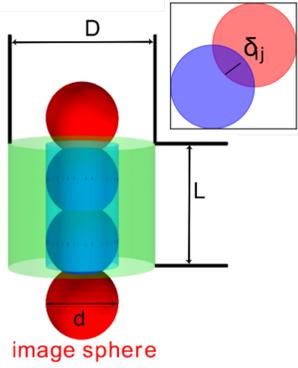




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## The model: Confined soft spheres



- Soft interaction dependent on overlap:  
 $U_{\text{soft}}(\delta_{ij}) = \varepsilon \delta_{ij}^2$
- Soft confinement dependent on wall overlap:  
 $U_{\text{conf}}(\rho_i) = \varepsilon \rho_i^2$
- Periodic boundaries at top and bottom: image spheres twisted by angle  $\alpha$
- pressure term  $pV = p\pi \left(\frac{D}{2}\right)^2 L$
- Energy:

$$E(\{\vec{r}_i\}, L) = \sum_{ij} U_{\text{soft}}(\delta_{ij}) + \sum_i U_{\text{conf}}(\rho_i) + pV$$

### The Algorithm: Energy minimisation

- Start from random initial configuration
- Find energy minimum for given pressure  $p$
- The **Basin-Hopping algorithm**
  - Monte-Carlo type algorithm
  - Global min. method in combination with direct min. (BFGS)
  - Directed **random** walk in parameter space ( $3N + 2$ )
  - niter steps with stepsize at temperature  $T$

## In the limit of hard spheres (no overlap)

hard spheres = no overlap

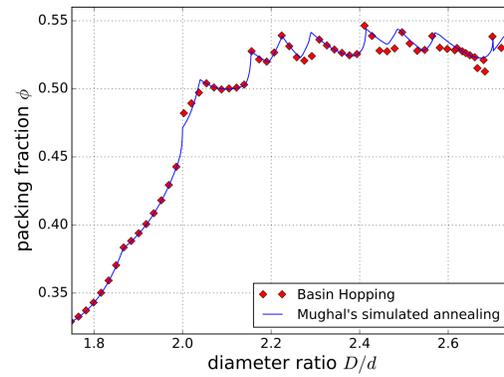


Figure 2: Comparison with present hard sphere methods [5, 3]

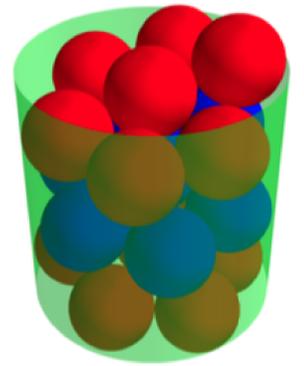


Figure 3: Hard sphere packing.

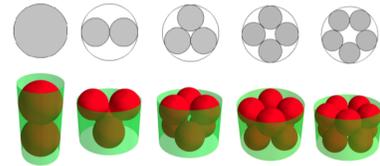
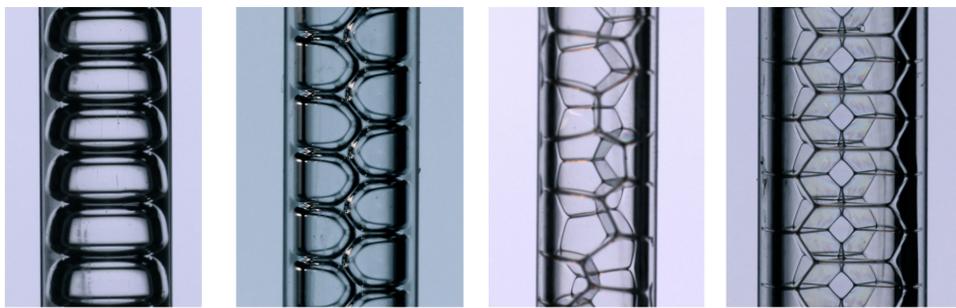


Figure 4: Columnar crystals.

