 7 \\ -7 & 3 \end{pmatrix}$ .

**(b)** Let us compute the images of the basis vectors:

$$e_1 \mapsto \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} -1 & -1 \\ 1 & 0 \end{pmatrix} = -e_1 - e_2 + e_3,$$

$$e_2 \mapsto \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = -e_1 + e_4,$$

$$e_3 \mapsto \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = e_1 - e_4,$$

$$e_4 \mapsto \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix} = e_2 - e_3 + e_4.$$

This immediately leads to the matrix

$$\begin{pmatrix} -1 & -1 & 1 & 0 \\ -1 & 0 & 0 & 1 \\ 1 & 0 & 0 & -1 \\ 0 & 1 & -1 & 1 \end{pmatrix}.$$

**2. (a)** Let us compute the transition matrix  $M_{e,f}$ . Solving the systems of equations  $f_1 = c_{11}e_1 + c_{21}e_2$  and  $f_2 = c_{12}e_1 + c_{22}e_2$ , we get  $c_{11} = 7$ ,  $c_{21} = -3$ ,  $c_{12} = 30$ ,  $c_{22} = -13$ , therefore  $M_{e,f} = \begin{pmatrix} 7 & 30 \\ -3 & -13 \end{pmatrix}$ . Therefore, we have

$$A_{\varphi,f} = M_{e,f}^{-1} A_{\varphi,e} M_{e,f} = \begin{pmatrix} 171 & 731 \\ -40 & -171 \end{pmatrix}.$$

**(b)** We clearly have  $M_{v,e} = \begin{pmatrix} 1 & 2 \\ 1 & 3 \end{pmatrix}$ , therefore  $M_{e,v} = M_{v,e}^{-1} = \begin{pmatrix} 3 & -2 \\ -1 & 1 \end{pmatrix}$ . Therefore,

$$A_{\varphi,v} = M_{e,v}^{-1} A_{\varphi,e} M_{e,v} = \begin{pmatrix} 5 & -3 \\ 8 & -5 \end{pmatrix}.$$

**3.** As the hint suggests,  $Ax = c \cdot x$  can be rewritten as  $(A - c \cdot I_2)x = 0$ . This system has a nontrivial solution if and only if  $\det(A - c \cdot I_2) = 0$ . Writing  $A = \begin{pmatrix} x & y \\ z & t \end{pmatrix}$ , we rewrite  $\det(A - c \cdot I_2)$  as

$$\det \begin{pmatrix} x - c & y \\ z & t - c \end{pmatrix} = (x - c)(t - c) - yz = (xt - yz) - c(x + t) + c^2 = c^2 = c \operatorname{tr}(A) + \det(A),$$

as required.