

MAU23401: Advanced Classical Mechanics I

Homework 8 due 04/12/2020

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I have completed the Online Tutorial in avoiding plagiarism 'Ready, Steady, Write', located at <http://tcd-ie.libguides.com/plagiarism/ready-steady-write>.

Problem 1

1.

$$\begin{aligned} L &= \frac{m}{2} \dot{v}^2 - U(r) \\ &= \frac{m}{2} (x'(t)^2 + y'(t)^2 + z'(t)^2) - mg z(t) \\ z(t) &= \frac{k}{2} (x^2 + y^2) \\ \Rightarrow L &= \frac{m}{2} (x'(t)^2 + y'(t)^2 + k^2 (x(t)x'(t) + y(t)y'(t))^2 - gk (x(t)^2 + y(t)^2)) \end{aligned}$$

Since swapping x and y results in no change to the Lagrangian, we can solve the equations of motion in terms of x only, and simply swap x for y to get our answer in terms of y .

$$\begin{aligned} \text{eom: } 0 &= \frac{d}{dt} \frac{\partial L}{\partial x'(t)} - \frac{\partial L}{\partial x(t)} + \eta x'(t) \\ \Rightarrow x''(t) &= - \frac{\eta x'(t) + km x(t) (g + k (x'(t)^2 + y'(t)^2 + y(t)y''(t)))}{m + k^2 m x(t)^2} \\ \Rightarrow y''(t) &= - \frac{\eta y'(t) + km y(t) (g + k (x'(t)^2 + y'(t)^2 + x(t)x''(t)))}{m + k^2 m y(t)^2} \end{aligned}$$

$$L = \frac{m}{2} (x'[\mathbf{t}]^2 + y'[\mathbf{t}]^2 + z'[\mathbf{t}]^2) - mg z[\mathbf{t}];$$

$$z[\mathbf{t}_-] = \frac{k}{2} (x[\mathbf{t}]^2 + y[\mathbf{t}]^2);$$

`L // FullSimplify`

$$\frac{1}{2} m (-gk (x[\mathbf{t}]^2 + y[\mathbf{t}]^2) + x'[\mathbf{t}]^2 + y'[\mathbf{t}]^2 + k^2 (x[\mathbf{t}] x'[\mathbf{t}] + y[\mathbf{t}] y'[\mathbf{t}])^2)$$

$$\text{EOMx} = D[D[L, x'[\mathbf{t}]], \mathbf{t}] - D[L, x[\mathbf{t}]] + \eta x'[\mathbf{t}];$$

`Solve[EOMx == 0, x''[\mathbf{t}]] // FullSimplify`

$$\left\{ \left\{ x''[\mathbf{t}] \rightarrow - \frac{\eta x'[\mathbf{t}] + km x[\mathbf{t}] (g + k (x'[\mathbf{t}]^2 + y'[\mathbf{t}]^2 + y[\mathbf{t}] y''[\mathbf{t}]))}{m + k^2 m x[\mathbf{t}]^2} \right\} \right\}$$

2.

Like before, we will only do this question with regards to x , and then write a similar answer for y based on this.

If we are only considering small oscillations then all quadratic terms will be approximately 0 compared to the linear terms.

$$\begin{aligned}
x''(t) &\approx -\frac{\eta x'(t) + gkm x(t)}{m} \\
\text{ansatz: } x(t) &= \Re(Ae^{rt}) \\
\Rightarrow r^2 &= -\frac{\eta r + gkm}{m} \\
\Rightarrow r_{\pm} &= \frac{1}{2} \left(-\frac{\eta}{m} \pm \frac{\sqrt{\eta^2 - 4gkm^2}}{m} \right) \\
x(t) &= \Re(A_+ e^{r_+ t} + A_- e^{r_- t}) \\
&= e^{-\frac{\eta t}{2m}} \Re \left(A_+ e^{\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} + A_- e^{-\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} \right)
\end{aligned}$$

Case 1: $\eta^2 < 4gkm^2$

$$\begin{aligned}
\Rightarrow x(t) &= e^{-\frac{\eta t}{2m}} \Re \left(A_+ e^{\frac{it}{2m} \sqrt{4gkm^2 - \eta^2}} + A_- e^{-\frac{it}{2m} \sqrt{4gkm^2 - \eta^2}} \right) \\
&= e^{-\frac{\eta t}{2m}} \Re \left(A_+ \cos \left(\frac{t}{2m} \sqrt{4gkm^2 - \eta^2} \right) + A_- \cos \left(-\frac{t}{2m} \sqrt{4gkm^2 - \eta^2} \right) \right) \\
&= \alpha e^{-\frac{\eta t}{2m}} \cos \left(\frac{t}{2m} \sqrt{4gkm^2 - \eta^2} \right), \quad \alpha \equiv \Re(A_+ + A_-)
\end{aligned}$$

