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## 3.8. Formal Description of the Minimum Cost Method

We describe the *Minimum Cost Method* for finding an initial basic feasible solution to a transportation problem.

Consider a transportation problem specified by positive integers mand *n* and non-negative real numbers  $s_1, s_2, \ldots, s_m$  and  $d_1, d_2, \ldots, d_n$ , where  $\sum_{i=1}^m s_i = \sum_{i=1}^n d_i$ . Let  $I = \{1, 2, \ldots, m\}$  and let  $J = \{1, 2, \dots, n\}$ . A feasible solution consists of an array of non-negative real numbers  $x_{i,j}$  for  $i \in I$  and  $j \in J$  with the property that  $\sum_{i \in I} x_{i,j} = s_i$  for all  $i \in I$  and  $\sum_{i \in I} x_{i,j} = d_j$  for all  $j \in J$ . The objective of the problem is to find a feasible solution that minimizes cost, where the cost of a feasible solution  $(x_{i,j}: i \in I \text{ and } j \in J)$  is  $\sum_{i \in I} \sum_{i \in J} c_{i,j} x_{i,j}$ .

In applying the Minimum Cost Method to find an initial basic solution to the Transportation we apply an algorithm that corresponds to the determination of elements  $(i_1, j_1), (i_2, j_2), \ldots, (i_{m+n-1}, j_{m+n-1})$  of  $I \times J$  and of subsets  $I_0, I_1, \ldots, I_{m+n-1}$  of I and  $J_0, J_1, \ldots, J_{m+n-1}$  of J such that  $I_0 = I$ ,  $J_0 = J$ , and such that, for each integer k between 1 and m + n - 1, exactly one of the following two conditions is satisfied:—

(i) 
$$i_k \notin I_k, j_k \in J_k, I_{k-1} = I_k \cup \{i_k\} \text{ and } J_{k-1} = J_k;$$
  
(ii)  $i_k \in I_k, j_k \notin J_k, I_{k-1} = I_k \text{ and } J_{k-1} = J_k \cup \{j_k\};$ 

Indeed let  $I_0 = I$ ,  $J_0 = J$  and  $B_0 = \{0\}$ . The Minimum Cost Method algorithm is accomplished in m + n - 1 stages.

Let k be an integer satisfying  $1 \le k \le m + n - 1$  and that subsets  $I_{k-1}$  of I,  $J_{k-1}$  of J and  $B_{k-1}$  of  $I \times J$  have been determined in accordance with the rules that apply at previous stages of the Minimum Cost algorithm. Suppose also that non-negative real numbers  $x_{i,j}$  have been determined for all ordered pairs (i,j) in  $I \times J$  that satisfy either  $i \notin I_{k-1}$  or  $j \notin J_{k-1}$  so as to satisfy the following conditions:—

• 
$$\sum_{j \in J \setminus J_{k-1}} x_{i,j} \leq s_i$$
 whenever  $i \in I_{k-1}$ ;

• 
$$\sum_{j \in J} x_{i,j} = s_i$$
 whenever  $i \notin I_{k-1}$ ;

• 
$$\sum_{i \in I \setminus I_{k-1}} x_{i,j} \leq d_j$$
 whenever  $j \in J_{k-1}$ ;

• 
$$\sum_{i \in I} x_{i,j} = d_j$$
 whenever  $j \notin J_{k-1}$ .

