

MAU23401: Advanced Classical Mechanics I

Homework 4 due 30/10/2020

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SF Theoretical Physics

I have read and I understand the plagiarism provisions in the General Regulations of the University Calendar for the current year, found at <http://www.tcd.ie/calendar>.
I have completed the Online Tutorial in avoiding plagiarism 'Ready, Steady, Write', located at <http://tcd-ie.libguides.com/plagiarism/ready-steady-write>.

Problem 1

1.

Maximising $U(x)$ is the same as finding the turning point(s) of $e^{ax} + \frac{1}{4}e^{-ax}$.

$$\begin{aligned}\frac{d}{dt} \left(e^{ax} + \frac{1}{4}e^{-ax} \right) &= ae^{ax} - \frac{a}{4}e^{-ax} = 0 \\ e^{ax} - \frac{1}{4}e^{-ax} &= 0 \\ e^{2ax} &= \frac{1}{4} \\ 2ax &= \ln \frac{1}{4} \\ x &= \frac{\ln \frac{1}{4}}{2a}\end{aligned}$$

$$\begin{aligned}U \left(\frac{\ln \frac{1}{4}}{2a} \right) &= \frac{V}{\left(e^{\frac{a \ln \frac{1}{4}}{2a}} + \frac{1}{4}e^{\frac{a \ln 4}{2a}} \right)^2} \\ &= \frac{V}{\left(\frac{1}{2} + \frac{1}{2} \right)^2} \\ U_{\max} &= V\end{aligned}$$

2.

Change of coordinates

$$\begin{aligned}
 y &= x + \frac{\ln 4}{2a} \\
 \Rightarrow x &= y - \frac{\ln 4}{2a} \\
 U(y) &= \frac{V}{\left(e^{ay} e^{\frac{\ln 4}{2}} + \frac{1}{4} e^{-ay} e^{\frac{\ln 4}{2}} \right)^2} \\
 &= \frac{V}{\left(\frac{1}{2} e^{ay} + \frac{1}{2} e^{-ay} \right)^2} \\
 &= \frac{V}{\cosh^2(ay)}
 \end{aligned}$$

Change of coordinates

$$\begin{aligned}
 z &= \sinh(ay) \\
 \Rightarrow y &= \frac{1}{a} \sinh^{-1} z \\
 U(z) &= \frac{V}{\cosh^2(\sinh^{-1} z)} \\
 &= \frac{V}{\sinh^2(\sinh^{-1} z) + 1} \\
 &= \frac{V}{z^2 + 1} \\
 K &= \frac{m}{2} \left(\frac{dx}{dt} \right)^2 \\
 &= \frac{m}{2} \left(\frac{dy}{dt} \right)^2 \\
 &= \frac{m}{2} \left(\frac{dy}{dz} \frac{dz}{dt} \right)^2 \\
 &= \frac{m}{2a^2} \frac{1}{z^2 + 1} \left(\frac{dz}{dt} \right)^2
 \end{aligned}$$

$$\begin{aligned}
E &= K + U \\
&= \frac{m}{2a^2} \frac{1}{z^2 + 1} \left(\frac{dz}{dt} \right)^2 + \frac{V}{z^2 + 1} \\
\frac{dz}{dt} &= a \sqrt{\frac{2(E(1+z^2) - V)}{m}} \\
dt &= \frac{1}{a} \sqrt{\frac{m}{2}} \frac{dz}{\sqrt{E(1+z^2) - V}} \\
T_L(U) &= \frac{1}{a} \sqrt{\frac{m}{2}} \int_{-\frac{1}{2}}^{\frac{1}{2}} \frac{dz}{\sqrt{E(1+z^2) - V}} \\
T_L(0) &= \frac{1}{a} \sqrt{\frac{m}{2}} \int_{-\frac{1}{2}}^{\frac{1}{2}} \frac{dz}{\sqrt{E(1+z^2)}} \\
T_{\text{delay}} &= \frac{1}{a} \sqrt{\frac{m}{2}} \int_{-\infty}^{\infty} \left(\frac{1}{\sqrt{E(1+z^2) - V}} - \frac{1}{\sqrt{E(1+z^2)}} \right) dz \\
&= \frac{\sqrt{2m}}{a} \int_0^{\infty} \left(\frac{1}{\sqrt{E(1+z^2) - V}} - \frac{1}{\sqrt{E(1+z^2)}} \right) dz \\
T_{\text{delay}} &= \frac{1}{a} \sqrt{\frac{m}{2E}} \ln \left(\frac{E}{E - V} \right)
\end{aligned}$$

$$\frac{\sqrt{2m}}{a} \text{ Assuming } \left[\{e > V, V > 0\}, \text{ Integrate} \left[\frac{1}{\sqrt{e \star (1+z^2) - V}} - \frac{1}{\sqrt{e \star (1+z^2)}}, \{z, 0, \text{Infinity}\} \right] \right]$$

$$\frac{\sqrt{m} \text{ Log} \left[\frac{e}{e-V} \right]}{\sqrt{2} a \sqrt{e}}$$

3.

$$E \approx V \implies T_{\text{delay}} = \frac{1}{a} \sqrt{\frac{m}{2V}} \ln \left(\frac{V}{E - V} \right)$$