Case 2: $\eta^2 > 4gkm^2$

$$\begin{aligned}
\Rightarrow x(t) &= e^{-\frac{\eta t}{2m}} \Re \left(A_+ e^{\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} + A_- e^{-\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} \right) \\
&= e^{-\frac{\eta t}{2m}} \left(\alpha_+ e^{\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} + \alpha_- e^{-\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} \right), \quad \alpha_{\pm} \equiv \Re(A_{\pm})
\end{aligned}$$

Case 3: $\eta^2 = 4gkm^2$

$$\begin{aligned}
\Rightarrow x(t) &= e^{-\frac{\eta t}{2m}} \Re(A_+ + A_-) \\
&= \alpha e^{-\frac{\eta t}{2m}}, \quad \alpha \equiv \Re(A_+ + A_-)
\end{aligned}$$

We can similarly define y , by letting $x \rightarrow y$, $A \rightarrow B$, $\alpha \rightarrow \beta$.

$$\text{Underdamped: } x(t) = \alpha e^{-\frac{\eta t}{2m}} \cos \left(\frac{t}{2m} \sqrt{4gkm^2 - \eta^2} \right)$$

$$\text{and } y(t) = \beta e^{-\frac{\eta t}{2m}} \cos \left(\frac{t}{2m} \sqrt{4gkm^2 - \eta^2} \right)$$

$$\text{Overdamped: } x(t) = e^{-\frac{\eta t}{2m}} \left(\alpha_+ e^{\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} + \alpha_- e^{-\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} \right)$$

$$\text{and } y(t) = e^{-\frac{\eta t}{2m}} \left(\beta_+ e^{\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} + \beta_- e^{-\frac{t}{2m} \sqrt{\eta^2 - 4gkm^2}} \right)$$

$$\text{Critically damped: } x(t) = \alpha e^{-\frac{\eta t}{2m}}$$

$$\text{and } y(t) = \beta e^{-\frac{\eta t}{2m}}$$

$$\text{Solve} \left[r^2 + \frac{\eta r + g k m}{m} == 0, r \right]$$

$$\left\{ \left\{ r \rightarrow \frac{1}{2} \left(-\frac{\eta}{m} - \frac{\sqrt{-4 g k m^2 + \eta^2}}{m} \right) \right\}, \left\{ r \rightarrow \frac{1}{2} \left(-\frac{\eta}{m} + \frac{\sqrt{-4 g k m^2 + \eta^2}}{m} \right) \right\} \right\}$$

$$r_+ = \frac{1}{2} \left(-\frac{\eta}{m} + \frac{\sqrt{-4 g k m^2 + \eta^2}}{m} \right);$$

$$r_- = \frac{1}{2} \left(-\frac{\eta}{m} - \frac{\sqrt{-4 g k m^2 + \eta^2}}{m} \right);$$

$$x[t_-] = A_+ e^{r_+ t} + A_- e^{r_- t}$$

$$e^{\frac{1}{2} t \left(-\frac{\eta}{m} - \frac{\sqrt{-4 g k m^2 + \eta^2}}{m} \right)} A_- + e^{\frac{1}{2} t \left(-\frac{\eta}{m} + \frac{\sqrt{-4 g k m^2 + \eta^2}}{m} \right)} A_+$$

Problem 2

1.

$$\begin{aligned}
\text{eom}_{\text{homo}}: 0 &= x''_{\text{homo}}(t) + 2\lambda x'_{\text{homo}}(t) + \omega_0^2 x_{\text{homo}}(t) \\
\Rightarrow x_{\text{homo}}(t) &= e^{(-\lambda - \sqrt{\lambda^2 - \omega_0^2})t} c_1 + e^{(-\lambda + \sqrt{\lambda^2 - \omega_0^2})t} c_2 \\
\text{eom}: 0 &= x''(t) + 2\lambda x'(t) + \omega_0^2 x(t) - f_0 e^{-\alpha|t|}, \quad f_0 = \frac{F_0}{m} \\
t < 0: \text{ansatz: } x(t) &= \Re(Ae^{\alpha t}) \\
\Rightarrow A &= \frac{f_0}{\alpha^2 + 2\alpha\lambda + \omega_0^2} \\
x_-(t) &= x_{\text{homo}}(t) + x(t) \\
&= e^{(-\lambda - \sqrt{\lambda^2 - \omega_0^2})t} c_1 + e^{(-\lambda + \sqrt{\lambda^2 - \omega_0^2})t} c_2 + \Re\left(\frac{f_0}{\alpha^2 + 2\alpha\lambda + \omega_0^2} e^{\alpha t}\right)
\end{aligned}$$

