

## Maths 3468 quizzes

### 2: Friday 10/2/12

**Note about Floyd-Warshsall:** diagonal entries  $W[i][i]$  should be initialised to 0.

(1) The runtime of Dijkstra's algorithm was not discussed, but  $O(n^2)$  was mentioned in the notes, with a simple implementation, with  $O(m + n \log n)$  for more complex implementations.

Simple implementation:  $T$  stored as a linked list, for example.

What part of the algorithm produces this non-linear cost?

**Answer.** It is in selecting a temporary node  $u$ , i.e.,  $u \in T$ , with  $w(u)$  minimal. With a simple implementation, linear search will be needed with cost  $O(|T|)$ , and overall cost  $O(n^2)$ .

(2) It's interesting to modify Dijkstra's algorithm so that shortest paths from  $s$  to any  $v$  can easily be found. Describe such a scheme.

**Answer.** Add a parent field to each node. Initially all nodes have null parent. When a node  $u$  is selected, and whenever

$$w(u) + w(u, v) < w(v),$$

replace  $w(v)$  and let  $u$  be the (new) parent of  $v$ .

This gives a tree of shortest paths, and the shortest path from  $s$  to  $v$  can be recovered by tracing back from  $v$  to the root.

(3) The same can be done with the Floyd-Warshall algorithm, though not so easily. It is enough to produce a matrix  $P$  such that for each  $i, j$ ,  $P[i][j]$  is the *second node* on a shortest weighted path from  $i$  to  $j$ .

Certainly  $P[i][j]$  should be initialised to  $j$  or some dummy value, depending on whether or not  $(i, j)$  is an edge of the graph.

(i) How should  $P[i][j]$  be updated when

$$W[i][j] = W[i][k] + W[k][j]$$

is executed?

**Answer.**

$$P[i][j] = P[i][k]$$

(ii) How does one construct a shortest path from  $i$  to  $j$ , using the matrix  $P$ ? (just an informal description).

**Answer.** For a shortest path from  $i$  to  $k$ , if  $i \neq k$ , assuming a path exists,

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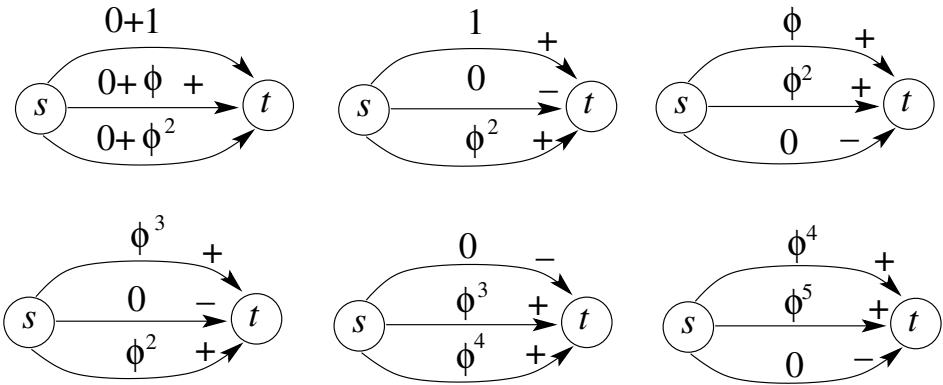
j = i;
while ( j != k && j != dummy value )
{
    output j;
    j = P[j][k];
}

```

(Of course if  $j$  assumes dummy value then there is no such path).

(4) The following is an example of where a flow can be augmented infinitely often, converging to the maximum flow but not reaching it (in finite time). Recall that a flow network can be a multigraph. This makes the construction simpler. The network has edges and capacities as shown, where  $\phi$  is the reciprocal of the golden ratio:  $\phi^2 + \phi = 1$ . Also, *residual* capacities are shown, i.e.,  $c(e) - f(e)$  on all edges  $e$  — not consistent with the definition for an augmenting path.

Explain what is going on, and how the process can continue indefinitely. (Figure corrected).



**Answer.** At each step there is one saturated edge, initially the middle one with a flow value of  $\phi$ . Thereafter there is always an augmenting path with two forward edges, residual capacity  $\phi^n, \phi^{n+1}$ , and one backward edge with flow value  $\geq \phi^{n+1}$ . The flow can be augmented by  $\phi^{n+1}$  leaving one saturated edge and two others with residual capacities  $\phi^{n+1}$  and  $\phi^{n+2}$ . This is because

$$\phi^n - \phi^{n+1} = \phi^{n+2}$$

Hence there can be infinitely many augmentations.