$\approx \infty$ as the motion is almost bounded

$$E \gg V \implies T_{\text{delay}} = \frac{1}{a} \sqrt{\frac{m}{2}} \frac{V}{E^{\frac{3}{2}}}$$

≈ 0 as the motion is very close to free motion

$$T_{\text{delay}} = \frac{\sqrt{m} \operatorname{Log} \left[\frac{e}{e-V} \right]}{\sqrt{2} a \sqrt{e}};$$

`Series[Tdelay, {e, V, 0}] // Normal // Expand`

`Series[Tdelay, {e, Infinity, 2}] // Normal // Expand`

$$\frac{\sqrt{m} \operatorname{Log} \left[\frac{V}{e-V} \right]}{\sqrt{2} a \sqrt{V}}$$

$$\frac{\sqrt{m} V}{\sqrt{2} a e^{3/2}}$$

4.

$$\begin{aligned}dt &= \frac{1}{a}\sqrt{\frac{m}{2}}\frac{dz}{\sqrt{E\left(1+z^2\right)-V}}\\t &= \frac{1}{a}\sqrt{\frac{m}{2E}}\sinh^{-1}\left(z\sqrt{\frac{E}{E-V}}\right)\\z &= \sqrt{\frac{E-V}{E}}\sinh\left(at\sqrt{\frac{2E}{m}}\right)\\y &= \frac{1}{a}\sinh^{-1}z\\&= \frac{1}{a}\sinh^{-1}\left(\sqrt{\frac{E-V}{E}}\sinh\left(at\sqrt{\frac{2E}{m}}\right)\right)\\x &= y-\frac{\ln 4}{2a}\\x(t) &= \frac{1}{a}\sinh^{-1}\left(\sqrt{\frac{E-V}{E}}\sinh\left(at\sqrt{\frac{2E}{m}}\right)\right)-\frac{\ln 4}{2a}\end{aligned}$$

$$\frac{1}{a}\sqrt{\frac{m}{2}}\text{ Assuming}\left[\left\{\textcolor{blue}{e}>\textcolor{blue}{V},\textcolor{blue}{V}>\textcolor{blue}{0}\right\},\text{ Integrate}\left[\frac{1}{\sqrt{\textcolor{blue}{e}\left(1+\textcolor{teal}{q}^2\right)-\textcolor{blue}{V}}},\left\{\textcolor{teal}{q},\textcolor{blue}{0},\textcolor{blue}{z}\right\}\right]\right]$$

$$\frac{\sqrt{m}\operatorname{ArcSinh}\left[\sqrt{\frac{e}{e-V}}z\right]}{\sqrt{2}a\sqrt{e}}\quad\text{if}\quad\operatorname{Re}\left[z\right]>0\&\&\operatorname{Im}\left[z\right]==0$$

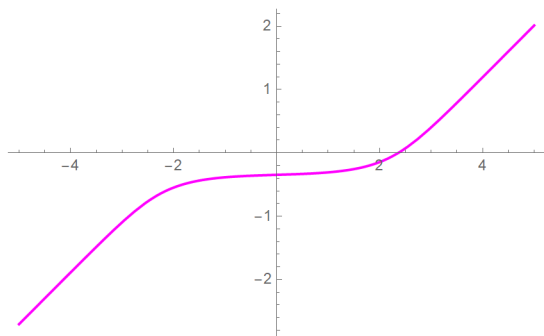
5.

$$V = 1$$

$$a = 2$$

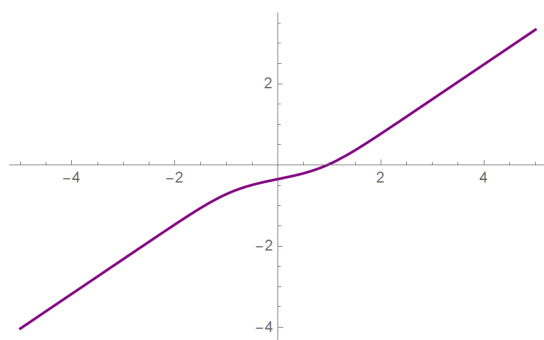
$$m = 3$$

$$\text{Plot}\left[\frac{1}{2} \text{ArcSinh}\left[\sqrt{\frac{1.001-1}{1.001}} \sinh\left[2 * t \sqrt{\frac{2 * 1.001}{3}}\right]\right] - \frac{\text{Log}[4]}{2 * 2}, \{t, -5, 5\}, \text{PlotStyle} \rightarrow \{\text{Magenta}, \text{Thick}\}\right]$$



