MAU11102: Linear Algebra II Homework 10 due 10/04/2020

Ruaidhrí Campion 19333850 Theoretical Physics

I have read and I understand the plagiarism provisions in the General Regulations of the University Calendar for the current year, found at http://www.tcd.ie/calendar.

I have completed the Online Tutorial in avoiding plagiarism 'Ready, Steady, Write', located at http://tcd-ie.libguides.com/plagiarism/ready-steady-write.

Problem 1

$$q(x) = x^{T}Ax$$

$$= (x_{1} \quad x_{2} \quad x_{3}) \begin{pmatrix} 1 & 1 & -1 \\ 1 & 1 & 0 \\ -1 & 0 & -1 \end{pmatrix} \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix}$$

$$= (x_{1} \quad x_{2} \quad x_{3}) \begin{pmatrix} x_{1} + x_{2} - x_{3} \\ x_{1} + x_{2} \\ -x_{1} - x_{3} \end{pmatrix}$$

$$= x_{1}^{2} + x_{2}^{2} - x_{3}^{2} + 2x_{1}x_{2} - 2x_{1}x_{3}$$

$$= x_{1}^{2} + (x_{1}^{2} + 2x_{1}x_{2} + x_{2}^{2}) - (x_{1}^{2} + 2x_{1}x_{3} + x_{3}^{2})$$

$$= x_{1}^{2} + (x_{1} + x_{2})^{2} - (x_{1} + x_{3})^{2}$$

$$= y_{1}^{2} + y_{2}^{2} - y_{3}^{2}$$

$$\begin{array}{cccc} y_1 = x_1 & x_1 = y_1 \\ x = My \Rightarrow & y_2 = x_1 + x_2 & \text{or} & x_2 = -y_1 + y_2 & \text{or} & M = \left(\begin{array}{cccc} 1 & 0 & 0 \\ -1 & 1 & 0 \\ y_3 = x_1 + x_3 & x_3 = -y_1 + y_3 \end{array}\right)$$

$$\begin{array}{l} \varepsilon_1 = 1 \\ \varepsilon_2 = 1 \\ \varepsilon_3 = -1 \end{array} \Rightarrow \text{Signature of } q = (2, 1, 0) \end{array}$$

Problem 2

$$q(x) = \sum_{i,j} a_{ij} x_i x_j$$

$$a_{11}, a_{22}, a_{33} = 4$$

$$a_{12} + a_{21} = -2, a_{13} + a_{31} = 2, a_{23} + a_{32} = -2$$

$$A \text{ is symmetric} \Rightarrow a_{ij} = a_{ji}$$

$$\Rightarrow a_{12} = a_{21} = -1$$

$$\Rightarrow a_{13} = a_{31} = 1 \Rightarrow A = \begin{pmatrix} 4 & -1 & 1 \\ -1 & 4 & -1 \\ 1 & -1 & 4 \end{pmatrix}$$

$$\Rightarrow q(x) = x^{T} \begin{pmatrix} 4 & -1 & 1 \\ -1 & 4 & -1 \\ 1 & -1 & 4 \end{pmatrix} x$$

$$\chi_A(t) = \det(tI - A)$$

$$= \begin{vmatrix} t - 4 & 1 & -1 \\ 1 & t - 4 & 1 \\ -1 & 1 & t - 4 \end{vmatrix}$$

$$= (t - 4)((t - 4)(t - 4) - 1) - (t - 4 + 1) - (1 + t - 4)$$

$$= (t - 4)(t^2 - 8t + 15) - 2t + 6$$

$$= t^3 - 12t^2 + 45t + 54$$

$$= (t - 3)^2(t - 6) \Rightarrow \lambda_1, \lambda_2 = 3, \lambda_3 = 6$$

$$q(x) = 3y_1^2 + 3y_2^2 + 6y_3^2$$

= $y^{\mathbf{T}}By$
= $y^{\mathbf{T}}\begin{pmatrix} 3 & 0 & 0\\ 0 & 3 & 0\\ 0 & 0 & 6 \end{pmatrix}y$
= $y^{\mathbf{T}}\operatorname{diag}(\lambda_1, \lambda_2, \lambda_3)y$

We can find M where x = My such that M is an orthogonal matrix consisting of eigenvectors of A, and $B = M^{T}AM$. We will find the eigenvectors of A and obtain a set of orthonormal vectors from these, which will make up M.

