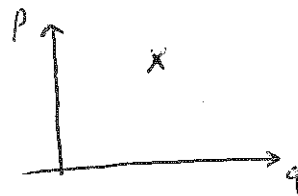


$$\mathcal{H}(\underbrace{q_1, q_2, \dots, q_m}_{\text{generalized coord}}, \underbrace{p_1, p_2, \dots, p_m}_{\text{generalized momenta}})$$

$2m$ -dimensional space of p 's and q 's is called phase space.

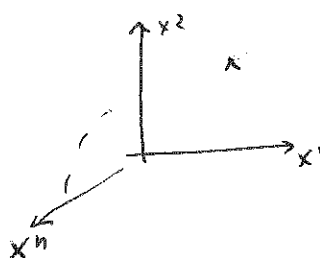
$$\dot{p}_i = -\frac{\partial \mathcal{H}}{\partial q_i}, \quad \dot{q}_i = \frac{\partial \mathcal{H}}{\partial p_i}$$



System of ODE's

n -dim. space $\{x_1^i, \dots, x_n^i\}$

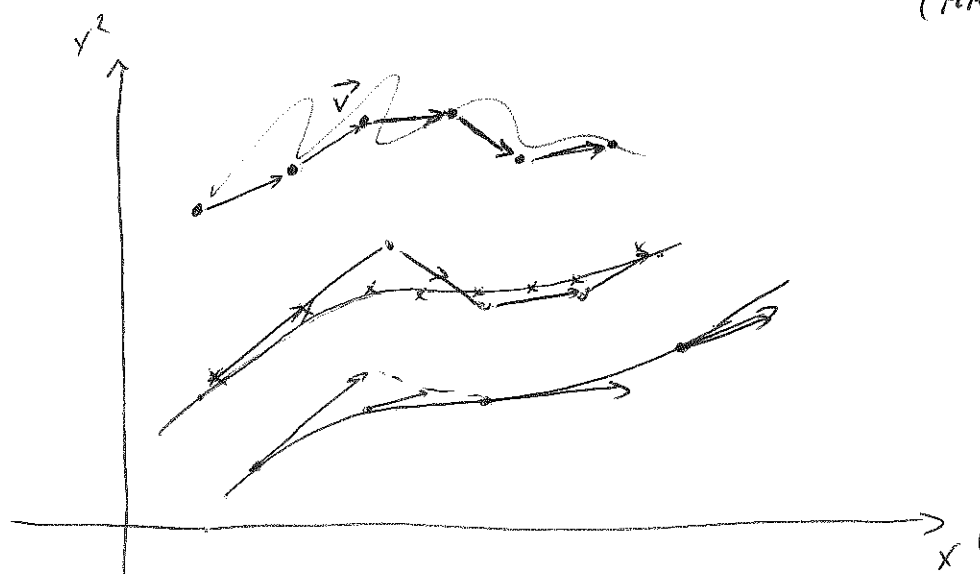
$$\frac{dx^i}{dt} = V^i(x)$$



$$x^i(t+\Delta t) = x^i(t) + V^i(x(t)) \Delta t + \mathcal{O}(\Delta t^2)$$

[Theorems about existence of soln, cons etc.]

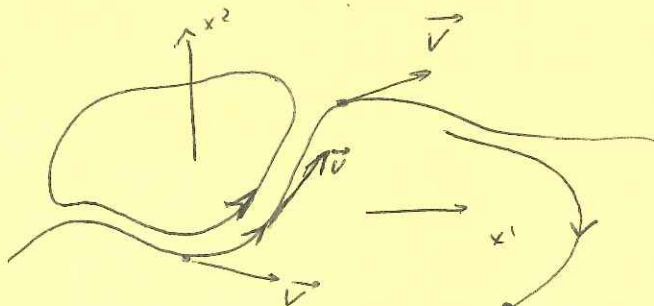
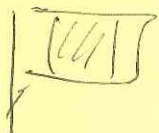
(MA2326: ODE)