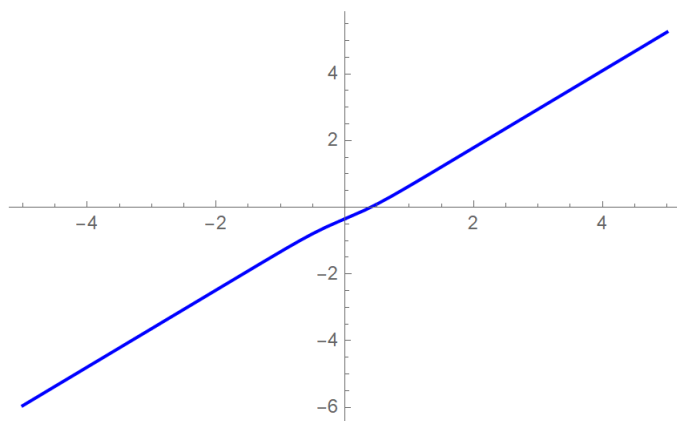
$$E = 1.001$$

$$\text{Plot}\left[\frac{1}{2} \text{ArcSinh}\left[\sqrt{\frac{1.1-1}{1.1}} \sinh\left[2 * t \sqrt{\frac{2 * 1.1}{3}}\right]\right] - \frac{\text{Log}[4]}{2 * 2}, \{t, -5, 5\}, \text{PlotStyle} \rightarrow \{\text{Purple}, \text{Thick}\}\right]$$



$$E = 1.1$$

$$\text{Plot}\left[\frac{1}{2} \text{ArcSinh}\left[\sqrt{\frac{2-1}{2}} \sinh\left[2 * t \sqrt{\frac{2 * 2}{3}}\right]\right] - \frac{\text{Log}[4]}{2 * 2}, \{t, -5, 5\}, \text{PlotStyle} \rightarrow \{\text{Blue}, \text{Thick}\}\right]$$



$$E = 2$$

Problem 2

1.

Minimising $U(x)$ is the same as finding the turning point(s) of $4e^{-2ax} + \frac{1}{4}e^{2ax} + 2$.

$$\begin{aligned}\frac{d}{dt} \left(4e^{-2ax} + \frac{1}{4}e^{2ax} + 2 \right) &= -8ae^{-2ax} + \frac{a}{2}e^{2ax} = 0 \\ e^{4ax} &= 16 \\ x &= \frac{\ln 4}{2a}\end{aligned}$$

$$\begin{aligned}U\left(\frac{\ln 4}{2a}\right) &= -\frac{4V}{4\left(\frac{1}{4}\right) + \frac{1}{4} + 2} \\ U_{\min} &= -V\end{aligned}$$

2.

(a)

$$\lim_{x \rightarrow -\infty} U(x) = \lim_{x \rightarrow \infty} u(x) = 0$$

$$\text{Finite motion} \implies E < 0$$

$$\text{Infinite motion} \implies E \geq 0$$

(b)

Change of coordinates

$$\begin{aligned}y &= x - \frac{\ln 4}{2a} \\ \Rightarrow x &= y + \frac{\ln 4}{2a} \\ U(y) &= -\frac{4V}{4e^{-2ay}e^{-\ln 4} + \frac{1}{4}e^{2ay}e^{\ln 4} + 2} \\ &= -\frac{4V}{e^{2ay} + 2 + e^{-2ay}} \\ &= -\frac{V}{\cosh^2(ay)}\end{aligned}$$

Change of coordinates

$$\begin{aligned}z &= \sinh(ay) \\ \Rightarrow y &= \frac{1}{a} \sinh^{-1} z \\ U(z) &= -\frac{V}{\cosh^2(\sinh^{-1} z)} \\ &= -\frac{V}{\sinh^2(\sinh^{-1} z) + 1} \\ &= -\frac{V}{z^2 + 1} \\ K &= \frac{m}{2} \left(\frac{dx}{dt} \right)^2 \\ &= \frac{m}{2} \left(\frac{dy}{dt} \right)^2 \\ &= \frac{m}{2} \left(\frac{dy}{dz} \frac{dz}{dt} \right)^2 \\ &= \frac{m}{2a^2} \frac{1}{z^2 + 1} \left(\frac{dz}{dt} \right)^2\end{aligned}$$

$$\begin{aligned}
E &= K + U \\
&= \frac{m}{2a^2} \frac{1}{z^2 + 1} \left(\frac{dz}{dt} \right)^2 - \frac{V}{z^2 + 1} \\
dt &= \frac{1}{a} \sqrt{\frac{m}{2}} \frac{dz}{\sqrt{E(z^2 + 1) + V}} \\
U(z) &= -\frac{V}{z^2 + 1} = E \\
z &= \pm \sqrt{\frac{-E - V}{E}} \\
\Rightarrow T &= \frac{2}{a} \sqrt{\frac{m}{2}} \int_{-\sqrt{\frac{-E - V}{E}}}^{\sqrt{\frac{-E - V}{E}}} \frac{dz}{\sqrt{E(z^2 + 1) + V}} \\
&= \frac{2\sqrt{2m}}{a} \int_0^{\sqrt{\frac{-E - V}{E}}} \frac{dz}{\sqrt{E(z^2 + 1) + V}} \\
T &= \frac{\pi}{a} \sqrt{-\frac{2m}{E}}
\end{aligned}$$

$$\frac{2 \sqrt{2 m}}{a} \text{Assuming}\left[\left\{\mathbf{e} < 0 \&\& \mathbf{V} > 0 \&\& -\mathbf{e} - \mathbf{V} < 0\right\}, \text{Integrate}\left[\frac{1}{\sqrt{\mathbf{e} \left(z^2 + 1\right) + \mathbf{V}}}, \left\{z, 0, \sqrt{\frac{-\mathbf{e} - \mathbf{V}}{\mathbf{e}}}\right\}\right]\right]$$