If $t = -\infty$ then $x = \infty$ and thus $E \neq 0$, thus $c_1, c_2 = 0$.

$$\begin{aligned}
\Rightarrow x_-(t) &= \Re\left(\frac{f_0}{\alpha^2 + 2\alpha\lambda + \omega_0^2} e^{\alpha t}\right) \\
&= \frac{f_0}{\alpha^2 + 2\alpha\lambda + \omega_0^2} e^{\alpha t} \\
x_-(0) &= \frac{f_0}{\alpha^2 + 2\alpha\lambda + \omega_0^2} \\
x_-'(t) &= \frac{\alpha f_0}{\alpha^2 + 2\alpha\lambda + \omega_0^2} \\
t > 0: x(t) &= e^{(-\lambda - \sqrt{\lambda^2 - \omega_0^2})t} d_1 + e^{(-\lambda + \sqrt{\lambda^2 - \omega_0^2})t} d_2 + B e^{-\alpha t} \\
\text{eom}: 0 &= x''(t) + 2\lambda x'(t) + \omega_0^2 x(t) - f_0 e^{-\alpha|t|} \\
\Rightarrow B &= \frac{f_0}{\alpha^2 - 2\alpha\lambda + \omega_0^2} \\
x_+(t) &= x(t) \\
&= e^{(-\lambda - \sqrt{\lambda^2 - \omega_0^2})t} d_1 + e^{(-\lambda + \sqrt{\lambda^2 - \omega_0^2})t} d_2 + \frac{f_0}{\alpha^2 - 2\alpha\lambda + \omega_0^2} e^{-\alpha t} \\
x_+(0) &= d_1 + d_2 + \frac{f_0}{\alpha^2 - 2\alpha\lambda + \omega_0^2} \\
x_+'(t) &= d_1 \left(-\lambda - \sqrt{\lambda^2 - \omega_0^2}\right) + d_2 \left(-\lambda + \sqrt{\lambda^2 - \omega_0^2}\right) - \frac{\alpha f_0}{\alpha^2 - 2\alpha\lambda + \omega_0^2} \\
x_-(0) &= x_+(0) \\
x_-'(0) &= x_+'(0) \\
\Rightarrow d_1 &= -\frac{\alpha f_0 (\alpha^2 + \omega_0^2 + 2\lambda (-\lambda + \sqrt{\lambda^2 - \omega_0^2}))}{\sqrt{\lambda^2 - \omega_0^2} (\alpha (\alpha - 2\lambda) + \omega_0^2) (\alpha (\alpha + 2\lambda) + \omega_0^2)} \\
\text{and } d_2 &= \frac{\alpha f_0 (\alpha^2 + \omega_0^2 - 2\lambda (\lambda + \sqrt{\lambda^2 - \omega_0^2}))}{\sqrt{\lambda^2 - \omega_0^2} (\alpha (\alpha - 2\lambda) + \omega_0^2) (\alpha (\alpha + 2\lambda) + \omega_0^2)} \\
\Rightarrow x_+(t) &= \frac{f_0 e^{-\alpha t}}{\alpha^2 - 2\alpha\lambda + \omega_0^2} - \frac{\alpha f_0 e^{(-\lambda - \sqrt{\lambda^2 - \omega_0^2})t} (\alpha^2 + \omega_0^2 + 2\lambda (-\lambda + \sqrt{\lambda^2 - \omega_0^2}))}{\sqrt{\lambda^2 - \omega_0^2} (\alpha (\alpha - 2\lambda) + \omega_0^2) (\alpha (\alpha + 2\lambda) + \omega_0^2)} \\
&\quad + \frac{\alpha f_0 (\alpha^2 + \omega_0^2 - 2\lambda (\lambda + \sqrt{\lambda^2 - \omega_0^2}))}{\sqrt{\lambda^2 - \omega_0^2} (\alpha (\alpha - 2\lambda) + \omega_0^2) (\alpha (\alpha + 2\lambda) + \omega_0^2)}
\end{aligned}$$

