## Course 424

## Group Representations II

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EELT3 Tuesday, 13 April 1999 16:00–17:30

Answer as many questions as you can; all carry the same number of marks.

All representations are finite-dimensional over  $\mathbb{C}$ .

1. What is meant by a *measure* on a compact space X? What is meant by saying that a measure on a compact group G is *invariant*? Sketch the proof that every compact group G carries such a measure. To what extent is this measure unique?

**Answer:** A measure  $\mu$  on X is a continuous linear functional

$$\mu: C(X) \to \mathbb{C},$$

where  $C(X) = C(X, \mathbb{R})$  is the space of real-valued continuous functions on X with norm  $||f|| = \sup |f(x)|$ .

The compact group G acts on C(G) by

$$(gf)(x) = f(g^{-1}x).$$

The measure  $\mu$  is said to be invariant under G if

$$\mu(gf)\mu(f)$$

for all  $q \in G$ ,  $f \in C(G)$ .

By an average F of  $f \in C(G)$  we mean a function of the form

$$F = \lambda_1 q_1 f + \lambda_2 q_2 f + \dots + \lambda_r q_r f,$$

where  $0 \le \lambda_i \le 1$ ,  $\sum \lambda_i = 1$  and  $g_1, g_2, \dots, g_r \in G$ .

If F is an average of f then

- (a)  $\inf f \le \inf F \le \sup F \le \sup f$ ;
- (b) If  $\mu$  is an invariant measure then  $\mu(F) = \mu(f)$ ;
- (c) An average of F is an average of f.

If we set

$$var(f) = \sup f - \inf f$$

then

$$var(F) \le var(f)$$

for any average F of f. We shall establish a sequence of averages  $F_0 = f, F_1, F_2, \ldots$  (each an average of its predecessor) such that  $var(F_i) \to 0$ . It follows that

$$F_i \to c \in \mathbb{R}$$
,

ie  $F_i(g) \to c$  for each  $g \in G$ .

Suppose  $f \in C(G)$ . It is not hard to find an average F of f with var(F) < var(f). Let

$$V = \{g \in G : f(g) < \frac{1}{2}(\sup f + \inf f),$$

ie V is the set of points where f is 'below average'. Since G is compact, we can find  $g_1, \ldots, g_r$  such that

$$G = g_1 V \cup \cdots \cup g_r V$$
.

Consider the average

$$F = \frac{1}{r} \left( g_1 f + \dots + g_r f \right).$$

Suppose  $x \in G$ . Then  $x \in g_iV$  for some i, ie

$$g_i^{-1}x \in V.$$

Hence

$$(g_i f)(x) < \frac{1}{2}(\sup f + \inf f),$$

and so

$$F(x) < \frac{r-1}{r} \sup f + \frac{1}{2r} (\sup f + \inf f)$$
$$= \sup f - \frac{1}{2r} \sup f - \inf f.$$

Hence  $\sup F < \sup f$  and so

$$var(F) < var(f)$$
.

This allows us to construct a sequence of averages  $F_0 = f, F_1, F_2, \dots$  such that

$$var(f) = var(F)_0 > var(F)_1 > var(F)_2 > \cdots.$$

But that is not sufficient to show that  $var(F)_i \to 0$ . For that we must use the fact that any  $f \in C(G)$  is uniformly continuous.

[I would accept this last remark as sufficient in the exam, and would not insist on the detailed argument that follows.]

In other words, given  $\epsilon > 0$  we can find an open set  $U \ni e$  such that

$$x^{-1}y \in U \implies |f(x) - f(y)| < \epsilon.$$

Since

$$(g^{-1}x)^{-1}(g^{-1}y) = x^{-1}y,$$

the same result also holds for the function gf. Hence the result holds for any average F of f.

Let V be an open neighbourhood of e such that

$$VV \subset U, \quad V^{-1} = V.$$

(If V satisfies the first condition, then  $V \cap V^{-1}$  satisfies both conditions.) Then

$$xV \cup yV \neq \emptyset \implies |f(x) - f(y)| < \epsilon.$$

For if xv = yv' then

$$x^{-1}y = vv'^{-1} \in U.$$

Since G is compact we can find  $g_1, \ldots, g_r$  such that

$$G = g_1 V \cup \cdots \cup g_r V$$
.