$$\frac{\sqrt{2} \sqrt{m} \pi}{a \sqrt{-\mathbf{e}}}$$

(c)

$$\begin{aligned}
 dt &= \frac{1}{a} \sqrt{\frac{m}{2}} \frac{dz}{E(z^2 + 1) + V} \\
 t &= \frac{1}{a} \sqrt{-\frac{m}{2E}} \sin^{-1} \left(z \sqrt{-\frac{E}{E+V}} \right) \\
 z &= \sqrt{-\frac{E+V}{E}} \sin \left(at \sqrt{-\frac{2E}{m}} \right) \\
 y &= \frac{1}{a} \sinh^{-1} z \\
 &= \frac{1}{a} \sinh^{-1} \left(\sqrt{-\frac{E+V}{E}} \sin \left(at \sqrt{-\frac{2E}{m}} \right) \right) \\
 x &= y + \frac{\ln 4}{2a} \\
 x(t) &= \frac{1}{a} \sinh^{-1} \left(\sqrt{-\frac{E+V}{E}} \sin \left(at \sqrt{-\frac{2E}{m}} \right) \right) + \frac{\ln 4}{2a}
 \end{aligned}$$

$$\frac{1}{a} \sqrt{\frac{m}{2}} \text{ Assuming } \left[\{e < 0 \&\& V > 0\}, \text{ Integrate} \left[\frac{1}{\sqrt{e (q^2 + 1) + V}}, \{q, 0, z\} \right] \right]$$

$$\frac{\sqrt{m} \text{ ArcSin} \left[\sqrt{-\frac{e}{e+V}} z \right]}{\sqrt{2} a \sqrt{-e}} \quad \text{if } z > 0 \&\& e + V + e z^2 > 0$$

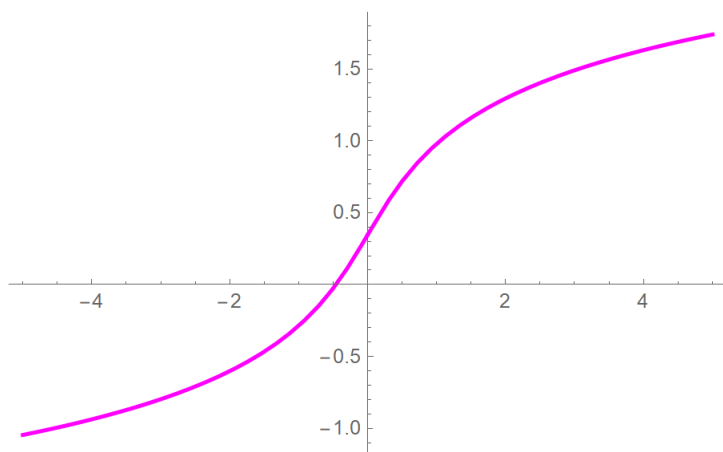
(d)

$$V = 1$$

$$a = 2$$

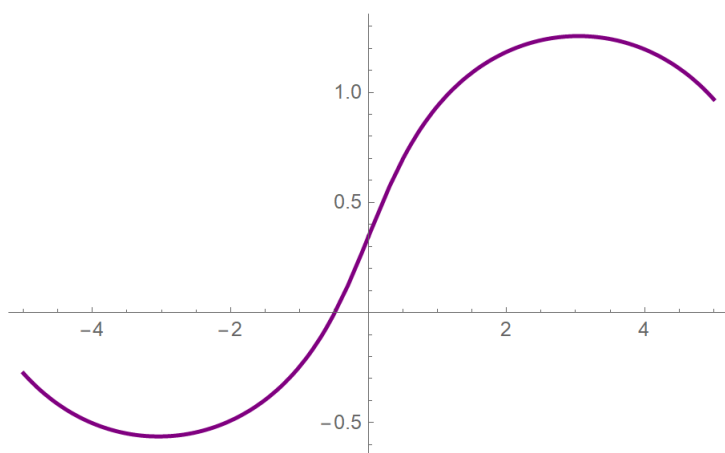
$$m = 3$$

```
Plot[ $\frac{1}{2}$  ArcSinh[ $\sqrt{-\frac{-0.001+1}{-0.001}}$  Sin[2* $t$   $\sqrt{-\frac{2*-0.001}{3}}$ ]]] +  $\frac{\text{Log}[4]}{2*2}$ , { $t$ , -5, 5},
PlotStyle -> {Magenta, Thick}]
```