$$x(t) = \begin{cases} x_-(t), & t \leq 0 \\ x_+(t), & t > 0 \end{cases}$$

$$= \begin{cases} \frac{f_0}{\alpha^2 + 2\alpha\lambda + \omega_0^2} e^{\alpha t}, & t \leq 0 \\ \frac{f_0 e^{-\alpha t}}{\alpha^2 - 2\alpha\lambda + \omega_0^2} - \frac{\alpha f_0 e^{(-\lambda - \sqrt{\lambda^2 - \omega_0^2})t} (\alpha^2 + \omega_0^2 + 2\lambda(-\lambda + \sqrt{\lambda^2 - \omega_0^2}))}{\sqrt{\lambda^2 - \omega_0^2}(\alpha(\alpha - 2\lambda) + \omega_0^2)(\alpha(\alpha + 2\lambda) + \omega_0^2)} + \frac{\alpha f_0 (\alpha^2 + \omega_0^2 - 2\lambda(\lambda + \sqrt{\lambda^2 - \omega_0^2}))}{\sqrt{\lambda^2 - \omega_0^2}(\alpha(\alpha - 2\lambda) + \omega_0^2)(\alpha(\alpha + 2\lambda) + \omega_0^2)}, & t > 0 \end{cases}$$

Clear[x];

\$Assumptions = m > 0 && f₀ > 0 && α > 0;

EOM1 = x''[t] + 2 λ x'[t] + ω₀² x[t];

DSolve[EOM1 == 0, x[t], t]

$$\left\{ \left\{ x[t] \rightarrow e^{t \left(-\lambda - \sqrt{\lambda^2 - \omega_0^2} \right)} c_1 + e^{t \left(-\lambda + \sqrt{\lambda^2 - \omega_0^2} \right)} c_2 \right\} \right\}$$

Clear[A];

f[t_] = Piecewise[{{f₀ e^{α t}, t < 0}, {f₀ e^{-α t}, t ≥ 0}}]

EOM2 = x''[t] + 2 λ x'[t] + ω₀² x[t] - f[t];

x[t_] = A e^{α t};

Assuming[t < 0, Solve[EOM2 == 0, A]]

$$\begin{cases} e^{t\alpha} f_0 & t < 0 \\ e^{-t\alpha} f_0 & t \geq 0 \\ 0 & \text{True} \end{cases}$$

$$\left\{ \left\{ A \rightarrow \frac{e^{-t\alpha} \left(\begin{cases} e^{t\alpha} f_0 & t < 0 \\ e^{-t\alpha} f_0 & t \geq 0 \\ 0 & \text{True} \end{cases} \right)}{\alpha^2 + 2\alpha\lambda + \omega_0^2} \right\} \right\}$$

$$\mathbf{x}[\mathbf{t_}] = \mathbf{A} \mathbf{e}^{\alpha \mathbf{t}};$$

$$\mathbf{A} = \frac{\mathbf{f0}}{\alpha^2 + 2 \alpha \lambda + \omega_{\theta}^2};$$

$$\mathbf{x}_{\text{homo}}[\mathbf{t_}] = \mathbf{e}^{\mathbf{t} \left(-\lambda - \sqrt{\lambda^2 - \omega_{\theta}^2} \right)} \mathbf{c}_1 + \mathbf{e}^{\mathbf{t} \left(-\lambda + \sqrt{\lambda^2 - \omega_{\theta}^2} \right)} \mathbf{c}_2;$$

$$\mathbf{x_}[\mathbf{t_}] = \mathbf{x}_{\text{homo}}[\mathbf{t}] + \mathbf{x}[\mathbf{t}]$$

... Set: Tag Plus in $\left(e^{\mathbf{t} \left(-\lambda - \sqrt{\text{Plus}[\ll 2 \gg]} \right)} \mathbf{c}_1 + e^{\mathbf{t} \left(-\lambda + \sqrt{\text{Power}[\ll 2 \gg] + \text{Times}[\ll 2 \gg]} \right)} \mathbf{c}_2 \right) [\mathbf{t_}]$ is Protected.

