

MA 216 Assignment 2

Due 15 November 2006

*Solutions*

1. Solve

$$\begin{aligned}x'(t) &= 22x(t) - 49y(t), \\y'(t) &= 9x(t) - 20y(t).\end{aligned}$$

*Solution:* The equation in matrix form is

$$\begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix} = \begin{pmatrix} 22 & -49 \\ 9 & -20 \end{pmatrix} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}.$$

The characteristic polynomial is

$$\det\left(\begin{pmatrix} \lambda - 22 & 49 \\ -9 & \lambda + 20 \end{pmatrix}\right) = \lambda^2 - 2\lambda + 1 = (\lambda - 1)^2.$$

The Jordan canonical form is then

$$J = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}.$$

It cannot be  $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$  because that would give  $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ , independently of what  $P$  is. Once we know  $J$ , the matrix  $P$  is then found by solving the system  $AP = PJ$ ,

$$\begin{aligned}22p_{11} - 49p_{21} &= 1p_{11} + 1p_{12} & 22p_{12} - 49p_{22} &= 0p_{11} + 1p_{12} \\9p_{11} - 20p_{21} &= 1p_{21} + 1p_{22} & 9p_{12} - 20p_{22} &= 0p_{21} + 1p_{22}\end{aligned}$$

A solution is

$$P = \begin{pmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{pmatrix} = \begin{pmatrix} 5 & 7 \\ 2 & 3 \end{pmatrix}.$$

You may well get a different solution, since the space of solutions is two dimensional, but you should get the same answer in the end. Inverting,

$$P^{-1} = \begin{pmatrix} 3 & -7 \\ -2 & 5 \end{pmatrix}.$$

We can calculate  $\exp(tJ)$  as follows. Since

$$\begin{pmatrix} t & 0 \\ t & t \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ t & 0 \end{pmatrix} + \begin{pmatrix} t & 0 \\ 0 & t \end{pmatrix}$$

and

$$\begin{pmatrix} 0 & 0 \\ t & 0 \end{pmatrix} \begin{pmatrix} t & 0 \\ 0 & t \end{pmatrix} = \begin{pmatrix} t & 0 \\ 0 & t \end{pmatrix} \begin{pmatrix} 0 & 0 \\ t & 0 \end{pmatrix}$$

we know that

$$\exp\left(\begin{pmatrix} t & 0 \\ t & t \end{pmatrix}\right) = \exp\left(\begin{pmatrix} 0 & 0 \\ t & 0 \end{pmatrix}\right) \exp\left(\begin{pmatrix} t & 0 \\ 0 & t \end{pmatrix}\right).$$

The matrix  $\begin{pmatrix} 0 & 0 \\ t & 0 \end{pmatrix}$  is nilpotent, so the exponential series stops after finitely many terms—two, in fact,

$$\exp\left(\begin{pmatrix} 0 & 0 \\ t & 0 \end{pmatrix}\right) = \begin{pmatrix} 1 & 0 \\ t & 1 \end{pmatrix}.$$

The matrix  $\begin{pmatrix} t & 0 \\ 0 & t \end{pmatrix}$  is diagonal, so

$$\exp\left(\begin{pmatrix} t & 0 \\ 0 & t \end{pmatrix}\right) = \begin{pmatrix} \exp(t) & 0 \\ 0 & \exp(t) \end{pmatrix}.$$

Multiplying,

$$\exp\left(\begin{pmatrix} t & 0 \\ t & t \end{pmatrix}\right) = \begin{pmatrix} \exp(t) & 0 \\ t \exp(t) & \exp(t) \end{pmatrix},$$

and, since  $\exp(tA) = P \exp(tJ) P^{-1}$ ,

$$\exp\left(t \begin{pmatrix} 22 & -49 \\ 9 & -20 \end{pmatrix}\right) = \begin{pmatrix} (1 + 21t) \exp(t) & -49t \exp(t) \\ 9t \exp(t) & (1 - 21t) \exp(t) \end{pmatrix}.$$

Then

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} (1 + 21t) \exp(t) & -49t \exp(t) \\ 9t \exp(t) & (1 - 21t) \exp(t) \end{pmatrix} \begin{pmatrix} x(0) \\ y(0) \end{pmatrix}.$$

