

## A SPECTRAL PROPERTY FOR THE SYMBOLIC DYNAMICAL SYSTEM

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Let  $(X, \phi)$  be a topological dynamical system, that is,  $X$  is a compact Hausdorff space and  $\phi : X \rightarrow X$  is a homeomorphism. Recently, a great deal of attention has been paid to topological dynamical systems with the so called chaotic behaviour, see [4, 6] and the bibliography therein for a comprehensive discussion about what the chaotic behaviour means mathematically.

We can consider the linear operator  $T_\phi$  defined by  $T_\phi(f) = f \circ \phi$ , where  $f$  is a function on  $X$ . If  $(X, \phi)$  and  $(Y, \psi)$  are topological dynamical systems, then they are *isomorphic*, and we write  $\phi \cong \psi$ , if there exists a homeomorphism  $h : X \rightarrow Y$  such that  $\phi = h^{-1}\psi h$ . Clearly,  $T_\phi = T_h T_\psi T_h^{-1}$  and therefore the spectral properties of  $T_\phi$  are natural invariants with respect to the isomorphism relationship. In particular, if the spectral properties of  $T_\phi$  are distinct from those of  $T_\psi$ , then we have  $\phi \not\cong \psi$ . It is interesting to investigate spectral properties of the operators  $T_\phi$  that are typical for the dynamical systems  $(X, \phi)$  with chaotic behaviour and this is the principal topic of the paper.

Consider the two-element group  $\mathbf{Z}_2 = \{0, 1\}$  under addition modulo 2 and define the set  $\Omega = \mathbf{Z}_2^{\mathbf{Z}}$ ; that is,  $\Omega$  is the set of all doubly infinite sequences  $\omega = (\omega_n)_{n \in \mathbf{Z}}$  with  $\omega_n \in \mathbf{Z}_2$ . Obviously  $\Omega$  is compact when endowed with the product topology and operation. Define the *shift transformation*  $\phi : \Omega \rightarrow \Omega$  by setting  $\phi(\omega) = (\omega')$ , where  $\omega'_n = \omega_{n+1}$  for all  $n \in \mathbf{Z}$ . The dynamical system  $(\Omega, \phi)$  is called the *symbolic dynamical system*. This is a traditional first choice for the system exemplifying chaotic behaviour [3]. Moreover, sometimes a dynamical system  $(X, \psi)$  is said to have chaotic behavior if there exists an invariant subset

$Y \subseteq X$  such that the dynamical system  $(Y, \psi|_Y)$  is isomorphic to the dynamical system  $(\Omega, \phi)$  [4].

**Theorem 1.**

(a) *There exists a continuous function  $g_0 \in C(\Omega)$  such that for each complex  $\lambda$ ,  $|\lambda| = 1$  the open ball  $B(g_0, 1/8)$  does not intersect the range of  $T_\phi - \lambda I$ .*

(b) *1 is the only eigenvalue of  $T_\phi$ .*

The property (a) of the operator  $T_\phi$  from Theorem 1 contrasts with the properties of the operator  $T_\phi$  in  $L_2(\mu)$  with the Bernoulli invariant measure  $\mu$ , [5]: for each  $\lambda \in \mathbf{T}$  the range of the operator  $\lambda I - T_\phi$  is dense in  $L_2(\mu)$ . Note also that the property mentioned in the theorem is invariant with respect to isomorphism:

**Corollary 2.** *Let  $(Y, \psi)$  be a topological dynamical system that is isomorphic to  $(\Omega, \phi)$ . Then the following spectral properties are valid:*

(a) *there exists a continuous function  $\tilde{g}_0 \in C(Y)$  such that for each  $\lambda \in \mathbf{T}$ , the open ball  $B(\tilde{g}_0, 1/8)$  does not intersect the range of  $T_\psi - \lambda I$ ;*

(b) *1 is the only eigenvalue of  $T_\psi$ .*

The *combination* of spectral properties mentioned in Theorem 1 looks rather peculiar and may be typical only for dynamical systems which behave in a similar way to the hyperbolic homeomorphisms, [3]. This suggests that the following definition could be useful.

**Definition.** A topological dynamical systems  $(X, \psi)$  is said to be *s-chaotic* if the operator  $T_\psi : C(X) \rightarrow C(X)$  has no eigenvalues apart from 1 and, on the other hand, there exists an open ball  $B(g_0, \varepsilon) \subset C(X)$  satisfying

$$B(g_0, \varepsilon) \cap \left( \bigcup_{\lambda \in \mathbf{T}} (T_\psi - \lambda I)(C(X)) \right) = \emptyset.$$

Note that by Corollary 2 this definition is in line with the definition of chaotic behaviour as suggested in [4]. The tentative analysis shows that this definition does not apply to the dynamical systems

$(Y, \psi)$  which are traditionally considered as ‘non-chaotic’ or have a non-chaotic component.

**Example 3.** As an example consider the irrational rotation  $\psi_\alpha$  of a circle:

$$e^{i\theta} \mapsto e^{i(\theta+2\pi\alpha)}$$

where  $0 \leq \theta < 2\pi$  and  $\alpha$  is a fixed irrational real number. This mapping is a typical example of an ergodic but not chaotic mapping. The spectrum of the operator  $T_{\psi_\alpha}$  coincides with the unit circle of the complex plane, but its further properties contrast sharply with those mentioned in the definition of  $s$ -chaotic behaviour: the operator  $T_{\psi_\alpha}$  has a countable number of eigenvalues  $\lambda_k = e^{i2\pi\alpha k}$ ,  $k = 0, \pm 1, \pm 2, \dots$  and for any  $\lambda \neq \lambda_k$ ,  $k = 0, \pm 1, \pm 2, \dots$  the range of the operator  $T_{\psi_\alpha} - \lambda I$  is dense in  $C(\mathbf{T})$ .

On the other hand, the chaotic homeomorphisms different from the symbolic dynamical system are likely to be  $s$ -chaotic.

**Problem.** Prove that an algebraic toral automorphism [4] is  $s$ -chaotic.

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**References**

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