$$\frac{\mathbf{e}^{\mathbf{t} \alpha} \mathbf{f0}}{\alpha^2 + 2 \alpha \lambda + \omega_{\theta}^2} + \left(\mathbf{e}^{\mathbf{t} \left(-\lambda - \sqrt{\lambda^2 - \omega_{\theta}^2} \right)} \mathbf{c}_1 + \mathbf{e}^{\mathbf{t} \left(-\lambda + \sqrt{\lambda^2 - \omega_{\theta}^2} \right)} \mathbf{c}_2 \right) [\mathbf{t}]$$

$$\mathbf{x_}[\mathbf{t_}] = \mathbf{x}[\mathbf{t}]$$

$$\frac{\mathbf{e}^{\mathbf{t} \alpha} \mathbf{f0}}{\alpha^2 + 2 \alpha \lambda + \omega_{\theta}^2}$$

$$\mathbf{X_}[\mathbf{t_}] = \text{Re}[\mathbf{x_}[\mathbf{t}]]$$

$$\text{Re} \left[\frac{\mathbf{e}^{\mathbf{t} \alpha} \mathbf{f0}}{\alpha^2 + 2 \alpha \lambda + \omega_{\theta}^2} \right]$$

$$x_{-0} = X_{-}[0]$$

$$\text{Re}\left[\frac{f_0}{\alpha^2 + 2 \alpha \lambda + \omega_0^2}\right]$$

$$v_{-0} = \text{Re}[x_{-}'[0]]$$

$$\text{Re}\left[\frac{f_0 \alpha}{\alpha^2 + 2 \alpha \lambda + \omega_0^2}\right]$$

(*t>0*)

Clear[x, B, c₁, c₂];

$$x[t_] = e^{t(-\lambda - \sqrt{\lambda^2 - \omega_0^2})} c_1 + e^{t(-\lambda + \sqrt{\lambda^2 - \omega_0^2})} c_2 + B e^{-\alpha t};$$

$$\text{EOM3} = x''[t] + 2 \lambda x'[t] + \omega_0^2 x[t] - f[t];$$

Assuming[{t ≥ 0}, EOM3 // FullSimplify]

$$e^{-t\alpha} (-f_0 + B \alpha (\alpha - 2 \lambda) + B \omega_0^2)$$

Assuming[{t ≥ 0}, Solve[EOM3 == 0, B]]

$$\left\{ \left\{ B \rightarrow \frac{e^{t\alpha} \left(\begin{cases} e^{t\alpha} f_0 & t < 0 \\ e^{-t\alpha} f_0 & t \geq 0 \\ 0 & \text{True} \end{cases} \right)}{\alpha^2 - 2 \alpha \lambda + \omega_0^2} \right\} \right\}$$

$$B = \frac{f\theta}{\alpha^2 - 2\alpha\lambda + \omega_\theta^2};$$

$$x_+[t_-] = x[t]$$

$$e^{t(-\lambda - \sqrt{\lambda^2 - \omega_\theta^2})} c_1 + e^{t(-\lambda + \sqrt{\lambda^2 - \omega_\theta^2})} c_2 + \frac{e^{-t\alpha} f\theta}{\alpha^2 - 2\alpha\lambda + \omega_\theta^2}$$

$$x_{+\theta} = x_+[\theta]$$

$$c_1 + c_2 + \frac{f\theta}{\alpha^2 - 2\alpha\lambda + \omega_\theta^2}$$

$$v_{+\theta} = x_+'[\theta]$$

$$-\frac{f\theta\alpha}{\alpha^2 - 2\alpha\lambda + \omega_\theta^2} + c_1(-\lambda - \sqrt{\lambda^2 - \omega_\theta^2}) + c_2(-\lambda + \sqrt{\lambda^2 - \omega_\theta^2})$$

$$\text{Solve}\left[\left\{c_1 + c_2 + \frac{f\theta}{\alpha^2 - 2\alpha\lambda + \omega_\theta^2} == \frac{f\theta}{\alpha^2 + 2\alpha\lambda + \omega_\theta^2}, -\frac{f\theta\alpha}{\alpha^2 - 2\alpha\lambda + \omega_\theta^2} + c_1(-\lambda - \sqrt{\lambda^2 - \omega_\theta^2}) + c_2(-\lambda + \sqrt{\lambda^2 - \omega_\theta^2}) == \frac{f\theta\alpha}{\alpha^2 + 2\alpha\lambda + \omega_\theta^2}\right\}, \{c_1, c_2\}\right] // \text{FullSimplify}$$

$$\left\{\left\{c_1 \rightarrow -\frac{f\theta\alpha(\alpha^2 + \omega_\theta^2 + 2\lambda(-\lambda + \sqrt{\lambda^2 - \omega_\theta^2}))}{\sqrt{\lambda^2 - \omega_\theta^2}(\alpha(\alpha - 2\lambda) + \omega_\theta^2)(\alpha(\alpha + 2\lambda) + \omega_\theta^2)}, c_2 \rightarrow \frac{f\theta\alpha(\alpha^2 + \omega_\theta^2 - 2\lambda(\lambda + \sqrt{\lambda^2 - \omega_\theta^2}))}{\sqrt{\lambda^2 - \omega_\theta^2}(\alpha(\alpha - 2\lambda) + \omega_\theta^2)(\alpha(\alpha + 2\lambda) + \omega_\theta^2)}\right\}\right\}$$