2. Solve

$$\begin{aligned} x'(t) &= 11x(t) - 30y(t), \\ y'(t) &= 4x(t) - 11y(t). \end{aligned}$$

*Solution:* The calculation is very similar, to the previous one, but slightly easier. The characteristic polynomial is

$$(\lambda - 11)(\lambda + 11) - (-30)(4) = \lambda^2 - 1 = (\lambda - 1)(\lambda + 1),$$

so

$$J = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

One of many possible  $P$ 's is

$$P = \begin{pmatrix} 3 & 5 \\ 1 & 2 \end{pmatrix} \quad P^{-1} = \begin{pmatrix} 2 & -5 \\ -1 & 3 \end{pmatrix}.$$

Then

$$\exp(tJ) = \begin{pmatrix} \exp(t) & 0 \\ 0 & \exp(-t) \end{pmatrix}$$

and

$$\exp(tA) = \begin{pmatrix} 6\exp(t) - 5\exp(-t) & -15\exp(t) + 15\exp(-t) \\ 2\exp(t) - 2\exp(-t) & -5\exp(t) + 6\exp(-t) \end{pmatrix}$$

so

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} 15\exp(t) - 14\exp(-t) & -35\exp(t) + 35\exp(-t) \\ 6\exp(t) - 6\exp(-t) & -14\exp(t) + 15\exp(-t) \end{pmatrix} \begin{pmatrix} x(0) \\ y(0) \end{pmatrix}.$$

3. Solve

$$x'(t) = 15x(t) - 8y(t),$$

$$y'(t) = 20x(t) - 9y(t).$$

*Solution:* This one is similar to the previous two, with the added complication that the characteristic polynomial,

$$\lambda^2 - 6\lambda + 25$$

has complex roots. The algebra is then a bit messier, but

$$J = \begin{pmatrix} 3 + 4i & 0 \\ 0 & 3 - 4i \end{pmatrix}$$

$$P = \begin{pmatrix} 1 + i & 1 - i \\ 2 + i & 2 - i \end{pmatrix}$$

and

$$P^{-1} = \begin{pmatrix} \frac{2-i}{2i} & \frac{-1+i}{2i} \\ \frac{-2-i}{2i} & \frac{1+i}{2i} \end{pmatrix}$$

Then  $\exp(tJ)$  is

$$\begin{pmatrix} \exp(3t)(\cos(4t) + i\sin(4t)) & 0 \\ 0 & \exp(3t)(\cos(4t) + i\sin(4t)) \end{pmatrix},$$

and

$$\exp(tA) = \begin{pmatrix} w_{11}(t) & w_{12}(t) \\ w_{21}(t) & w_{22}(t) \end{pmatrix}$$

where

$$w_{11}(t) = \exp(3t) \cos(4t) + 3 \exp(3t) \sin(4t)$$

$$w_{12}(t) = -2 \exp(3t) \sin(4t)$$

$$w_{21}(t) = 5 \exp(3t) \sin(4t)$$

$$w_{22}(t) = \exp(3t) \cos(4t) - 3 \exp(3t) \sin(4t)$$

and

$$x(t) = w_{11}(t)x(0) + w_{12}(t)y(0)$$

$$y(t) = w_{21}(t)x(0) + w_{22}(t)y(0)$$

4. Under what conditions on  $a$ ,  $b$ ,  $c$  and  $d$  is it true that *all* solutions of

$$x'(t) = ax(t) + by(t)$$

$$y'(t) = cx(t) + dy(t)$$

satisfy

$$\lim_{t \rightarrow +\infty} x(t) = 0 = \lim_{t \rightarrow +\infty} y(t)?$$

*Solution:* The characteristic polynomial of the coefficient matrix of the corresponding first order system is

$$\lambda^2 - (a + d)\lambda + ad - bc.$$

Depending on the sign of

$$\Delta = (a + d)^2 - 4(ad - bc)$$

we have two real roots

$$\frac{a + d}{2} \pm \frac{\sqrt{\Delta}}{2}$$

if  $\Delta > 0$  or two complex roots

$$\frac{a + d}{2} \pm i \frac{\sqrt{-\Delta}}{2}$$

if  $\Delta < 0$ , or a real root

$$\frac{a + d}{2}$$

if  $\Delta = 0$ .