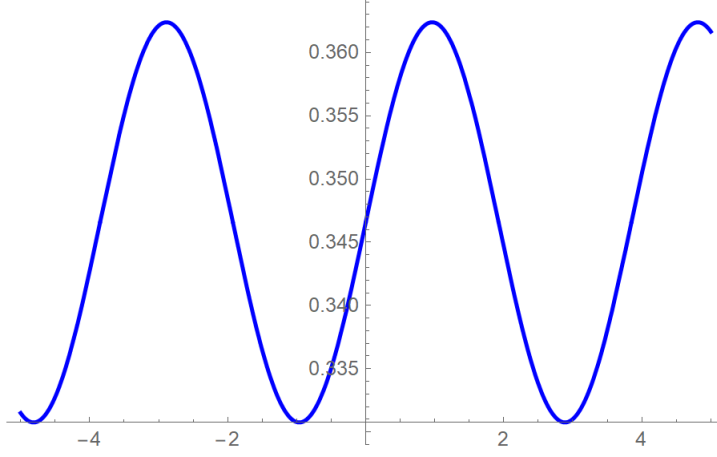
$$E = -0.001$$

```
Plot[ $\frac{1}{2}$  ArcSinh[ $\sqrt{-\frac{-0.1+1}{-0.1}}$  Sin[2* $t$   $\sqrt{-\frac{2*-0.1}{3}}$ ]]] +  $\frac{\text{Log}[4]}{2*2}$ , { $t$ , -5, 5},
PlotStyle -> {Purple, Thick}]
```



$$E = -0.1$$

```
Plot[ $\frac{1}{2}$  ArcSinh[ $\sqrt{-\frac{-0.999+1}{-0.999}}$  Sin[2* $t$   $\sqrt{-\frac{2*-0.999}{3}}$ ]] +  $\frac{\text{Log}[4]}{2*2}$ , { $t$ , -5, 5},
PlotStyle -> {Blue, Thick}]
```



$$E = -0.999$$

3.

(a)

$$\begin{aligned} dt &= \frac{1}{a} \sqrt{\frac{m}{2}} \frac{dz}{E(z^2 + 1) + V} \\ T_L(U) &= \frac{1}{a} \sqrt{\frac{m}{2}} \int_{-\frac{L}{2}}^{\frac{L}{2}} \frac{dz}{E(z^2 + 1) + V} \\ T_L(0) &= \frac{1}{a} \sqrt{\frac{m}{2}} \int_{-\frac{L}{2}}^{\frac{L}{2}} \frac{dz}{E(z^2 + 1)} \\ T_{\text{delay}} &= \frac{1}{a} \sqrt{\frac{m}{2}} \int_{-\infty}^{\infty} \left(\frac{1}{E(z^2 + 1) + V} - \frac{1}{E(z^2 + 1)} \right) dz \\ &= \frac{\sqrt{2m}}{a} \int_0^{\infty} \left(\frac{1}{E(z^2 + 1) + V} - \frac{1}{E(z^2 + 1)} \right) dz \\ T_{\text{delay}} &= \frac{1}{a} \sqrt{\frac{m}{2E}} \ln \left(\frac{E}{E + V} \right) \end{aligned}$$

$$\frac{\sqrt{2m}}{a} \text{Assuming}\left[\{e \geq 0 \&\& V > 0\}, \text{Integrate}\left[\frac{1}{\sqrt{e(z^2 + 1) + V}} - \frac{1}{\sqrt{e(z^2 + 1)}}, \{z, 0, \text{Infinity}\}\right]\right]$$

$$\frac{\sqrt{m} \text{Log}\left[\frac{e}{e+V}\right]}{\sqrt{2} a \sqrt{e}}$$

(b)

$$E \approx 0 \implies T_{\text{delay}} = \frac{1}{a} \sqrt{\frac{m}{2E}} \ln \left(\frac{E}{V} \right)$$

$\approx -\infty$ as the motion is almost bounded

$$E \gg V \implies T_{\text{delay}} = -\frac{1}{a} \sqrt{\frac{m}{2}} \frac{V}{E^{\frac{3}{2}}}$$

≈ 0 as the motion is very close to free motion

$$T_{\text{delay}} = \frac{\sqrt{m} \operatorname{Log} \left[\frac{e}{e+V} \right]}{\sqrt{2} a \sqrt{e}};$$

`Series[Tdelay, {e, 0, 0}] // Normal // Expand`

`Series[Tdelay, {e, Infinity, 2}] // Normal // Expand`

$$\frac{\sqrt{m} \operatorname{Log} \left[\frac{e}{V} \right]}{\sqrt{2} a \sqrt{e}}$$

$$- \frac{\sqrt{m} V}{\sqrt{2} a e^{3/2}}$$

(c)

$$dt = \frac{1}{a} \sqrt{\frac{m}{2}} \frac{dz}{E(z^2 + 1) + V}$$

$$t = \frac{1}{a} \sqrt{\frac{m}{2E}} \sinh^{-1} \left(z \sqrt{\frac{E}{E+V}} \right)$$

$$z = \sqrt{\frac{E+V}{E}} \sinh \left(at \sqrt{\frac{2E}{m}} \right)$$

$$y = \frac{1}{a} \sinh^{-1} z$$

$$= \frac{1}{a} \sinh^{-1} \left(\sqrt{\frac{E+V}{E}} \sinh \left(at \sqrt{\frac{2E}{m}} \right) \right)$$

$$x = y + \frac{\ln 4}{2a}$$

$$x(t) = \frac{1}{a} \sinh^{-1} \left(\sqrt{\frac{E+V}{E}} \sinh \left(at \sqrt{\frac{2E}{m}} \right) \right) + \frac{\ln 4}{2a}$$

$$\frac{1}{a} \sqrt{\frac{m}{2}} \operatorname{Assuming} \left[\{e \geq 0 \&\& V > 0\}, \operatorname{Integrate} \left[\frac{1}{\sqrt{e (q^2 + 1) + V}}, \{q, 0, z\} \right] \right]$$

$$\frac{\sqrt{m} \operatorname{ArcSinh} \left[\sqrt{\frac{e}{e+V}} z \right]}{\sqrt{2} a \sqrt{e}} \quad \text{if } e > 0 \&\& \operatorname{Re}[z] > 0 \&\& \operatorname{Im}[z] == 0$$