Suppose f attains its minimum inf f at  $x_0 \in g_iV$ ; and suppose  $x \in g_jV$ . Then

$$g_i^{-1}x_0, \ g_i^{-1}x \in V.$$

Hence

$$(g_i^{-1}x)^{-1}(g_i^{-1}x_0) = (g_ig_i^{-1}x)^{-1}x_0 \in U,$$

and so

$$|f(g_ig_j^{-1}x) - f(x_0)| < \epsilon.$$

In particular,

$$(g_j g_i^{-1} f)(x) < \inf f + \epsilon.$$

Let F be the average

$$F = \frac{1}{r^2} \sum_{i,j} g_j g_i^{-1} f.$$

Then

$$\sup F < \frac{r^2 - 1}{r^2} \sup f + \frac{1}{r^2} (\inf f + \epsilon),$$

and so

$$var(F) < \frac{r^2 - 1}{r^2} var(f) + \frac{1}{r^2} \epsilon$$

$$< \frac{r^2 - 1/2}{r^2} var(f),$$

if  $\epsilon < \operatorname{var}(f)/2$ .

Moreover this result also holds for any average of f in place of f. It follows that a succession of averages of this kind

$$F_0 = f, F_1, \ldots, F_s$$

will bring us to

$$\operatorname{var}(F)_s < \frac{1}{2}\operatorname{var}(f).$$

Now repeating the same argument with  $F_s$ , and so on, we will obtain a sequence of successive averages  $F_0 = f, F_1, \ldots$  with

$$var(F)_i \downarrow 0.$$

It follows that

$$F_i \to c$$

(the constant function with value c).

It remains to show that this limit value c is unique. For this we introduce right averages

$$H(x) = \sum_{j} \mu_{j} f(xh_{j})$$

where  $0 \le \mu_j \le 1$ ,  $\sum \mu_j = 1$ . (Note that a right average of f is in effect a left average of  $\tilde{f}$ , where  $\tilde{f}(x) = f(x^{-1})$ . In particular the results we have established for left averages will hold equally well for right averages.)

Given a left average and a right average of f, say

$$F(x) = \sum \lambda_i f(g_i^{-1}x), \quad H(x) = \sum \mu_j f(xh_j),$$

we can form the joint average

$$J(x) = \sum_{i,j} \lambda_i \mu_j f(g_i^{-1} x h_j).$$

It is easy to see that

$$\inf F \le \inf J \le \sup J \le \sup H$$
,  
 $\sup F \ge \sup J \ge \inf J \ge \inf H$ .

But if now  $H_0 = f, H_1, ...$  is a succession of right averages with  $H_i \to d$  then it follows that

$$c = d$$
.

In particular, any two convergent sequences of successive left averages must tend to the same limit. We can therefore set

$$\mu(f) = c$$
.

Thus  $\mu(f)$  is well-defined; and it is invariant since f and gf have the same set of averages. Finally, if f = 1 then var(f) = 0, and  $f, f, f, \ldots$  converges to 1, so that

$$\mu(1) = 1.$$

The invariant measure on G is unique up to a scalar multiple. In other words, it is unique if we normalise the measure by specifying that

$$\mu(1) = 1$$

(where 1 on the left denotes the constant function 1).

2. Prove that every simple representation of a compact abelian group is 1-dimensional and unitary.

Determine the simple representations of SO(2).

Determine also the simple representations of O(2).

**Answer:** Suppose  $\alpha$  is a simple representation of the compact abelian group G in V.

Suppose  $g \in G$ . Let  $\lambda$  be an eigenvalue of g, and let  $E = E_{\lambda}$  be the corresponding eigenspace. We claim that E is stable under G. For suppose  $h \in G$ . Then

$$e \in E \implies g(he) = h(ge) = \lambda he \implies he \in E.$$

Since  $\alpha$  is simple, it follows that E = V, ie  $gv = \lambda v$  for all v, or  $g = \lambda I$ .

Since this is true for all  $g \in G$ , it follows that every subspace of V is stable under G. Since  $\alpha$  is simple, this implies that dim V = 1, ie  $\alpha$  is of degree 1.

Thus a simple representation of G is a homomorphism  $\alpha: G \to \mathbb{C}^*$ . We must show that

$$|\alpha(g)| = 1$$

for all  $g \in G$ .