Last time

$$\frac{dx^i}{dt} = v^i(x)$$

①
FET

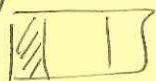


critical point x_0 : $\vec{v}(x_0) = 0$

? what is the behaviour near critical point

$$x^i = x_0^i + y^i; \quad \vec{y} \text{ is small}$$

$$\vec{y}^i = A^i_j y^j; \quad A^i_j = \left. \frac{\partial v^i}{\partial x^j} \right|_{x=x_0}$$



$$y^i = y^i(t) = c^i e^{\lambda t}$$

$$\lambda c^i e^{\lambda t} = A^i_j c^j e^{\lambda t}; \quad \hat{A} \cdot \vec{c} = \lambda \vec{c}$$

characteristic equation

$$\text{in solutions: } \{ \lambda_\alpha, \vec{c}_\alpha \}$$

General

$$y^i = \sum_{\alpha=1}^n B_\alpha c_\alpha^i e^{\lambda_\alpha t}$$

↑
constants of integration

②

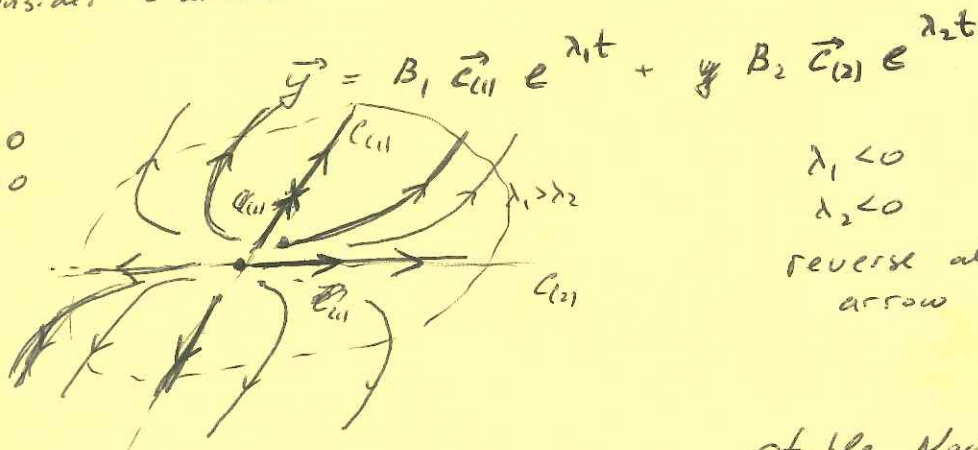
2-dimensional solutions

Consider 2-dimensional case:

③

$$\lambda_1 > 0$$

$$\lambda_2 > 0$$



$$\lambda_1 < 0$$

$$\lambda_2 < 0$$

reverse all
arrow

unstable Node

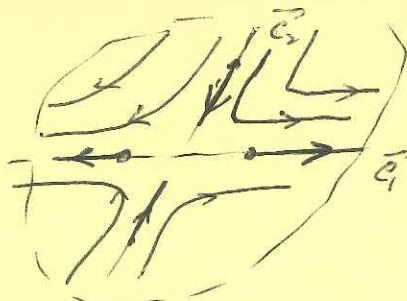
stable Node

no time to reach critical point.

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$$\lambda_1 > 0$$

$$\lambda_2 < 0$$

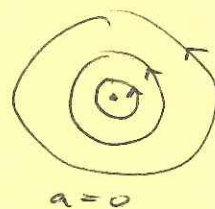
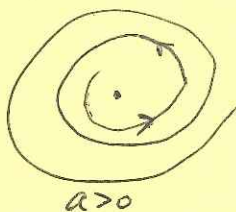


saddle point

$$\lambda_1 = a + ib$$

$$\lambda_2 = a - ib$$

$$\vec{y} = \text{Re} \left(\underset{\text{complex}}{B} \vec{c} e^{(a \pm ib)t} \right) + \text{c.c.}$$



focal points

center

② Formal solution [can skip]

$$\vec{y} = e^{\hat{A}t} \cdot \vec{y}_0 \quad ; \quad f(\hat{A}) = f(0) + \hat{A} f'(0) + \frac{1}{2} \hat{A}^2 f''(0) + \dots =$$

$$\hat{A} = U \underset{\text{diagonal}}{\Lambda} U^{-1}$$

$$\Lambda = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}$$

$$\hat{A}^n = U \Lambda^n U^{-1}$$

$$f(\hat{A}) = U f(\Lambda) U^{-1}$$

$$e^{\hat{A}t} = U e^{\Lambda t} U^{-1} = U \begin{pmatrix} e^{\lambda_1 t} & & \\ & \ddots & \\ & & e^{\lambda_n t} \end{pmatrix} U^{-1}$$

$$(\vec{y}(t)) = e^{\hat{A}t} \vec{y}_0$$

Question:

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