

# The Equations of Motion of Systems of Particles

## 1 System of Coupled Anharmonic Oscillators

Our potential  $U$  describes a system of  $n$  coupled anharmonic oscillators,

$$U(x_1, \dots, x_n) = \sum_{i=1}^{n-1} \frac{\kappa}{2}(x_{i+1} - x_i)^2 + \sum_{i,j=1}^n \frac{\lambda}{4}(x_i - x_j)^4.$$

The equations of motion of a system of  $n$  particles are given by

$$m_i \ddot{x}_i = -\partial_i U(x_1, \dots, x_n),$$

so

$$\begin{aligned} m_i \ddot{x}_i &= -\partial_i \sum_{j=1}^{n-1} \frac{\kappa}{2}(x_{j+1} - x_j)^2 - \partial_i \sum_{j,k=1}^n \frac{\lambda}{4}(x_k - x_j)^4 \\ &= -\kappa \sum_{j=1}^{n-1} (x_{j+1} - x_j)(\delta_{i,j+1} - \delta_{ij}) - \lambda \sum_{j,k=1}^n (x_k - x_j)^3 (\delta_{ik} - \delta_{ij}) \\ &= -\kappa \sum_{j=1}^{n-1} \delta_{i,j+1} (x_{j+1} - x_j) + \kappa \sum_{j=1}^n \delta_{ij} (x_{j+1} - x_j) \\ &\quad - \lambda \sum_{j,k=1}^n \delta_{ik} (x_k - x_j)^3 + \lambda \sum_{j,k=1}^n \delta_{ij} (x_k - x_j)^3 \\ &= -\kappa (x_i - x_{i-1}) \sum_{j=1}^{n-1} \delta_{i,j+1} + \kappa (x_{i+1} - x_i) \sum_{j=1}^{n-1} \delta_{ij} \\ &\quad - \lambda \sum_{j=1}^n (x_i - x_j)^3 + \lambda \sum_{k=1}^n (x_k - x_i)^3 \\ &= -\kappa (x_i - x_{i-1}) \sum_{j=1}^{n-1} \delta_{i,j+1} + \kappa (x_{i+1} - x_i) \sum_{j=1}^{n-1} \delta_{ij} \\ &\quad - \lambda \sum_{j=1}^n (x_i - x_j)^3 - \lambda \sum_{k=1}^n (x_i - x_k)^3 \end{aligned}$$

$$= -\kappa(x_i - x_{i-1}) \sum_{j=1}^{n-1} \delta_{i,j+1} + \kappa(x_{i+1} - x_i) \sum_{j=1}^{n-1} \delta_{ij} - 2 \sum_{j=1}^n \lambda(x_i - x_j)^3.$$

Note that

$$\sum_{j=1}^{n-1} \delta_{i,j+1} = \begin{cases} 1 & \text{if } i \neq 1 \\ 0 & \text{otherwise} \end{cases} = 1 - \delta_{i1}$$

and similarly for the sum over  $j$  of  $\delta_{ij}$ ,

$$\sum_{j=1}^{n-1} \delta_{ij} = \begin{cases} 1 & \text{if } i \neq n \\ 0 & \text{otherwise} \end{cases} = 1 - \delta_{in}.$$

Then

$$\begin{aligned} m_i \ddot{x}_i &= -\kappa(x_i - x_{i-1})(1 - \delta_{i1}) + \kappa(x_{i+1} - x_i)(1 - \delta_{in}) - 2 \sum_{j=1}^n \lambda(x_i - x_j)^3 \\ &= -\kappa(x_i - x_{i-1}) + \kappa(x_{i+1} - x_i) + \kappa\delta_{i1}(x_i - x_{i-1}) - \kappa\delta_{in}(x_{i+1} - x_i) \\ &\quad - 2 \sum_{j=1}^n \lambda(x_i - x_j)^3 \\ &= -\kappa(2x_i - x_{i-1} - x_{i+1}) + \kappa\delta_{i1}x_1 + \kappa\delta_{in}x_n - 2 \sum_{j=1}^n \lambda(x_i - x_j)^3, \end{aligned}$$

where  $x_0 = x_{n+1} = 0$  by assumption.