If 
$$|\alpha(g)| > 1$$
 then

$$|\alpha(g^n)| = (|g|)^n \to \infty.$$

This is a contradiction, since  $\operatorname{im} \alpha \subset \mathbb{C}^*$  is compact and so bounded. On the other hand, if  $|\alpha(g)| < 1$  then  $|\alpha(g^{-1})| > 1$ . Hence  $|\alpha(g)| = 1$  for all g, ie  $\alpha$  is unitary.

We can identify SO(2) with

$$U(1) = \{ z \in \mathbb{C} : |z| = 1 \}.$$

From above, a representation of U(1) is a homomorphism

$$\alpha: \mathbf{U}(1) \to \mathbf{U}(1).$$

For each  $n \in \mathbb{Z}$  the map

$$E(n): z \to z^n$$

defines such a homomorphism. We claim that every representation of  $\mathbf{U}(1)$  is of this form.

3. Determine the conjugacy classes in SU(2); and prove that this group has just one simple representation of each dimension.

Find the character of the representation D(j) of dimensions 2j + 1 (where  $j = 0, \frac{1}{2}, 1, \frac{3}{2}, \dots$ ).

Determine the representation-ring of SU(2), ie express each product D(i)D(j) as a sum of simple representations D(k).

**Answer:** We know that

(a) if  $U \in SU(2)$  then U has eigenvalues

$$e^{\pm i\theta} \ (\theta \in \mathbb{R}).$$

(b) if  $X, Y \in \mathbf{GL}(n, k)$  then

$$X \sim Y \implies X, Y$$
 have the same eigenvalues.

A fortiori, if  $U \sim V \in \mathbf{SU}(2)$  then U, V have the same eigenvalues.

We shall show that the converse of the last result is also true, that is:  $U \sim V$  in  $\mathbf{SU}(2)$  if and only if U, V have the same eigenvalues  $e^{\pm i\theta}$ , This is equivalent to proving that

$$U \sim U(\theta) = \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix},$$

ie we can find  $V \in SU(2)$  such that

$$V^{-1}UV = U(\theta).$$

To see this, let v be an  $e^{i\theta}$ -eigenvalue of U. Normalise v, so that  $v^*v=1$ ; and let w be a unit vector orthogonal to v, ie  $w^*w=1$ ,  $v^*w=0$ . Then the matrix

$$V = (vw) \in \mathbf{Mat}(2, \mathbb{C})$$

is unitary; and

$$V^{-1}UV = \begin{pmatrix} e^{i\theta} & x \\ 0 & e^{-i\theta} \end{pmatrix}$$

But in a unitary matrix, the squares of the absolute values of each row and column sum to 1. It follows that

$$|e^{i\theta}|^2 + |x|^2 = 1 \implies x = 0,$$

ie

$$V^{-1}UV = U(\theta).$$

We only know that  $V \in \mathbf{U}(2)$ , not that  $V \in \mathbf{SU}(2)$ . However

$$V \in \mathbf{U}(2) \implies |\det V| = 1 \implies \det V = e^{i\phi}.$$

Thus

$$V' = e^{-i\phi/2}V \in \mathbf{SU}(2)$$

and still

$$(V')^{-1}UV = U(\theta).$$

To summarise: Since  $U(-\theta) \sim U(\theta)$  (by interchange of coordinates), we have show that if

$$C(\theta) = \{U \in \mathbf{SU}(2) : U \text{ has eigenvalues } e^{\pm i\theta}\}$$

then the conjugacy classes in SU(2) are

$$C(\theta) \quad (0 \le \theta \le \pi).$$

Now suppose  $m \in \mathbb{N}$ , Let V(m) denote the space of homogeneous polynomials P(z,w) in z,w. Thus V(m) is a vector space over  $\mathbb{C}$  of dimension m+1, with basis  $z^m, z^{m-1}w, \ldots, w^m$ .

Suppose  $U \in SU(2)$ . Then U acts on z, w by

$$\begin{pmatrix} z \\ w \end{pmatrix} \mapsto \begin{pmatrix} z' \\ w' \end{pmatrix} = U \begin{pmatrix} z \\ w \end{pmatrix}.$$

This action in turn defines an action of SU(2) on V(m):

$$P(z, w) \mapsto P(z', w').$$

We claim that the corresponding representation of SU(2) — which we denote by  $D_{m/2}$  — is simple, and that these are the only simple (finite-dimensional) representations of SU(2) over  $\mathbb{C}$ .

