

2. Representations of S_3 Seen Geometrically and Algebraically

Today we look at reps of the symmetric group S_3 over the fields $\mathbb{R} = \mathbb{R}$ & $\mathbb{C} = \mathbb{C}$.

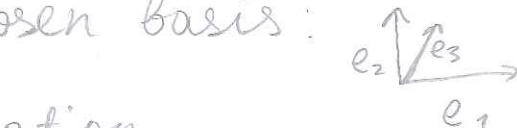
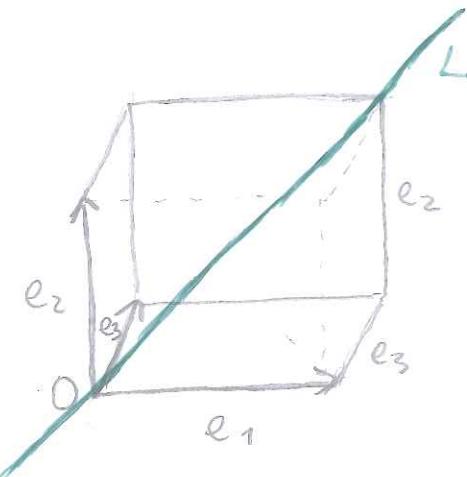
Recall the permutation rep. $V^{\text{perm}} = \underbrace{\mathbb{R}e_1 + \mathbb{R}e_2 + \mathbb{R}e_3}$,
with $\sigma \cdot e_i = e_{\sigma(i)}$, $\sigma \in S_3$, vector space over \mathbb{R} ,
with a basis (e_1, e_2, e_3) .

A) Geometrically ($\mathbb{R} = \mathbb{R}$):

V^{perm} is the plane \mathbb{R}^3 with a chosen basis:

$(123) \in S_3$ acts on \mathbb{R}^3 by a rotation

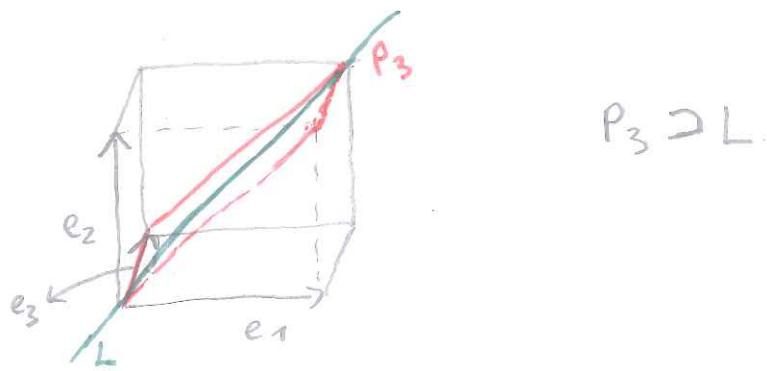
around the axis L with the angle $\frac{2\pi}{3}$:



$v_L = e_1 + e_2 + e_3$
is a direction
vector of L

(132) acts by a rotation around L
with angle $-\frac{2\pi}{3}$

(12) acts by reflexion w.r.t. the plane P_3 :



$$P_3 \supseteq L$$

(13) & (23) act by reflexions w.r.t.
similar planes P_2 & P_1 , both of which
contain L .

$\text{Id} \in S_3$ acts by identity.

We see that all $\sigma \in S_3$ fix L point-wise.

Moreover, they fix the plane P (as a whole,
not point-wise this time). Here P is the
plane passing through 0
orthogonally to L .

The reason: rotations & reflexions
preserve angles, so if σ fixes L , it sends things
orthogonal to L to other things orthogonal to L .



Thus the S_3 -action preserves the vector space
decomposition $V^{\text{perm}} = L \oplus P$.

$$\dim = 3 \quad 1 \quad 2$$

P does not decompose further, since (123) rotates any line in P by $\frac{2\pi}{3}$, and thus doesn't fix it.

Let us identify $L \otimes P$ with the reps we have already seen:

- $L \cong V^{\text{tr}}$ (the trivial rep. of degree 1).

- $P = \{v \in \mathbb{R}^3 \mid v \perp v_L\}$

$$= \left\{ \begin{pmatrix} d_1 \\ d_2 \\ d_3 \end{pmatrix} \mid \left(\begin{pmatrix} d_1 \\ d_2 \\ d_3 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right) = 0 \right\}$$

$$= \left\{ \sum_{i=1}^3 d_i e_i \mid \sum_{i=1}^3 d_i = 0, d_i \in \mathbb{R} \right\}$$

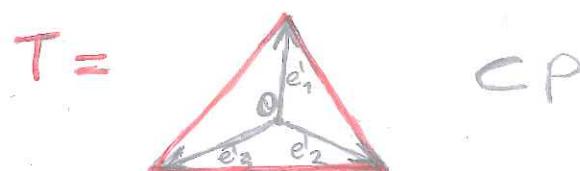
A basis of P : $(e_1 - e_3, e_2 - e_3)$.