## 2 $x^4$ with a Hyperbolic Term

*I think this question should possibly be  $U = \sum \kappa \cosh(x_{i+1} - x_i) + \sum \frac{\lambda}{4} x_i^4$ .*

Our potential is

$$U(x_1, \dots, x_n) = \sum_{i=1}^{n-1} \cosh(\kappa(x_{i+1} - x_i)) + \sum_{i=1}^n \frac{\lambda}{4} x_i^4.$$

The equations of motion of a system of  $n$  particles are given by

$$m_i \ddot{x}_i = -\partial_i U(x_1, \dots, x_n),$$

so

$$\begin{aligned} m_i \ddot{x}_i &= -\partial_i \sum_{j=1}^{n-1} \cosh(\kappa(x_{j+1} - x_j)) - \partial_i \sum_{j=1}^n \frac{\lambda}{4} x_j^4 \\ &= -\sum_{j=1}^{n-1} \sinh(\kappa(x_{j+1} - x_j)) \kappa(\delta_{i,j+1} - \delta_{ij}) - \sum_{j=1}^n \lambda x_j^3 \delta_{ij} \\ &= -\kappa \sum_{j=1}^{n-1} \delta_{i,j+1} \sinh(\kappa(x_{j+1} - x_j)) + \kappa \sum_{j=1}^{n-1} \delta_{ij} \sinh(\kappa(x_{j+1} - x_j)) - \lambda x_i^3 \end{aligned}$$

$$\begin{aligned}
&= -\kappa \sinh(\kappa(x_i - x_{i-1})) \sum_{j=1}^{n-1} \delta_{i,j+1} + \kappa \sinh(\kappa(x_{i+1} - x_i)) \sum_{j=1}^{n-1} \delta_{ij} - \lambda x_i^3 \\
&= -\kappa \sinh(\kappa(x_i - x_{i-1}))(1 - \delta_{i1}) + \kappa \sinh(\kappa(x_{i+1} - x_i))(1 - \delta_{in}) - \lambda x_i^3 \\
&= -\kappa \sinh(\kappa(x_i - x_{i-1})) + \kappa \sinh(\kappa(x_{i+1} - x_i)) \\
&\quad + \kappa \delta_{i1} \sinh(\kappa(x_i - x_{i-1})) - \kappa \delta_{in} \sinh(\kappa(x_{i+1} - x_i)) - \lambda x_i^3 \\
&= -\kappa (\sinh(\kappa(x_i - x_{i-1})) + \sinh(\kappa(x_i - x_{i+1}))) \\
&\quad + \kappa \delta_{i1} \sinh(\kappa x_1) + \kappa \delta_{in} \sinh(\kappa x_n) - \lambda x_i^3
\end{aligned}$$

since  $\sinh$  is odd, where we of course assume  $x_0 = x_{n+1} = 0$ .

### 3 The Toda Potential

The (non-periodic) Toda potential  $U$  is

$$U(x_1, \dots, x_n) = \sum_{i=1}^{n-1} \exp(\alpha(x_{i+1} - x_i)).$$

The equations of motion of a system of  $n$  particles are given by

$$m_i \ddot{x}_i = -\partial_i U(x_1, \dots, x_n),$$

so

$$\begin{aligned}
m_i \ddot{x}_i &= -\partial_i \sum_{j=1}^{n-1} \exp(\alpha(x_{j+1} - x_j)) \\
&= -\sum_{j=1}^{n-1} \partial_i (e^{\alpha x_{j+1}} \cdot e^{-\alpha x_j}) \\
&= -\sum_{j=1}^{n-1} (e^{\alpha x_{j+1}} \partial_i e^{-\alpha x_j} + e^{-\alpha x_j} \partial_i e^{\alpha x_{j+1}}) \\
&= -\sum_{j=1}^{n-1} (-\alpha \delta_{ij} e^{\alpha x_{j+1}} e^{-\alpha x_j} + \alpha \delta_{i,j+1} e^{-\alpha x_j} e^{\alpha x_{j+1}}) \\
&= -\sum_{j=1}^{n-1} \alpha \delta_{i,j+1} e^{\alpha(x_{j+1} - x_j)} + \sum_{j=1}^{n-1} \alpha \delta_{ij} e^{\alpha(x_{j+1} - x_j)} \\
&= -\alpha e^{\alpha(x_i - x_{i-1})} \sum_{j=1}^{n-1} \delta_{i,j+1} + \alpha e^{\alpha(x_{i+1} - x_i)} \sum_{j=1}^{n-1} \delta_{ij} \\
&= -\alpha e^{\alpha(x_i - x_{i-1})}(1 - \delta_{i1}) + \alpha e^{\alpha(x_{i+1} - x_i)}(1 - \delta_{in}) \\
&= -\alpha e^{\alpha(x_i - x_{i-1})} + \alpha e^{\alpha(x_{i+1} - x_i)} + \alpha \delta_{i1} e^{\alpha(x_i - x_{i-1})} - \alpha \delta_{in} e^{\alpha(x_{i+1} - x_i)} \\
&= -\alpha e^{\alpha(x_i - x_{i-1})} + \alpha e^{\alpha(x_{i+1} - x_i)} + \alpha \delta_{i1} e^{\alpha x_1} - \alpha \delta_{in} e^{-\alpha x_n}.
\end{aligned}$$

Again, we have to assume that  $x_0 = x_{n+1} = 0$ .