To prove this, let

$$U(1) \subset SU(2)$$

be the subgroup formed by the diagonal matrices  $U(\theta)$ . The action of SU(2) on z, w restricts to the action

$$(z,w) \mapsto (e^{i\theta}z, e^{-i\theta}w)$$

of U(1). Thus in the action of U(1) on V(m),

$$z^{m-r}w^r \mapsto e^{(m-2r)i\theta}z^{m-r}w^r,$$

It follows that the restriction of  $D_{m/1}$  to U(1) is the representation

$$D_{m/2}|\mathbf{U}(1) = E(m) + E(m-2) + \dots + E(-m)$$

where E(m) is the representation

$$e^{i\theta} \mapsto e^{mi\theta}$$

of U(1).

In particular, the character of  $D_{m/2}$  is given by

$$\chi_{m/2}(U) = e^{mi\theta} + e^{(m-2}i\theta + \dots + e^{-mi\theta}$$

if U has eigenvalues  $e^{\pm i\theta}$ .

Now suppose  $D_{m/2}$  is not simple, say

$$D_{m/2} = \alpha + \beta$$
.

(We know that  $D_{m/2}$  is semisimple, since SU(2) is compact.) Let a corresponding split of the representation space be

$$V(m) = W_1 \oplus W_2.$$

Since the simple parts of  $D_{m/2}|\mathbf{U}(1)$  are distinct, the expression of V(m) as a direct sum of  $\mathbf{U}(1)$ -spaces,

$$V(m) = \langle z^m \rangle \oplus \langle z^{m-1} w \rangle \oplus \cdots \oplus \langle w^m \rangle$$

is unique. It follows that  $W_1$  must be the direct sum of some of these spaces, and  $W_2$  the direct sum of the others. In particular  $z^m \in W_1$  or  $z^n \in W_2$ , say  $z^m \in W_1$ . Let

$$U = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \in \mathbf{SU}(2).$$

Then

$$\begin{pmatrix} z \\ w \end{pmatrix} \mapsto \frac{1}{\sqrt{2}} \begin{pmatrix} z+w \\ -z+w \end{pmatrix}$$

under U. Hence

$$z^m \mapsto 2^{-m/2}(z+w)^m.$$

Since this contains non-zero components in each subspace  $\langle z^{m-r}w^r \rangle$ , it follows that

$$W_1 = V(m),$$

ie the representation  $D_{m/2}$  of SU(2) in V(m) is simple.

To see that every simple (finite-dimensional) representation of SU(2) is of this form, suppose  $\alpha$  is such a representation. Consider its restriction to U(1). Suppose

$$\alpha | \mathbf{U}(1) = e_r E(r) + e_{r-1} E(r-1) + \dots + e_{-r} E(-r) \quad (e_r, e_{r-1}, \dots, e_{-r} \in \mathbb{N}).$$

Then  $\alpha$  has character

$$\chi(U) = \chi(\theta) = e_r e^{ri\theta} + e_{r-1} e^{(r-1)i\theta} + \dots + e_{-r} e^{-ri\theta}$$

if U has eigenvalues  $e^{\pm i\theta}$ .

Since  $U(-\theta) \sim U(\theta)$  it follows that

$$\chi(-\theta) = \chi(\theta),$$

and so

$$e_{-i} = e_i,$$

ie

$$\chi(\theta) = e_r(e^{ri\theta} + e^{-ri\theta}) + e_{r-1}(e^{(r-1)i\theta} + e^{-(r-1)i\theta}) + \cdots$$

It is easy to see that this is expressible as a sum of the  $\chi_j(\theta)$  with integer (possibly negative) coefficients:

$$\chi(\theta) = a_0 \chi_0(\theta) + a_{1/2} \chi_{1/2}(\theta) + \dots + a_s \chi_s(\theta) \quad (a_0, a_{1/2}, \dots, a_s \in \mathbb{Z}).$$

Using the intertwining number,

$$I(\alpha, \alpha) = a_0^2 + a_{1/2}^2 + \dots + a_s^2$$

(since  $I(D_i, D_k) = 0$ ). Since  $\alpha$  is simple,

$$I(\alpha, \alpha) = 1.$$

It follows that one of the coefficients  $a_i$  is  $\pm 1$  and the rest are 0, ie

$$\chi(\theta) = \pm \chi_i(\theta)$$

for some half-integer j. But

$$\chi(\theta) = -\chi_j(\theta) \implies I(\alpha, D_j) = -I(D_j, D_j) = -1,$$

which is impossible. Hence

$$\chi(\theta) = \chi_i(\theta),$$

and so (since a representation is determined up to equivalence by its character)

$$\alpha = D_j$$
.