Consider first the case  $\Delta > 0$ . Set

$$\lambda_1 = \frac{a+d}{2} + \frac{\sqrt{\Delta}}{2}$$

and

$$\lambda_2 = \frac{a+d}{2} - \frac{\sqrt{\Delta}}{2}.$$

The Jordan canonical form of  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is

$$\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$$

and its exponential is

$$\begin{pmatrix} \exp(\lambda_1 t) & 0 \\ 0 & \exp(\lambda_2 t) \end{pmatrix}.$$

From  $\exp(tA) = P \exp(tJ) P^{-1}$  we obtain a solution of the form

$$x(t) = w_{11}(t)x(0) + w_{12}(t)y(0)$$

$$y(t) = w_{21}(t)x(0) + w_{22}(t)y(0)$$

where

$$w_{11}(t) = \frac{p_{11}p_{22} \exp(\lambda_1 t) - p_{12}p_{21} \exp(\lambda_2 t)}{p_{11}p_{22} - p_{12}p_{21}}$$

$$w_{12}(t) = \frac{-p_{11}p_{12} \exp(\lambda_1 t) - p_{12}p_{11} \exp(\lambda_2 t)}{p_{11}p_{22} - p_{12}p_{21}}$$

$$w_{21}(t) = \frac{p_{21}p_{22} \exp(\lambda_1 t) - p_{22}p_{21} \exp(\lambda_2 t)}{p_{11}p_{22} - p_{12}p_{21}}$$

$$w_{22}(t) = \frac{-p_{21}p_{12} \exp(\lambda_1 t) + p_{22}p_{11} \exp(\lambda_2 t)}{p_{11}p_{22} - p_{12}p_{21}}$$

The best way to think about this is as the vector equation

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} p_{11} \\ p_{21} \end{pmatrix} \exp(\lambda_1 t) \alpha + \begin{pmatrix} p_{12} \\ p_{22} \end{pmatrix} \exp(\lambda_2 t) \beta$$

where

$$\alpha = \frac{p_{22}x(0) - p_{12}y(0)}{p_{11}p_{22} - p_{12}p_{21}}$$

$$\beta = \frac{-p_{21}x(0) + p_{11}y(0)}{p_{11}p_{22} - p_{12}p_{21}}$$

In other words the set

$$\left\{ \begin{pmatrix} p_{11} \\ p_{21} \end{pmatrix} \exp(\lambda_1 t), \begin{pmatrix} p_{12} \\ p_{22} \end{pmatrix} \exp(\lambda_2 t) \right\}$$

is a basis for the vector space of solutions to the differential equation. We don't know what  $P$  is, but

$$\lim_{t \rightarrow +\infty} \exp(\lambda_1 t) = 0 = \lim_{t \rightarrow +\infty} \exp(\lambda_2 t)$$

if  $\lambda_1$  and  $\lambda_2$  are both negative. Conversely if  $\lambda_1$  is non-negative then

$$x(t) = p_{11} \exp(\lambda_1 t)$$

$$y(t) = p_{21} \exp(\lambda_1 t)$$

is a solution and at least one of  $x$  or  $y$  does not converge to zero. Note that  $p_{11}$  and  $p_{21}$  cannot both be zero, since  $P$  would then fail to be invertible. Similarly, if  $\lambda_2$  is non-negative then

$$x(t) = p_{12} \exp(\lambda_2 t)$$

$$y(t) = p_{22} \exp(\lambda_2 t)$$

is a solution and at least one of  $x$  or  $y$  does not converge to zero. Thus a necessary and sufficient condition in the case  $\Delta > 0$  is that both  $\lambda_1$  and  $\lambda_2$  are negative.

In the case  $\Delta < 0$  things are a bit messier, but the same idea can be made to work. Our Jordan matrix is

$$J = \begin{pmatrix} \mu + i\nu & 0 \\ 0 & \mu - i\nu \end{pmatrix}.$$

We may assume that the second column of  $P$  is the complex conjugate of the first, since the two columns of  $P$  are simply eigenvectors of  $A$  with eigenvalues  $\mu + i\nu$  and  $\mu - i\nu$  and the complex conjugate of an eigenvector with eigenvalue  $\mu + i\nu$  will be an eigenvector with eigenvalue  $\mu - i\nu$ . Thus  $P$  can be taken to have the form