For each diameter ratio  $D/d$ :

1. decrease packing fraction  $\phi = NV_{\text{sphere}}/V$
2. minimise energy
3. if overlap: continue with 1.
4. else: hard sphere packing found

## Experimental structures



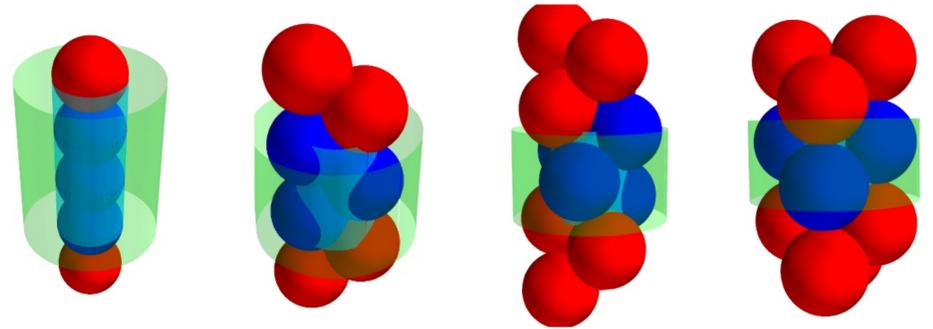
Bamboo

(2, 1, 1)

(3, 2, 1)

(4, 2, 2)

## Simulation structures



## Coexistence of two structures

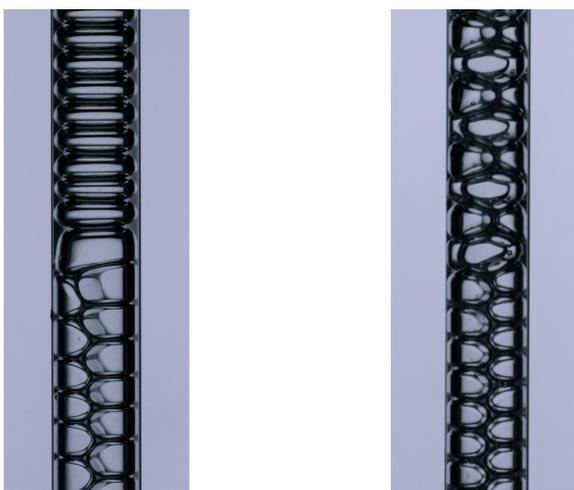


Figure 5: **Bamboo** and **stair case** (2, 1, 1).  
Figure 6: stair case and (2, 2, 0).

## Results for the soft sphere simulation

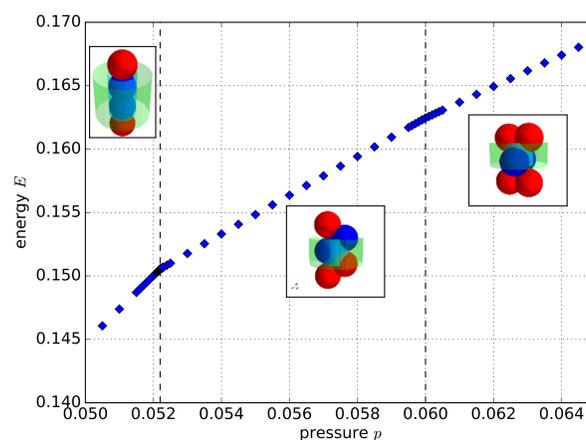


Figure 7: Energy per particle  $E$  for different pressures  $p$ .

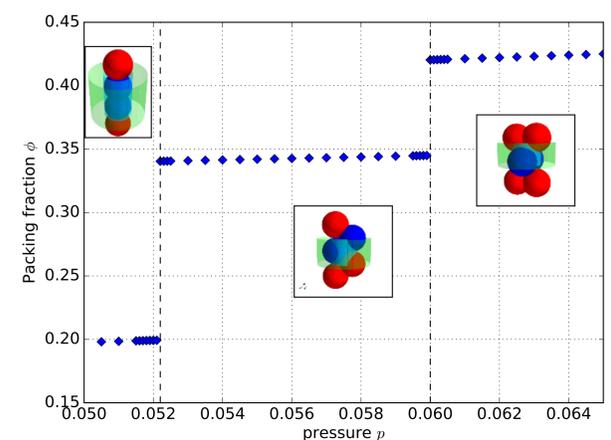


Figure 8: Packing fraction  $\phi$  for different pressures  $p$ .

## References

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