The Minimum Cost Method specifies that one should choose  $(i_k, j_k) \in I_{k-1} \times J_{k-1}$  so that

$$c_{i_k,j_k} \leq c_{i,j}$$
 for all  $(i,j) \in I_{k-1} \times J_{k-1}$ ,

and set  $B_k = B_{k-1} \cup \{(i_k, j_k)\}$ . Having chosen  $(i_k, j_k)$ , the non-negative real number  $x_{i_k, j_k}$  is then determined so that

$$x_{i_k,j_k} = \min\left(s_{i_k} - \sum_{j \in J \setminus J_{k-1}} x_{i_k,j}, d_{j_k} - \sum_{i \in I \setminus I_{k-1}} x_{i,j_k}\right)$$

The subsets  $I_k$  and  $J_k$  of I and J respectively are then determined, along with appropriate values of  $x_{i,j}$ , according to the following rules:—

## 3. The Transportation Problem (continued)

## (i) if

$$s_{i_k} - \sum_{j \in J \setminus J_{k-1}} x_{i_k,j} < d_{j_k} - \sum_{i \in I \setminus I_{k-1}} x_{i,j_k}$$

then we set  $I_k = I_{k-1} \setminus \{i_k\}$  and  $J_k = J_{k-1}$ , and we also let  $x_{i_k,j} = 0$  for all  $j \in J_{k-1} \setminus \{j_k\}$ ; (ii) if

$$s_{i_k} - \sum_{j \in J \setminus J_{k-1}} x_{i_k,j} > d_{j_k} - \sum_{i \in I \setminus I_{k-1}} x_{i,j_k}$$

then we set  $J_k = J_{k-1} \setminus \{j_k\}$  and  $I_k = I_{k-1}$ , and we also let  $x_{i,j_k} = 0$  for all  $i \in I_{k-1} \setminus \{i_k\}$ ; (iii) if

$$s_{i_k} - \sum_{j \in J \setminus J_{k-1}} x_{i_k,j} = d_{j_k} - \sum_{i \in I \setminus I_{k-1}} x_{i,j_k}$$

then we determine  $I_k$  and  $J_k$  and the corresponding values of  $x_{i,j}$  either in accordance with the specification in rule (i) above or else in accordance with the specification in rule (ii) above.

These rules ensure that the real numbers  $x_{i,j}$  determined at this stage are all non-negative, and that the following conditions are satisfied at the conclusion of the *k*th stage of the Minimum Cost Method algorithm:—

• 
$$\sum_{j \in J \setminus J_k} x_{i,j} \leq s_i$$
 whenever  $i \in I_k$ ;

• 
$$\sum_{j \in J} x_{i,j} = s_i$$
 whenever  $i \notin I_k$ ;

• 
$$\sum_{i \in I \setminus I_k} x_{i,j} \leq d_j$$
 whenever  $j \in J_k$ ;

• 
$$\sum_{i \in I} x_{i,j} = d_j$$
 whenever  $j \notin J_k$ .

At the completion of the final stage (for which k = m + n - 1) we have determined a subset *B* of  $I \times J$ , where  $B = B_{m+n-1}$ , together with non-negative real numbers  $x_{i,j}$  for  $i \in I$  and  $j \in I$  that constitute a feasible solution to the given transportation problem.

## 3.9. Formal Description of the Northwest Corner Method

The Northwest Corner Method for finding a basic feasible solution proceeds according to the stages of the Minimum Cost Method above, differing only from that method in the choice of the ordered pair  $(i_k, j_k)$  at the kth stage of the method. In the Minimum Cost Method, the ordered pair  $(i_k, j_k)$  is chosen such that  $(i_k, j_k) \in I_{k-1} \times J_{k-1}$  and

$$c_{i_k,j_k} \leq c_{i,j}$$
 for all  $(i,j) \in I_{k-1} imes J_{k-1}$ 

(where the sets  $I_{k-1}$ ,  $J_{k-1}$  are determined as in the specification of the Minimum Cost Method).

In applying the Northwest Corner Method, costs associated with ordered pairs (i, j) in  $I \times J$  are not taken into account. Instead  $(i_k, j_k)$  is chosen so that  $i_k$  is the minimum of the integers in  $I_{k-1}$  and  $j_k$  is the minimum of the integers in  $J_{k-1}$ . Otherwise the specification of the Northwest Corner Method corresponds to that of the Minimum Cost Method, and results in a basic feasible solution of the given transportation problem.