$$(A-3I)v = 0 \Rightarrow \begin{pmatrix} 1 & -1 & 1 & | & 0 \\ -1 & 1 & -1 & | & 0 \\ 1 & -1 & 1 & | & 0 \end{pmatrix} \begin{array}{c} r_2 + r_1 \\ r_3 - r_1 & \begin{pmatrix} 1 & -1 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix}$$
$$v_1 = v_2 - v_3 \Rightarrow v_{\lambda_1} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \ v_{\lambda_2} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$$\begin{split} (A-6I)v &= 0 \Rightarrow \begin{pmatrix} -2 & -1 & 1 & | & 0 \\ -1 & -2 & -1 & | & 0 \\ 1 & -1 & -2 & | & 0 \end{pmatrix} \begin{array}{c} r_1 + 2r_3 \\ r_2 + r_3 & \begin{pmatrix} 0 & -3 & -3 & | & 0 \\ 0 & -3 & -3 & | & 0 \\ 1 & -1 & -2 & | & 0 \end{pmatrix} \\ \\ & -\frac{1}{3}r_1 & \begin{pmatrix} 0 & 1 & 1 & | & 0 \\ 0 & 1 & 1 & | & 0 \\ 1 & -1 & -1 & | & 0 \end{pmatrix} \begin{array}{c} r_1 - r_2 \\ r_3 + r_2 & \begin{pmatrix} 0 & 0 & 0 & | & 0 \\ 0 & 1 & 1 & | & 0 \\ 1 & 0 & -1 & | & 0 \end{pmatrix} \\ \\ & w_1 = v_3 \\ w_2 = -v_3 & \Rightarrow v_{\lambda_3} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \\ \\ & w_1 = \frac{v_{\lambda_1}}{||v_{\lambda_1}||} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \\ \\ & u_2 = v_{\lambda_2} - (v_{\lambda_2}, w_1)w_1 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + \frac{1}{\sqrt{2}}\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \\ \\ & w_3 = \frac{v_{\lambda_3}}{||v_{\lambda_3}||} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \\ \\ & w_3 = \frac{v_{\lambda_3}}{||v_{\lambda_3}||} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \\ \\ & w_4 = \begin{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \left| \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \right| \\ & \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{3}} \\ & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{pmatrix} \\ \\ \end{array}$$

$$x_{1} = \frac{1}{\sqrt{2}}y_{1} - \frac{1}{\sqrt{6}}y_{2} + \frac{1}{\sqrt{3}}y_{3} \qquad y_{1} = \frac{1}{\sqrt{2}}x_{1} + \frac{1}{\sqrt{2}}x_{2}$$

or $x_{2} = \frac{1}{\sqrt{2}}y_{1} + \frac{1}{\sqrt{6}}y_{2} - \frac{1}{\sqrt{3}}y_{3}$ or $y_{2} = -\frac{1}{\sqrt{6}}x_{1} + \frac{1}{\sqrt{6}}x_{2} + \frac{2}{\sqrt{6}}x_{3}$
 $x_{3} = \frac{2}{\sqrt{6}}y_{2} + \frac{1}{\sqrt{3}}y_{3} \qquad y_{3} = \frac{1}{\sqrt{3}}x_{1} - \frac{1}{\sqrt{3}}x_{2} + \frac{1}{\sqrt{3}}x_{3}$

We can already say that q is positive definite, as A is symmetric and all eigenvalues of A are positive (3, 3, 6). We can also say that q is positive definite if all corner minors of A are positive.

Order 1 corner minor = det(4)
= 4 > 0
Order 2 corner minor =
$$\begin{vmatrix} 4 & -1 \\ -1 & 4 \end{vmatrix}$$

= 4(4) - (-1)(-1)
= 15 > 0
Order 3 corner minor = $\begin{vmatrix} 4 & -1 & 1 \\ -1 & 4 & -1 \\ 1 & -1 & 4 \end{vmatrix}$
= 4(4(4) - 1) + (-4 + 1) + (1 - 4)
= 54 > 0

All corner minors are positive $\Rightarrow q$ is positive definite.