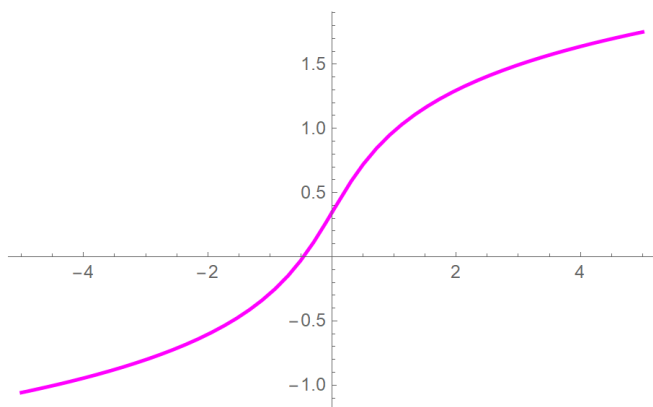
(d)

$$V = 1$$

$$a = 2$$

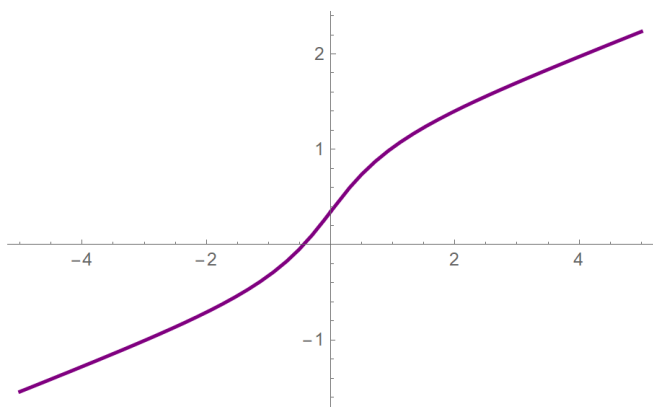
$$m = 3$$

```
Plot[ $\frac{1}{2}$  ArcSinh[ $\sqrt{\frac{0.001+1}{0.001}}$  Sinh[ $2 * t \sqrt{\frac{2 * 0.001}{3}}$ ]] +  $\frac{\text{Log}[4]}{2 * 2}$ , {t, -5, 5},
PlotStyle -> {Magenta, Thick}]
```



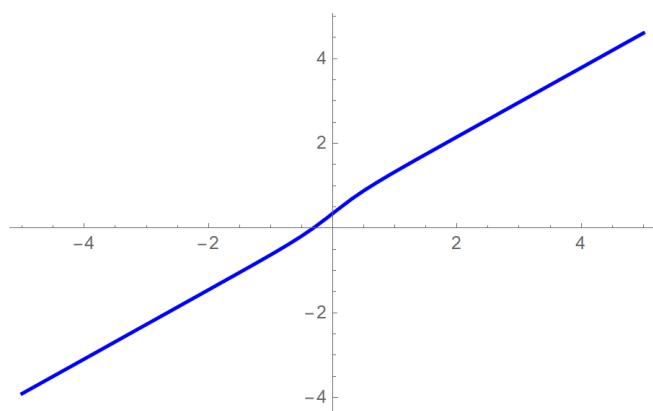
$$E = 0.001$$

```
Plot[ $\frac{1}{2}$  ArcSinh[ $\sqrt{\frac{0.1+1}{0.1}}$  Sinh[ $2 * t \sqrt{\frac{2 * 0.1}{3}}$ ]] +  $\frac{\text{Log}[4]}{2 * 2}$ , {t, -5, 5},
PlotStyle -> {Purple, Thick}]
```



$$E = 0.1$$

```
Plot[ $\frac{1}{2} \text{ArcSinh}\left[\sqrt{\frac{1+1}{1}} \text{Sinh}\left[2 * \textcolor{teal}{t} \sqrt{\frac{2 * 1}{3}}\right]\right] + \frac{\text{Log}[4]}{2 * 2}$ , { $\textcolor{teal}{t}$ , -5, 5}, PlotStyle -> {Blue, Thick}]
```



$$E = 1$$

Problem 3

1.

$$\begin{aligned}\frac{dU}{dx} &= -2aV \cot(ax) \csc^2(ax) \\ &= 0 \\ x &= \frac{\pi}{2a}\end{aligned}$$

Change of coordinates

$$\begin{aligned}y &= x - \frac{\pi}{2a} \\ \implies x &= y + \frac{\pi}{2a} \\ U(y) &= V \cot^2\left(ay - \frac{\pi}{2}\right) \\ &= V \tan^2(ay)\end{aligned}$$