Finally, we show that

$$D_j D_k = D_{j+k} + D_{j+k-1} + \dots + D_{|j-k|}.$$

It is sufficient to prove the corresponding result for the characters

$$\chi_j(\theta)\chi_k(\theta) = \chi_{j+k}(\theta) + \chi_{j+k-1}(\theta) + \dots + \chi_{|j-k|}(\theta).$$

We may suppose that  $j \geq k$ . We prove the result by induction on k.

If k = 0 the result is trivial, since  $\chi_0(\theta) = 1$ . If k = 1/2 then

$$\chi_{j}(\theta)\chi_{1/2}(\theta) = \left(e^{2ji\theta} + e^{2(j-1)i\theta} + e^{-2ji\theta}\right) \left(e^{i\theta} + e^{-i\theta}\right)$$

$$= \left(e^{(2j+1)i\theta} + e^{-(2j-1)i\theta}\right) + \left(e^{(2j-1)i\theta} + e^{-(2j+1)i\theta}\right)$$

$$= \chi_{j+1/2}(\theta) + \chi_{j-1/2}(\theta),$$

as required.

Suppose  $k \geq 1$ . Then

$$\chi_k(\theta) = \chi_{k-1}(\theta) + (e^{ki\theta} + e^{-ki\theta}).$$

Thus applying our inductive hypothesis,

$$\chi_j(\theta)\chi_k(\theta) = \chi_{j+k-1}(\theta) + \dots + \chi_{j-k+1} + \chi_j(\theta)(e^{ki\theta} + e^{-ki\theta}).$$

But

$$\chi_j(\theta)(e^{ki\theta} + e^{-ki\theta}) = \left(e^{2ji\theta} + e^{2(j-1)i\theta} + e^{-2ji\theta}\right) \left(e^{ki\theta} + e^{-ki\theta}\right)$$
$$= \chi_{j+k}(\theta) + \chi_j - k(\theta),$$

giving the required result

$$\chi_j(\theta)\chi_k(\theta) = \chi_{j+k-1}(\theta) + \dots + \chi_{j-k+1} + \chi_{j+k}(\theta) + \chi_{j-k}(\theta)$$
$$= \chi_{j+k}(\theta) + \dots + \chi_{j-k}.$$

## 4. Show that there exists a surjective homomorphism

$$\Theta: \mathbf{SU}(2) \to \mathbf{SO}(3)$$

with finite kernel.

Hence or otherwise determine all simple representations of SO(3).

Determine also all simple representations of O(3).

**Answer:** The set of skew-hermitian  $2 \times 2$  matrices

$$S = \begin{pmatrix} ia & -b + ic \\ b + ic & id \end{pmatrix} \qquad (a, b, c, d \in \mathbb{R})$$

forms a 4-dimensional real vector space U. The group  $\mathbf{SU}(2)$  acts on this space by

$$(U,S) \mapsto U^{-1}SU = U^*SU.$$

since

$$(U^*SU)^* = U^*S^*U = -U^*SU.$$

The 3-dimensional subspace  $W \subset U$  formed by trace-free skew-hermitian matrices

$$T = \begin{pmatrix} ix & -y + iz \\ y + iz & -ix \end{pmatrix} \qquad (x, y, z \in \mathbb{R})$$

is stable under SU(2) since

$$\operatorname{tr}(U^*TU) = \operatorname{tr}(U^{-1}TU) = \operatorname{tr} T = 0.$$

Thus W carries a representation of SU(2) of degree 3, corresponding to a homomorphism

$$\Theta: \mathbf{SU}(2) \to \mathbf{GL}(3, \mathbb{R}).$$

Moreover, this homomorphism preserves the positive-definite quadratic form

$$\det T = x^2 + y^2 + z^2$$

on W since

$$\det(U^*TU) = \det(U^{-1}TU) = \det T.$$

Hence

$$im \Theta \subset \mathbf{O}(3)$$
.