$$c_1 = -\frac{f\theta\alpha(\alpha^2 + \omega_\theta^2 + 2\lambda(-\lambda + \sqrt{\lambda^2 - \omega_\theta^2}))}{\sqrt{\lambda^2 - \omega_\theta^2}(\alpha(\alpha - 2\lambda) + \omega_\theta^2)(\alpha(\alpha + 2\lambda) + \omega_\theta^2)};$$

$$c_2 = \frac{f\theta\alpha(\alpha^2 + \omega_\theta^2 - 2\lambda(\lambda + \sqrt{\lambda^2 - \omega_\theta^2}))}{\sqrt{\lambda^2 - \omega_\theta^2}(\alpha(\alpha - 2\lambda) + \omega_\theta^2)(\alpha(\alpha + 2\lambda) + \omega_\theta^2)};$$

$$x_+[t]$$

$$x_+ = \text{Re}[x_+[t]]$$

$$\frac{e^{-t\alpha} f\theta}{\alpha^2 - 2\alpha\lambda + \omega_\theta^2} - \frac{e^{t(-\lambda - \sqrt{\lambda^2 - \omega_\theta^2})} f\theta\alpha(\alpha^2 + \omega_\theta^2 + 2\lambda(-\lambda + \sqrt{\lambda^2 - \omega_\theta^2}))}{\sqrt{\lambda^2 - \omega_\theta^2}(\alpha(\alpha - 2\lambda) + \omega_\theta^2)(\alpha(\alpha + 2\lambda) + \omega_\theta^2)} + \frac{e^{t(-\lambda + \sqrt{\lambda^2 - \omega_\theta^2})} f\theta\alpha(\alpha^2 + \omega_\theta^2 - 2\lambda(\lambda + \sqrt{\lambda^2 - \omega_\theta^2}))}{\sqrt{\lambda^2 - \omega_\theta^2}(\alpha(\alpha - 2\lambda) + \omega_\theta^2)(\alpha(\alpha + 2\lambda) + \omega_\theta^2)}$$

$$\text{Re}\left[\frac{e^{-t\alpha} f\theta}{\alpha^2 - 2\alpha\lambda + \omega_\theta^2} - \frac{e^{t(-\lambda - \sqrt{\lambda^2 - \omega_\theta^2})} f\theta\alpha(\alpha^2 + \omega_\theta^2 + 2\lambda(-\lambda + \sqrt{\lambda^2 - \omega_\theta^2}))}{\sqrt{\lambda^2 - \omega_\theta^2}(\alpha(\alpha - 2\lambda) + \omega_\theta^2)(\alpha(\alpha + 2\lambda) + \omega_\theta^2)} + \frac{e^{t(-\lambda + \sqrt{\lambda^2 - \omega_\theta^2})} f\theta\alpha(\alpha^2 + \omega_\theta^2 - 2\lambda(\lambda + \sqrt{\lambda^2 - \omega_\theta^2}))}{\sqrt{\lambda^2 - \omega_\theta^2}(\alpha(\alpha - 2\lambda) + \omega_\theta^2)(\alpha(\alpha + 2\lambda) + \omega_\theta^2)}\right]$$

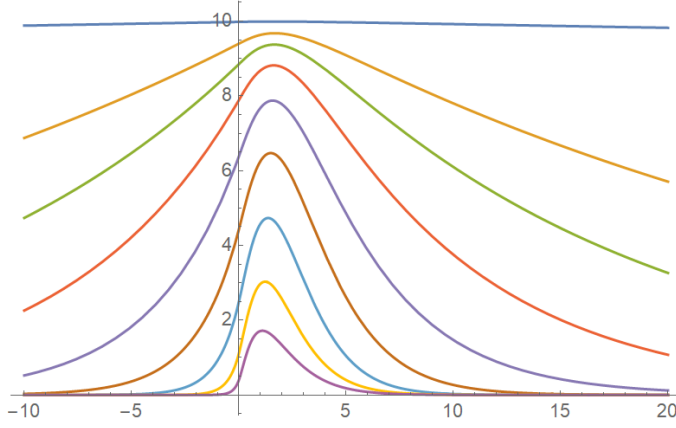
$$x[t_-] = \text{Piecewise}[\{\{x_+[t], t < 0\}, \{x_+[t], t \geq 0\}\}]$$