Change of coordinates

$$\begin{aligned}z &= \sin(ay) \\ \implies y &= \frac{1}{a} \sin^{-1} z \\ U(z) &= V \tan^2(\sin^{-1} z) \\ &= V (\sec^2(\sin^{-1} z) - 1) \\ &= V \left(\frac{1}{\cos^2(\sin^{-1} z)} - 1 \right) \\ &= V \left(\frac{1}{1 - z^2} - 1 \right) \\ &= \frac{Vz^2}{1 - z^2} \\ K &= \frac{m}{2} \left(\frac{dx}{dt} \right)^2 \\ &= \frac{m}{2} \left(\frac{dy}{dt} \right)^2 \\ &= \frac{m}{2} \left(\frac{dy}{dz} \frac{dz}{dt} \right)^2 \\ &= \frac{m}{2a^2} \frac{1}{1 - z^2} \left(\frac{dz}{dt} \right)^2\end{aligned}$$

$$\begin{aligned}
E &= K + U \\
&= \frac{m}{2a^2} \frac{1}{1-z^2} \left(\frac{dz}{dt} \right)^2 + \frac{Vz^2}{1-z^2} \\
\frac{dz}{dt} &= a \sqrt{\frac{2(E(1-z^2) - Vz^2)}{m}} \\
dt &= \frac{1}{a} \sqrt{\frac{m}{2}} \frac{dz}{\sqrt{E(1-z^2) - Vz^2}} \\
U(z) &= \frac{Vz^2}{1-z^2} = E \\
z &= \pm \sqrt{\frac{E}{E+V}} \\
T &= \frac{\sqrt{2m}}{a} \int_{-\sqrt{\frac{E}{E+V}}}^{\sqrt{\frac{E}{E+V}}} \frac{dz}{\sqrt{E(1-z^2) - Vz^2}} \\
&= \frac{2\sqrt{2m}}{a} \int_0^{\sqrt{\frac{E}{E+V}}} \frac{dz}{\sqrt{E(1-z^2) - Vz^2}} \\
T &= \frac{\pi}{a} \sqrt{\frac{2m}{E+V}}
\end{aligned}$$

$$\frac{2 \sqrt{2 \textcolor{blue}{m}}}{\textcolor{blue}{a}} \text{ Assuming } \left[\left\{ \textcolor{blue}{e} > \textcolor{black}{0} \ \&\& \ \textcolor{blue}{V} > \textcolor{black}{0} \ \&\& \ \textcolor{blue}{e} \left(1 - \textcolor{blue}{z}^2 \right) - \textcolor{blue}{V} * \textcolor{blue}{z}^2 > \textcolor{black}{0} \right\}, \right.$$

$$\left. \text{Integrate} \left[\frac{1}{\sqrt{\textcolor{blue}{e} \left(1 - \textcolor{teal}{z}^2 \right) - \textcolor{blue}{V} * \textcolor{teal}{z}^2}}, \left\{ \textcolor{teal}{z}, \textcolor{black}{0}, \sqrt{\frac{\textcolor{blue}{e}}{\textcolor{blue}{e} + \textcolor{blue}{V}}} \right\} \right] \right]$$

$$\frac{\sqrt{2} \sqrt{\textcolor{teal}{m}} \pi}{\textcolor{black}{a} \sqrt{\textcolor{blue}{e} + \textcolor{blue}{V}}}$$

2.

$$E \approx 0 \implies T = \frac{\pi}{a} \sqrt{\frac{2m}{V}} \text{ as the motion is almost harmonic}$$

$$E \gg V \implies T = \frac{\pi}{a} \sqrt{\frac{2m}{E}} \\ \approx 0 \text{ as the motion is almost unbounded}$$

$$T = \frac{\sqrt{2} \sqrt{m} \pi}{a \sqrt{e + V}};$$

`Series[T, {e, 0, 0}] // Normal // Expand`

`Series[T, {e, Infinity, 1}] // Normal // Expand`

$$\frac{\sqrt{2} \sqrt{m} \pi}{a \sqrt{V}}$$

$$\frac{\sqrt{2} \sqrt{m} \pi}{a \sqrt{e}}$$

3.

$$\begin{aligned}
 dt &= \frac{1}{a} \sqrt{\frac{m}{2}} \frac{dz}{\sqrt{E(1-z^2) - Vz^2}} \\
 t &= \frac{1}{a} \sqrt{\frac{m}{2(E+V)}} \sin^{-1} \left(z \sqrt{\frac{E+V}{E}} \right) \\
 z &= \sqrt{\frac{E}{E+V}} \sin \left(at \sqrt{\frac{2(E+V)}{m}} \right) \\
 y &= \frac{1}{a} \sin^{-1} z \\
 &= \frac{1}{a} \sin^{-1} \left(\sqrt{\frac{E}{E+V}} \sin \left(at \sqrt{\frac{2(E+V)}{m}} \right) \right) \\
 x &= y + \frac{\pi}{2a} \\
 x(t) &= \frac{1}{a} \sin^{-1} \left(\sqrt{\frac{E}{E+V}} \sin \left(at \sqrt{\frac{2(E+V)}{m}} \right) \right) + \frac{\pi}{2a}
 \end{aligned}$$

$$\frac{1}{a} \sqrt{\frac{m}{2}} \text{ Assuming } \left[\{e > 0 \ \&\& \ v > 0\}, \right.$$

$$\left. \text{Integrate} \left[\frac{1}{\sqrt{e(1-q^2) - v * q^2}}, \{q, 0, z\} \right] \right]$$

$$\frac{\sqrt{m} \text{ ArcSin} \left[\sqrt{\frac{e+V}{e}} z \right]}{\sqrt{2} a \sqrt{e+V}} \quad \text{if} \quad (e+V) z^2 < e \ \&\& \ z > 0$$