P contains the vectors $e'_i = e_1 + e_2 + e_3 - 3e_i$, $i = 1, 2, 3$

The S_3 -action permutes the e'_i : $\sigma \cdot e'_i = e'_{\sigma(i)}$.

In particular, the $\frac{2\pi}{3}$ -rotation realised by (123)

acts by $e'_1 \xrightarrow{\text{rot}} e'_2 \downarrow e'_3$. So the triangle



is equilateral. Our S_3 -action on P is then precisely the action of S_3 on \mathbb{R}^2 fixing the triangle T , seen in Lecture 1.

P is called the standard rep. of S_3 , denoted by V^{st} .

This is the general pattern we'll prove for reps of finite groups: they decompose into elementary pieces (indecomposable reps), belonging to some finite list.



The geometric approach is nice for getting intuitions, but difficult to implement when dimensions increase. We'll thus describe the same reps algebraically.

(B) Algebraically ($\mathbb{k} = \mathbb{R}$ or $\mathbb{k} = \mathbb{C}$)

is defined
to be

(or any field of characteristic 0)

$$L := \{ \lambda(e_1 + e_2 + e_3) \mid \lambda \in \mathbb{k} \}$$

$$\dim_{\mathbb{k}} L = 1$$

$$V^{\text{st}} := \left\{ \sum_{i=1}^3 \lambda_i e_i \mid \lambda_i \in \mathbb{k}, \sum_{i=1}^3 \lambda_i = 0 \right\}$$

$$\dim_{\mathbb{k}} V^{\text{st}} = 2, \text{ basis:}$$

are subspaces of V^{perm} .

$$(e_1 - e_3, e_2 - e_3)$$

(*) $V^{\text{perm}} = L \oplus V^{\text{st}}$ as vector spaces over \mathbb{k} . Indeed,
direct sum

(1) $L \cap V^{\text{st}} = \{0\}$, since $v \in L \cap V^{\text{st}} \Rightarrow v = \lambda(e_1 + e_2 + e_3)$, $\lambda \in \mathbb{k}$,

and $3\lambda = 0$ (since $v \in V^{\text{st}} \Rightarrow \lambda = 0 \Rightarrow v = 0$).

$$(2) \dim_{\mathbb{k}} V^{\text{perm}} = \underset{3}{\overset{\parallel}{\dim}} L + \underset{1}{\overset{\parallel}{\dim}} V^{\text{st}} + \underset{2}{\overset{\parallel}{\dim}}$$

Reminder (Linear algebra): $(*) \Leftrightarrow (1) \wedge (2)$

for finite-dimensional spaces

Further, L & V^{st} are S_3 -invariant.

(a) for L : $\sigma \cdot (\sum_{i=1}^3 e_i) = \sum e_{\sigma(i)} = \sum e_i$

(b) for V^{st} : $\sigma \cdot (\sum_{i=1}^3 d_i e_i) = \sum d_i e_{\sigma(i)}$, so the S_3 -action preserves the sum of coefficients.

(a) also gives $L \cong V^{tr}$.

Conclusion: $V^{\text{perm}} \cong V^{tr} \oplus V^{st}$ (decomposition of S_3 -rep)
this time

Let us show that V^{st} is indecomposable.

Otherwise there would be an S_3 -invariant subspace $W \subsetneq V^{st}$, $W \neq \{0\}$. Choose a $w = \sum d_i e_i \in W$, $w \neq 0$. One has either $d_1 \neq d_3$ or $d_2 \neq d_3$ (otherwise $w \in L$, and $w \in W \subset V^{st}$, but $L \cap V^{st} = \{0\}$).

Suppose, without the loss of generality, $d_2 \neq d_3$.

$$W \ni w = d_1 e_1 + d_2 e_2 + d_3 e_3$$

$$W \ni (123) \cdot w = d_1 e_1 + d_3 e_3 + d_2 e_2$$

$$\Rightarrow W \ni w - (123) \cdot w = (d_2 - d_3)(e_2 - e_3) \quad \left\{ \begin{array}{l} \Leftarrow S_3\text{-invariance} \\ \Leftarrow \text{linearity} \end{array} \right.$$

$$\Rightarrow W \ni e_2 - e_3 \quad \left\{ \begin{array}{l} \Leftarrow d_2 - d_3 \neq 0 \end{array} \right.$$

$$\Rightarrow W \ni (12) \cdot (e_2 - e_3) = e_1 - e_3 \quad \left\{ \begin{array}{l} \Leftarrow S_3\text{-invariance} \\ \Leftarrow (e_1 - e_3, e_2 - e_3) \text{ is a basis} \end{array} \right.$$

$$\Rightarrow W = V^{st}, \text{ contradiction.}$$

We'll see the same decomposition for all groups S_n .