$$\begin{cases} \frac{e^{t\alpha} f\theta}{1 + \alpha^2 + 2\alpha\lambda} & t < 0 \\ \frac{e^{-t\alpha} f\theta}{1 + \alpha^2 - 2\alpha\lambda} - \frac{e^{t(-\lambda - \sqrt{1 + \lambda^2})} f\theta\alpha(1 + \alpha^2 + 2\lambda(-\lambda + \sqrt{1 + \lambda^2}))}{(1 + \alpha(\alpha - 2\lambda))\sqrt{-1 + \lambda^2}(1 + \alpha(\alpha + 2\lambda))} + \frac{e^{t(-\lambda + \sqrt{1 + \lambda^2})} f\theta\alpha(1 + \alpha^2 - 2\lambda(\lambda + \sqrt{1 + \lambda^2}))}{(1 + \alpha(\alpha - 2\lambda))\sqrt{-1 + \lambda^2}(1 + \alpha(\alpha + 2\lambda))} & t \geq 0 \\ 0 & \text{True} \end{cases}$$

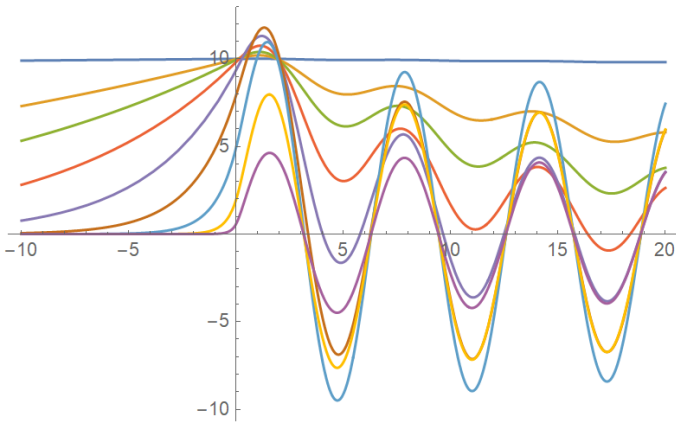
The first plot is overdamped motion as $\lambda > \omega_0$. The second plot is underdamped motion as $\lambda < \omega_0$.

2.

$\text{Plot}\left[\left\{X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 1.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{1000}\right\}, X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 1.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{32}\right\},\right.\right.$
 $X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 1.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{16}\right\}, X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 1.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{8}\right\},$
 $X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 1.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{4}\right\}, X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 1.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{2}\right\},$
 $X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 1.01, f_0 \rightarrow 10, \alpha \rightarrow 1\right\}, X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 1.01, f_0 \rightarrow 10, \alpha \rightarrow 2\right\},$
 $X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 1.01, f_0 \rightarrow 10, \alpha \rightarrow 4\right\}\right], \{t, -10, 20\}]$



$\text{Plot}\left[\left\{X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 0.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{1000}\right\}, X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 0.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{32}\right\},\right.\right.$
 $X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 0.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{16}\right\}, X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 0.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{8}\right\},$
 $X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 0.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{4}\right\}, X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 0.01, f_0 \rightarrow 10, \alpha \rightarrow \frac{1}{2}\right\},$
 $X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 0.01, f_0 \rightarrow 10, \alpha \rightarrow 1\right\}, X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 0.01, f_0 \rightarrow 10, \alpha \rightarrow 2\right\},$
 $X[t] /. \left\{\omega_0 \rightarrow 1, \lambda \rightarrow 0.01, f_0 \rightarrow 10, \alpha \rightarrow 4\right\}\right], \{t, -10, 20\}]$



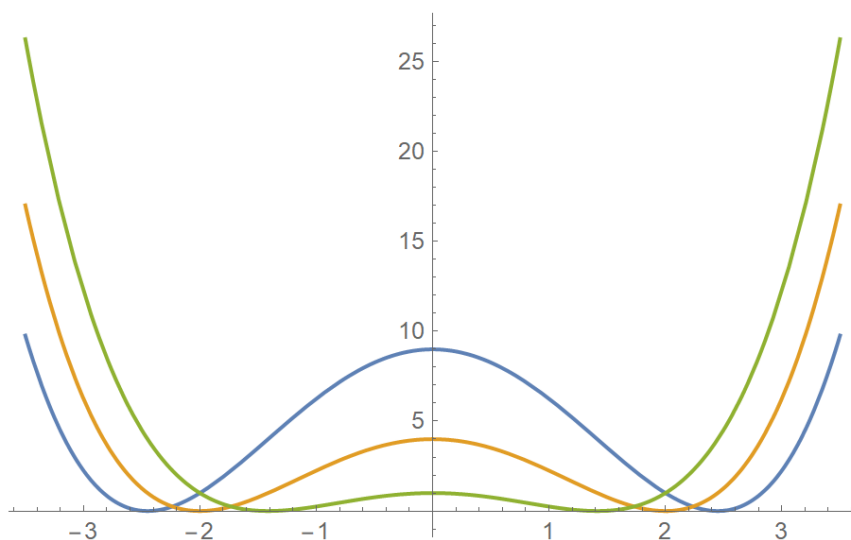
Problem 3

1.