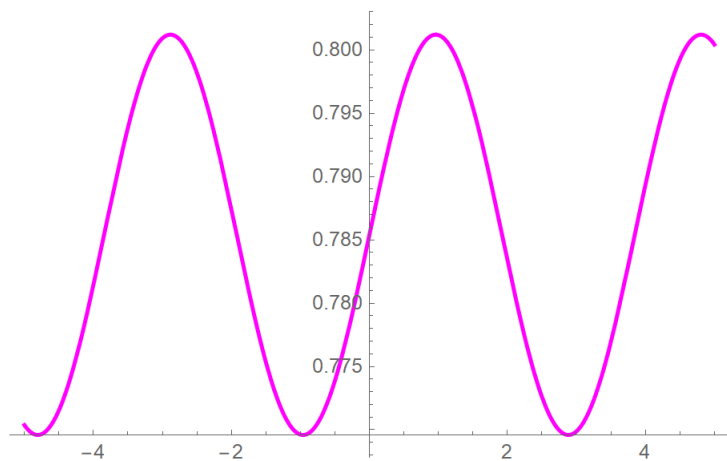
4.

$$V = 1$$

$$a = 2$$

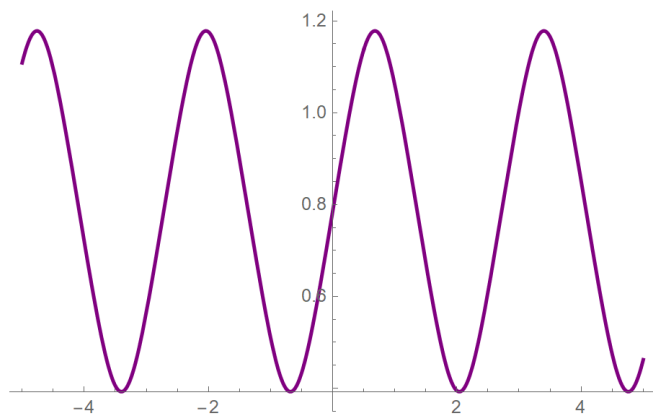
$$m = 3$$

$\text{Plot}\left[\frac{1}{2} \text{ArcSin}\left[\sqrt{\frac{0.001}{0.001+1}} \sin\left[2 * t \sqrt{\frac{2 * (0.001+1)}{3}}\right]\right] + \frac{\pi}{2 * 2}, \{t, -5, 5\}, \right.$
 $\left. \text{PlotStyle} \rightarrow \{\text{Magenta}, \text{Thick}\}\right]$



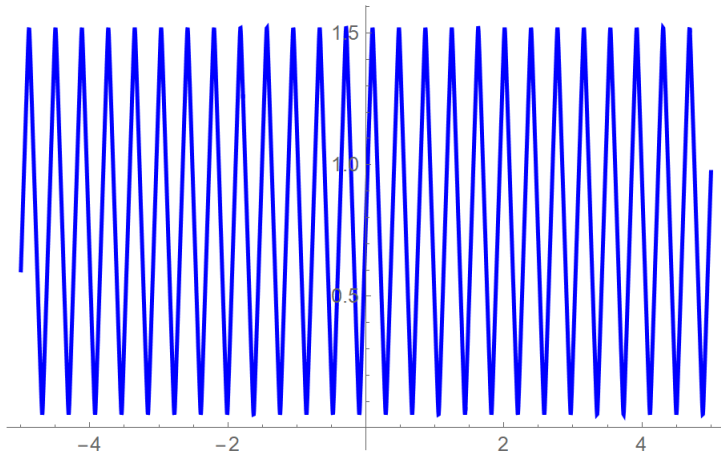
$$E = 0.001$$

$\text{Plot}\left[\frac{1}{2} \text{ArcSin}\left[\sqrt{\frac{1}{1+1}} \sin\left[2 * t \sqrt{\frac{2 * (1+1)}{3}}\right]\right] + \frac{\pi}{2 * 2}, \{t, -5, 5\}, \text{PlotStyle} \rightarrow \{\text{Purple}, \text{Thick}\}\right]$



$$E = 1$$

```
Plot[ $\frac{1}{2} \text{ArcSin}\left[\sqrt{\frac{100}{100+1}} \sin\left[2 * t \sqrt{\frac{2 * (100+1)}{3}}\right]\right] + \frac{\pi}{2 * 2}, \{t, -5, 5\},$   
PlotStyle -> {Blue, Thick}]
```



$E = 100$