Finally,  $SU(2) \cong S^3$  is connected; and so therefore is its image. But SO(3) is an open subgroup of O(3). Hence

$$im \Theta \subset SO(3)$$
.

Thus our homomorphism takes the form

$$\Theta: \mathbf{SU}(2) \to \mathbf{SO}(3).$$

It remains to show that  $\Theta$  has a finite kernel, and is surjective.

If

$$U \in \ker \Theta$$

then

$$U^{-1}TU = T$$

for all  $T \in W$ . Each  $S \in U$  can be expressed in the form

$$S = T + \rho I$$

where  $T \in W$  and  $\rho = \operatorname{tr} S/2$ . It follows that

$$U^{-1}SU = S$$

for all skew-hermitian  $S \in U$ .

Hence

$$U^{-1}HU = H$$

for all hermitian H, since H is hermitian if and only if S=iH is skew-hermitian.

It follows from this that

$$U^{-1}XU = X$$

for all  $X \in \mathbf{Mat}(2,\mathbb{C})$ , since every X is expressible in the form

$$X = H + S$$

with  $H = (X + X^*)/2$  hermitian and  $S = (X - X^*)/2$  skew-hermitian. But it is a simple matter to see that the only such U are  $U = \pm I$ . Thus

$$\ker\Theta=\{\pm I\}.$$

To see that  $\Theta$  is surjective, we note that if

$$U(\theta) = \begin{pmatrix} e^{i\theta} & 0\\ 0 & e^{-i\theta} \end{pmatrix}$$

then

$$U(\theta)^{-1} \begin{pmatrix} ix & -y+iz \\ y+iz & -ix \end{pmatrix} U(\theta) = \begin{pmatrix} ix & e^{-2i\theta}(-y+iz) \\ e^{2i\theta}(y+iz) & -ix \end{pmatrix},$$

$$\Theta U(\theta) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos 2\theta & -\sin 2\theta \\ 0 & \sin 2\theta & \cos 2\theta \end{pmatrix} = R(Ox, 2\theta),$$

rotation about Ox through angle  $2\theta$ . In particular, im  $\Theta$  contains all rotations about Ox.

Now let

$$U = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}.$$

Then  $U \in SU(2)$  and

$$U^{-1}\begin{pmatrix} ix & -y+iz \\ y+iz & -ix \end{pmatrix}U = \begin{pmatrix} iz & -y-ix \\ y-ix & -iz \end{pmatrix}.$$

Thus

$$\alpha(U) = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix} = R(Oy, \pi/2).$$

Writing  $P = R(Oy, \pi/2)$ ,

$$P^{-1}R(Ox,\theta)P = R(Oz,\theta).$$

Thus im  $\Theta$  contains all rotations about Oz as well as Ox. But is is easy to see that every rotation  $R \in SO(3)$  is expressible as a product of rotations about Ox and Oz. Hence

$$im \Theta = SO(3),$$

ie  $\Theta$  is surjective.

Thus

$$\mathbf{SO}(3) = \mathbf{SU}(2)/\{\pm i\}.$$

It follows that the representations of SO(3) are just the representations  $\alpha$  of SO(2) such that

$$\alpha(-I) = I$$
.

In particular, the simple representations of SO(3) are those simple representations  $D_j$  of SU(2) such that  $D_j(-I) = I$ . But  $D_j$  is defined by the action of SU(2) on the polynomials

$$P(z, w) = c_0 z^{2j} + c_1 z^{2j-1} w + \dots + c_{2j} w^{2j}.$$

It is clear that

$$P(-z, -w) = P(z, w)$$

for all P of degree 2j if and only if 2j is even, ie j is an integer.

Thus the simple representations of SO(3) are  $D_0, D_1, D_2, \ldots$  of degrees  $1, 3, 5, \ldots$ 

Since

$$\mathbf{O}(3) = \mathbf{SO}(3) \times C_2,$$

where  $C_2 = \{\pm I\}$ , the simple representations of  $\mathbf{O}(3)$  are of the form  $\alpha \times \beta$ , where  $\alpha$  is a simple representation of  $\mathbf{SO}(3)$ , and  $\beta$  is a simple representation of  $\mathbf{C}_2$ . Thus the simple representations of  $\mathbf{O}(3)$  are  $D_j \times 1$  and  $D_j \times \epsilon$ , where  $j \in \mathbb{N}$  and  $\epsilon$  is the representation  $-I \to -1$  of  $C_2$ .