`$Assumptions = m > 0 && k > 0 && g > 0;`

$$U[x] = \frac{k^2}{4g} - \frac{k}{2}x^2 + \frac{g}{4}x^4;$$

`Plot[{U[x] /. {k → 6, g → 1}, U[x] /. {k → 4, g → 1}, U[x] /. {k → 2, g → 1}},
{x, -3.5, 3.5}]`



2.

$$\frac{\partial U}{\partial x} = 0$$

$$\Rightarrow x = 0, \pm \sqrt{\frac{k}{g}}$$

$$\frac{\partial^2 U}{\partial x^2} > 0$$

$$\Rightarrow x \neq 0$$

$$\Rightarrow x_{\text{stable}} = \pm \sqrt{\frac{k}{g}}$$

$$U(x_{\text{stable}}) = 0$$

$$\text{Solve}[U'[x] == 0, x]$$

$$\left\{ \{x \rightarrow 0\}, \left\{x \rightarrow -\frac{\sqrt{k}}{\sqrt{g}}\right\}, \left\{x \rightarrow \frac{\sqrt{k}}{\sqrt{g}}\right\} \right\}$$

$$U''[x] /. \left\{ \{x \rightarrow 0\}, \left\{x \rightarrow \sqrt{\frac{k}{g}}\right\}, \left\{x \rightarrow -\sqrt{\frac{k}{g}}\right\} \right\}$$

$$\{-k, 2k, 2k\}$$

$$U[x] /. \left\{ \left\{x \rightarrow \sqrt{\frac{k}{g}}\right\}, \left\{x \rightarrow -\sqrt{\frac{k}{g}}\right\} \right\}$$

$$\{0, 0\}$$

3.

$$x(t) = \delta(t) + \sqrt{\frac{k}{g}}$$

$$\text{eom: } 0 = x''(t) + \frac{1}{m} \frac{\partial U}{\partial x}$$

$$0 = \delta''(x) + \frac{1}{m} \left(2k \delta(t) + 3\sqrt{gk} \delta(t)^2 + g \delta(t)^3 \right)$$

$$\text{EOM} = m x''[t] + (U'[x] /. x \rightarrow x[t])$$

$$-k x[t] + g x[t]^3 + m x''[t]$$

$$x[t_] = \delta[t] + \sqrt{\frac{k}{g}};$$

$$\text{EOM}_{\frac{\text{EOM}}{m}} = \frac{\text{EOM}}{m} // \text{FullSimplify} // \text{Expand}$$

$$\frac{2 k \delta[t]}{m} + \frac{3 \sqrt{g k} \delta[t]^2}{m} + \frac{g \delta[t]^3}{m} + \delta''[t]$$

4.

$$\omega_0 = \sqrt{\frac{2k}{m}}$$

$$\epsilon_1 = \frac{3\sqrt{gk}}{m}$$

$$\epsilon_2 = \frac{g}{m}$$

$$\omega = A^2 \left(-\frac{5\epsilon_1^2}{12\omega_0^3} + \frac{3\epsilon_2}{8\omega_0} \right)$$

$$\omega = -\frac{3A^2 g}{2\sqrt{2km}}$$

$$\frac{\omega}{\omega_0} = -\frac{3A^2 g}{4k}$$

$$\Omega_{\theta} = \sqrt{\frac{2 k}{m}} ;$$

$$\epsilon_1 = \frac{3 \sqrt{g k}}{m} ;$$

$$\epsilon_2 = \frac{g}{m} ;$$

$$\omega = A^2 \left(-\frac{5 \epsilon_1^2}{12 \Omega_{\theta}^3} + \frac{3 \epsilon_2}{8 \Omega_{\theta}} \right) // \text{FullSimplify}$$

$$\frac{\omega}{\Omega_{\theta}} // \text{FullSimplify}$$

$$-\frac{3 A^2 g}{2 \sqrt{2} \sqrt{k m}}$$

$$-\frac{3 A^2 g}{4 k}$$