$$P = \begin{pmatrix} p + iq & p - iq \\ r + is & r - is \end{pmatrix}$$

for some  $p, q, r$  and  $s$ . Then

$$P^{-1} = \frac{i}{2}(pq - rs)^{-1} \begin{pmatrix} r - is & -p + iq \\ -r - is & p + iq \end{pmatrix}$$

and, after much algebra,

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} x_1(t) \\ y_1(t) \end{pmatrix} \alpha + \begin{pmatrix} x_2(t) \\ y_2(t) \end{pmatrix} \beta$$

where

$$\begin{pmatrix} x_1(t) \\ y_1(t) \end{pmatrix} = \begin{pmatrix} p \exp(\mu t) \cos(\nu t) - q \exp(\mu t) \sin(\nu t) \\ r \exp(\mu t) \cos(\nu t) - s \exp(\mu t) \sin(\nu t) \end{pmatrix}$$

$$\begin{pmatrix} x_2(t) \\ y_2(t) \end{pmatrix} = \begin{pmatrix} q \exp(\mu t) \cos(\nu t) + p \exp(\mu t) \sin(\nu t) \\ s \exp(\mu t) \cos(\nu t) + r \exp(\mu t) \sin(\nu t) \end{pmatrix}$$

$$\alpha = \frac{sx(0) - qy(0)}{pq - rs}$$

$$\beta = \frac{-rx(0) + py(0)}{pq - rs}$$

Regardless of what  $p$ ,  $q$ ,  $r$  and  $s$  are, if  $\mu$  is negative then

$$\lim_{t \rightarrow +\infty} x(t) = 0 = \lim_{t \rightarrow +\infty} y(t).$$

Conversely, if  $\mu \geq 0$  then either  $x(t)$  or  $y(t)$  fails to tend to zero for at least one of the solutions  $(x_1, y_1)$  or  $(x_2, y_2)$ . Thus a necessary and sufficient condition in the case  $\Delta < 0$  is that  $\mu < 0$ .

The simplest case is that of a repeated real root,  $\Delta = 0$ . Set

$$\lambda = \frac{a + d}{2}.$$

The repeated root is  $\lambda$  and there are two possibilities for the Jordan form.

If the Jordan form is

$$\begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}$$

then

$$x(t) = x(0) \exp(\lambda t)$$

and

$$y(t) = y(0) \exp(\lambda t)$$

If  $\lambda < 0$  then all solutions tend to zero. If  $\lambda \geq 0$  then no non-trivial solutions tend to zero.

If the Jordan form is

$$\begin{pmatrix} \lambda & 0 \\ 1 & \lambda \end{pmatrix}$$

then things are slightly more complicated. Multiplying

$$\begin{pmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{pmatrix} \begin{pmatrix} \exp(t) & 0 \\ t \exp(t) & \exp(t) \end{pmatrix} \begin{pmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{pmatrix}^{-1} = \begin{pmatrix} (1 + \frac{a-d}{2}t) \exp(\lambda t) & bt \exp(\lambda t) \\ ct \exp(\lambda t) & (1 + \frac{d-a}{2}t) \exp(\lambda t) \end{pmatrix}$$

shows, however, that we have the same conclusion. If  $\lambda < 0$  then all solutions tend to zero. If  $\lambda \geq 0$  then no non-trivial solutions tend to zero.

In all cases the conclusion is the same. A necessary and sufficient condition for all solutions to tend to zero is that the roots of the characteristic polynomial have negative real parts. An equivalent condition, which is a bit easier to check, is that  $a + d$  and  $ad - bc$  are both positive.

5. Find a basis for the vector space of solutions to

$$x'''(t) - x''(t) - x'(t) + x(t) = 0.$$

*Solution:* The characteristic polynomial of the coefficient matrix of the corresponding first order system is

$$\lambda^3 - \lambda^2 - \lambda + 1 = (\lambda - 1)^2(\lambda + 1)$$

The Jordan canonical form would be

$$J = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

whose exponential is

$$\exp(tJ) = \begin{pmatrix} \exp(t) & 0 & 0 \\ t \exp(t) & \exp(t) & 0 \\ 0 & 0 & \exp(-t) \end{pmatrix}.$$

Multiplying from the left by  $P$ , whatever it is, and on the right by  $P^{-1}$  will give us some linear combinations of

$$\{\exp(t), t \exp(t), \exp(-t)\},$$

which is therefore the basis we are looking for.