

List of Theorems from Geometry

2321, 2322

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There's already a list of geometry theorems out there, but the course has changed since, so here's a new one. They're in order of 'appearance in my notes', which corresponds reasonably well to chronological order. 24 onwards is Hilary term stuff.

The following theorems have actually been asked (in either summer or schol papers):

5, 7, 8, 17, 18, 20, 21, 22, 26, 27, 30 a), 31 (associative only), 35, 36 a), 37, 38, 39, 43, 45, 47, 48.

Definitions are also asked, which aren't included here.

1. On a finite-dimensional real vector space, the statement 'V is open in M' is independent of the choice of norm on M.
2. Let $\mathbb{R}^n \supset V \xrightarrow{f} \mathbb{R}^m$ be differentiable with $f = (f^1, \dots, f^m)$. Then $\mathbb{R}^n \xrightarrow{f'} \mathbb{R}^m$, and $f' = \left(\frac{\partial f^i}{\partial x_j} \right)$
3. Let $M \supset V \xrightarrow{f} N, a \in V$. Then f is differentiable at $a \Rightarrow f$ is continuous at a .
4. $f = (f^1, \dots, f^n)$ continuous $\Leftrightarrow f^i$ continuous, and same for differentiable.
5. The chain rule for functions on finite-dimensional real vector spaces.
6. The chain rule for functions of several real variables.
7. Let $\mathbb{R}^n \supset V \xrightarrow{f} \mathbb{R}, V$ open. Then f is $C^1 \Leftrightarrow \frac{\partial f}{\partial x_i}$ exists and is continuous, for $i = 1, \dots, n$.
8. Let $\mathbb{R}^n \supset V \xrightarrow{f} \mathbb{R}, V$ open. f is C^2 . Then $\frac{\partial^2 f}{\partial x^i \partial x^j} = \frac{\partial^2 f}{\partial x^j \partial x^i}$
9. $(\phi \circ \psi)_* = \phi_* \circ \psi_*$, where ϕ, ψ are maps of manifolds, and ϕ_* is the push-forward of ϕ .
10. Something about the components of the push-forward. Doubt this'll come up.
11. $B_x(a, r)$ is open in X .
12. $M \supset X \xrightarrow{f} Y \subset N$, M, N normed, finite-dimensional vector spaces. Then f is continuous at $a \Leftrightarrow$ for each open NBD V of $f(a)$ in Y , there exists an open NBD W of a in X , such that $f(W) \subset V$.
13. Let $X \subset M$, M a finite-dimensional normed space. Then any union of open sets is open, any finite intersection of open sets is open, and a set $V \subset X$ is open in $X \Leftrightarrow$ there exists W open in M such that $V = W \cap X$.
14. Let X, Y be topological spaces, with $f : X \rightarrow Y$. Then f is continuous $\Leftrightarrow V$ open in $Y \Rightarrow f^{-1}V$ open in X .
15. f, g continuous $\Rightarrow f \circ g$ continuous.
16. The mean value theorem for vector-valued functions.