Problem 3

$$q(x) = \sum_{i,j} a_{ij} x_i x_j = \sum_{i < j} (x_i - x_j)^2, \ 1 \le i, j \le n$$

$$\Rightarrow \sum_i a_{ii} x_i^2 + \sum_{i \neq j} a_{ij} x_i x_j = (n-1) \sum_i x_i^2 - 2 \sum_{i < j} x_i x_j \ \forall x$$

$$\Rightarrow \sum_i a_{ii} x_i^2 = \sum_i (n-1) x_i^2 , \quad \sum_{i \neq j} a_{ij} x_i x_j = \sum_{i < j} -2 x_i x_j$$

$$\Rightarrow a_{ii} = n-1 \ \forall i \quad , \quad a_{ij} + a_{ji} = -2 \ \forall i \neq j$$

Consider $x_1 = x_2 = \ldots = x_n = 1$, i.e. $x = \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix}$. Then $q(x) = 0 \Rightarrow q(x)$ is not

positive definite. Thus, A cannot have full rank. If $a_{ij} \neq a_{ji}$ then the columns of A are linearly independent, and thus A has full rank. Thus $a_{ij} = a_{ji} = -1$.

$$\Rightarrow A_n = \begin{pmatrix} n-1 & -1 & \dots & -1 \\ -1 & n-1 & \dots & -1 \\ \vdots & \vdots & \ddots & \vdots \\ -1 & -1 & \dots & n-1 \end{pmatrix}$$

$$\chi_{A_1}(t) = \det(t) = t \Rightarrow \lambda = 0 \Rightarrow (0, 0, 1)$$

$$\chi_{A_2}(t) = \begin{vmatrix} t-1 & 1 \\ 1 & t-1 \end{vmatrix} = t(t-2) \Rightarrow \lambda = 0, 2 \Rightarrow (1, 0, 1)$$

$$\chi_{A_3}(t) = \begin{vmatrix} t-2 & 1 & 1 \\ 1 & t-2 & 1 \\ 1 & 1 & t-2 \end{vmatrix} = t(t-3)^2 \Rightarrow \lambda = 0, 3, 3 \Rightarrow (2, 0, 1)$$

$$\chi_{A_4}(t) = \begin{vmatrix} t-3 & 1 & 1 & 1 \\ 1 & t-3 & 1 & 1 \\ 1 & 1 & t-3 & 1 \\ 1 & 1 & t-3 \end{vmatrix} = t(t-4)^3 \Rightarrow \lambda = 0, 4, 4, 4 \Rightarrow (3, 0, 1)$$

$$\chi_{A_5}(t) = \begin{vmatrix} t-4 & 1 & 1 & 1 & 1 \\ 1 & t-4 & 1 & 1 & 1 \\ 1 & 1 & t-4 & 1 & 1 \\ 1 & 1 & 1 & t-4 & 1 \\ \vdots \\ \Rightarrow \chi_{A_n}(t) = t(t-n)^{n-1} \Rightarrow \lambda = 0, n, n, \dots, n \Rightarrow (n-1, 0, 1)$$

:. Signature of q(x) = (n - 1, 0, 1)

Alternatively, we can use the fact that A is symmetric to find n_+, n_- and n_0 . There exists only one vector in $\ker(A) \Rightarrow n_0 = 1$ and $\operatorname{rk}(A) = n_+ + n_- = n - 1$. $q(x) \ge 0 \Rightarrow n_- = 0 \Rightarrow n_+ = n - 1$.

: Signature of q(x) = (n - 1, 0, 1), as before.

Problem 4

$$q(x) = x^{T}Ax$$

$$= (x_{1} \quad x_{2}) (\frac{1}{3} \quad \frac{1}{a}) (\frac{x_{1}}{x_{2}})$$

$$= x_{1}^{2} + ax_{2}^{2} + 4x_{1}x_{2}$$

$$= (x_{1}^{2} + 4x_{1}x_{2} + 4x_{2}^{2}) + (a - 4)x_{2}^{2}$$

$$= (x_{1} + 2x_{2})^{2} + (a - 4)x_{2}^{2}$$

$$> 0 \forall x_{1}, x_{2} \in \mathbb{R} \setminus \{0\}$$

$$(x_{1} + 2x_{2})^{2} \geq 0$$

$$\Rightarrow (a - 4)x_{2}^{2} > 0$$

$$\Rightarrow a > 4$$