5. Explain the division of simple representations of a finite or compact group G over  $\mathbb{C}$  into real, essentially complex and quaternionic. Give an example of each (justifying your answers).

Show that if  $\alpha$  is a simple representation with character  $\chi$  then the value of

$$\int_G \chi(g^2) \ dg$$

determines which of these three types  $\alpha$  falls into.

**Answer:** Suppose  $\alpha$  is a simple representation of G over  $\mathbb{C}$ . Then  $\alpha$  is said to be real if

$$\alpha = \beta_{\mathbb{C}}$$

for some representation of G over  $\mathbb{R}$ . If this is so then the character

$$\chi_{\alpha}(q) = \chi_{\beta}(q)$$

is real. We say that  $\alpha$  is quaternionic if its character is real, but it is not real. Finally, we say that  $\alpha$  is essentially complex if its character is not real.

The trivial character 1 of any group is real, since it is the complexification of the trivial character over  $\mathbb{R}$ .

The 1-dimensional character  $\theta$  of the cyclic group  $C_3 = \langle g \rangle$  given by

$$\theta: q \mapsto \omega = e^{2\pi/3}$$

is essentially complex, since its character  $\theta$  is not real.

Consider the quaternion group

$$Q_8 = \{\pm 1, \pm i, \pm j, \pm k\}.$$

We can regard the quaternions  $\mathbb{H}$  as a 2-dimensional vector space over  $\mathbb{C} = \langle 1, i \rangle$ . The action of  $Q_8$  on  $\mathbb{H}$  by multiplication on the left defines a 2-dimensional representation  $\alpha$  of  $D_8$ . We assert that this is a simple quaternionic representation.

It is certainly simple, since otherwise  $\mathbb{H}$  would have a 1-dimensional subspace  $\langle q \rangle$  stable under  $D_8$ , and therefore under  $\mathbb{H}$ , since  $D_8$  spans  $\mathbb{H}$ . But that is impossible since

$$x = (xq^{-1})q$$

for any  $x \in \mathbb{H}$ . The simple representations of  $D_4$  must have dimensions 1, 1, 1, 1, 2 (since  $\sum \dim_i^2 = 8$ ). It follows that

$$\alpha^* = \alpha$$

since there is only 1 2-dimensional simple representation. Hence  $\chi_{\alpha}$  is real.

It remains to show that  $\alpha$  is not real. Consider the 4-dimensional representation  $\beta$  of  $D_8$  over  $\mathbb{R}$ , defined by the same action of  $D_4$  on  $\mathbb{H}$ . This is easily seen to be simple, by the argument above. It follows that  $\beta_{\mathbb{C}}$  is either simple, or splits into 2 simple representations over  $\mathbb{C}$  of dimension 2. The only possibility is that

$$\beta_{\mathbb{C}} = 2\alpha$$
.

Now if  $\alpha$  were real, say

$$\alpha = \gamma_{\mathbb{C}}$$

we would deduce that  $\beta = 2\gamma$  which is impossible, since  $\beta$  is simple.

Now suppose  $\alpha$  is a simple representation of G in V. Then  $(\alpha^*)^2$  is the representation arising from the action of G on the space of bilinear forms on V.

But

$$\alpha^* = \alpha \iff \chi_\alpha \text{ is real.}$$

Thus

$$I(1,(\alpha^*)^2) = I(\alpha,\alpha^*) = \begin{cases} 1 & \text{if } \alpha \text{ is real or quaternionic} \\ 0 & \text{if } \alpha \text{ is essentially complex} \end{cases}.$$

In other words, there is just 1 invariant bilinear form (up to a scalar multiple) if  $\alpha$  is real or quaternionic, and no such form if  $\alpha$  is essentially complex.

Now the space of bilinear forms splits into the direct sum of symmetric (or quadratic) and skew-symmetric forms, since each bilinear form B(u, v) can be expressed as

$$B(u,v) = \frac{1}{2} (B(u,v) + B(v,u)) + \frac{1}{2} (B(u,v) - B(v,u)),$$

where the first form is symmetric and the second skew-symmetric.

$$(\alpha^*)^2 = \phi + \psi,$$

where  $\phi$  is the representation of G in the space of symmetric forms, and  $\psi$  the representation in the space of skew-symmetric forms.