17. The inverse function theorem.
18. The implicit function theorem.
19. Something about coordinate systems, the statement of the theorem is literally 8 times the length of the proof.
20. If u_i is a basis for M , then the coordinate functions u^i are the basis for the dual space M^* .
21. The pull-back commutes with the differential.
22. The chain rule for maps of manifolds (*identical to theorem 9*).
23. Properties of the operator norm. (*Anachronistic - I didn't have it down as a theorem when I first made up my notes.*)
24. If ω is an exact one-form on X , then $\int \omega$ is path-independent.
25. Integration by parts.
26. Let u_i be a basis for M . Then, for example, $u^i \otimes u_j \otimes u^k$ is a basis for $M^* \otimes M \otimes M^*$.
27. Contraction is well-defined independent of choice of basis.
28. The group S_r acts on the vector space $\otimes^r M^*$ by linear transformations.
29. If $T \in \otimes^r M^*$, then $\sum_{\sigma \in S_r} \varepsilon^\sigma \sigma \cdot T$ is skew-symmetric.
30. Let $S \in \otimes^s M^*, T \in \otimes^t M^*$. Then
 - a) $a[(aS) \otimes T] = a[S \otimes T] = a[S \otimes (aT)]$
 - b) $a[S \otimes T] = (-1)^{st} a[T \otimes S]$
31. The wedge product is bilinear, associative, and super-commutative.
32. Let u_1, \dots, u_n be a basis for M . And let $i_1 < \dots < i_r, j_1 < \dots < j_r$. Then $u^{i_1} \wedge \dots \wedge u^{i_r} [u_{j_1}, \dots, u_{j_r}] = 1$ if $i_k = j_k$, and 0 otherwise.
33. Let $\Lambda^r M^*$ be the vector space of skew-symmetric tensors of type $\underbrace{M \times \dots \times M}_r \rightarrow \mathbb{R}$. Let u_i, \dots, u_n be a basis of M . Then
 - a) $\Lambda^r M^* = \{0\}$ if $r > n$.
 - b) The tensor $\sum_{i_1 < \dots < i_n} \alpha_{i_1, \dots, i_r} u^{i_1} \wedge \dots \wedge u^{i_r}$ has components α_{i_1, \dots, i_r} for $i_1 < \dots < i_n$.
 - c) $\{u^{i_1} \wedge \dots \wedge u^{i_r}\}_{i_1 < \dots < i_r}$ is a basis for $\Lambda^r M^*$, so its dimension is $\frac{n!}{r!(n-r)!}$
34. T_*, T^* preserve commutative diagrams, ie $(UT)_* = U_* T_*$, and $(UT)^* = T^* U^*$.
35. The pullback/pushforward preserve the tensor product, skew-symmetry, and wedge product.
36. If M is an n -dimensional, real, oriented vector space with non-degenerate symmetric scalar product, then
 - a) The volume form $u^1 \wedge \dots \wedge u^n$ is independent of choice of standard basis u_1, \dots, u_n of M .
 - b) For any positively oriented basis w_1, \dots, w_n , we have $\text{vol}(w_1, \dots, w_n) = \sqrt{|\det(w_i | w_j)|}$.
37. Let u_1, \dots, u_n be a standard basis with $(u_i | u_i) = \delta_i = \pm 1$. Then $\star(u^1 \wedge \dots \wedge u^r) = \delta_{r+1} \dots \delta_n u^{r+1} \wedge \dots \wedge u^n$.
38. Defining the linear operator $\Omega^r(V) \xrightarrow{d} \Omega^{r+1}(V)$, and then
 - a) The Leibniz rule: $d(\omega \wedge \eta) = (d\omega) \wedge \eta + (1)^r \omega \wedge (d\eta)$ if ω is an r -form.
 - b) $dd\omega = 0$.

- c) The definition of $d\omega$ is independent of the choice of coordinates on V .
39. The pull-back of differential forms is a linear operator, preserves wedge products, and commutes with the differential.
 40. $\int_V \omega$ is independent of choice of coordinates on V . *(In my notes, there are quotation marks around this being a theorem, so it may not be examinable.)*
 41. Let $X \xrightarrow{\phi} Y$ be a diffeomorphism of n -dimensional oriented manifolds, preserving orientations, and V a coordinate domain on X , ω an n -form on Y , then... $\int_{\phi V} \omega = \int_V \phi^* \omega$.
 42. $\int_X \omega$ is independent of the choice of partition of unity. *(Another potentially fake theorem.)*
 43. Stokes' Theorem.
 44. Solutions to the Laplace equation on a region are unique. *(This is almost certainly not a proper theorem we did, but hey, it might come up in methods.)*
 45. Poincaré's Lemma.
 46. Let u_1, \dots, u_n be a moving frame on a Riemannian n -dimensional manifold. Then there exists a unique skew-symmetric $n \times n$ matrix $\Omega = (\omega_j^i)$ of 1-forms such that $du^i = -\omega_j^i \wedge u^j$.
 47. x_1, \dots, x_r are linearly independent if and only if $x_1 \wedge \dots \wedge x_r \neq 0$. *(This and the next 'theorem' came up in a problem set.)*
 48. x_1, \dots, x_r generate the same subspace as y_1, \dots, y_r if and only if $x_1 \wedge \dots \wedge x_r$ is a scalar multiple of $y_1 \wedge \dots \wedge y_r$.