If  $\alpha$  is essentially complex, there is no invariant symmetric or skew-symmetric form. But if  $\alpha$  is real or quaternionic, there must be just 1 invariant form, either symmetric or skew-symmetric. We shall see that in fact there is an invariant symmetric form if and only if  $\alpha$  is real.

Certainly if  $\alpha$  is real, say  $\alpha = \beta_{\mathbb{C}}$ , where  $\beta$  is a representation in the real vector space U, then we know that there is an invariant positive-definite form on U, and this will give an invariant quadratic form on  $V = U_{\mathbb{C}}$ .

Conversely, suppose  $\alpha$  is a quaternionic simple representation on V. Then  $\beta = \alpha_{\mathbb{R}}$  is simple. For

$$(\alpha_{\mathbb{R}})_{\mathbb{C}} = \alpha + \alpha^*$$

for any representation  $\alpha$  over  $\mathbb{C}$ . Thus if  $\beta = \gamma + \gamma'$  then (with  $\alpha$  quaternionic)

$$2\alpha = \gamma_{\mathbb{C}} + \gamma_{\mathbb{C}}',$$

and it will follow that

$$\alpha = \gamma_{\mathbb{C}} = \gamma'_{\mathbb{C}},$$

so that  $\alpha$  is real.

Since  $\beta$  is simple, there is a unique invariant quadratic form P on  $V_{\mathbb{R}}$ , and this form is positive-definite. But if there were an invariant quadratic form Q on V this would give an invariant quadratic form on  $V_{\mathbb{R}}$ , which would not be positive-definite, since we would have

$$Q(iu, iu) = -Q(u).$$

Thus if  $\alpha$  is quaternionic, then there is no invariant quadratic form on V, and therefore there is an invariant skew-symmetric form.

It follows that we can determine which class  $\alpha$  falls into by computing

$$I(1,\phi)$$
 and  $I(1,\psi)$ .

To this end we compute the characters of  $\phi$  and  $\psi$ .

Suppose  $g \in G$ . Then we can diagonalise g, ie we can find a basis  $e_1, \ldots, e_n$  of V consisting of eivenvectors, say

$$qe_i = \lambda_i e_i$$
.

The space of quadratic forms is spanned by the n(n+1)/2 forms

$$x_i x_j \quad (i \le j),$$

where  $x_1, \ldots, x_n$  are the coordinates with respect to the basis  $e_1, \ldots, e_n$ . It follows that

$$\chi_{\phi}(g) = \sum_{i < j} \lambda_i^2 + \sum_{i < j} \lambda_i \lambda_j.$$

Now

$$\chi_{\alpha}(g) = \sum \lambda_i, \ \chi_{\alpha}(g^2) = \sum \lambda_i^2.$$

It follows that

$$\chi_p hi(g) = \frac{1}{2} \left( \chi_\alpha(g)^2 + \chi_a lpha(g^2) \right).$$

We deduce from this that

$$I(1,\phi) = \frac{1}{2||G||} \sum_{g \in G} (\chi_{\alpha}(g)^2 + \chi_{\alpha}(g^2)).$$

Since

$$I(1,\phi) + I(1,\psi) = I(1,(\alpha^*)^2)$$

$$= \frac{1}{\|G\|} \sum_{g} \chi_{\alpha}(g^{-1})^2$$

$$= \frac{1}{\|G\|} \sum_{g} \chi_{\alpha}(g)^2,$$

it follows that

$$I(1, \psi) = \frac{1}{2||G||} \sum_{g \in G} (\chi_{\alpha}(g)^2 - \chi_{\alpha}(g^2)).$$

Putting all this together, we conclude that

$$\begin{split} \frac{1}{\|G\|} \sum_{g \in G} \chi_{\alpha}(g^2) &= I(1, \phi) - I(1, \psi) \\ &= \begin{cases} 1 & \text{if } \alpha \text{ is real,} \\ -1 & \text{if } \alpha \text{ is quaternionic,} \\ 0 & \text{if } \alpha \text{ is essentially complex.} \end{cases} \end{split}$$