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Some Examples on Weak Symmetries

B.B. Chaturvedi¹ and Pankaj Pandey²

^{1,2}Department of Pure and Applied Mathematics Guru Ghasidas Vishwavidyalaya Bilaspur (C.G.)- 495009, India
¹E-mail: brajbhushan25@gmail.com
²E-mail: pankaj.anvarat@gmail.com

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Abstract

In this paper some examples of weakly symmetric manifold, weakly Ricci symmetric manifold, conformally flat weakly symmetric manifold and weakly projective symmetric manifold are constructed.

Keywords: Conformally flat manifold, Kähler manifold, projectively flat manifold, weakly symmetric manifold, weakly Ricci symmetric manifold.

1 Introduction

The idea of weakly symmetric and weakly Ricci symmetric manifolds is introduced by L. Tamassy and T. Q. Binh [1]. After then, these ideas are extended by M. Prvanovic [6], U. C. De and S. Bandyopdhyay [2] and also by the other differential geometers.

A Riemannian manifold is said to be weakly symmetric if the curvature tensor R of the manifold satisfies

$$(\nabla_X R)(Y, Z, U, V) = A(X)R(Y, Z, U, V) + B(Y)R(X, Z, U, V) + C(Z)R(Y, X, U, V) + D(U)R(Y, Z, X, V)$$
(1)
+ E(V)R(Y, Z, U, X),

and if the Ricci tensor S of the manifold satisfies

$$(\nabla_X S)(Y, Z) = A(X)S(Y, Z) + B(Y)S(X, Z) + C(Z)S(Y, X),$$
(2)

then manifold is called weakly Ricci symmetric manifold. A, B, C, D, E are simultaneously non-vanishing 1-forms and X, Y, Z, U, V are vector fields.

In 1995, Prvanovic [6] proved that if the manifold be weakly symmetric satisfying equation (1) then B = C = D = E.

In this paper we have assumed that $B = C = D = E = \omega$, such that $g(X, \rho) = \omega(X)$, and therefore, the equations (1) and (2) can be written as

$$(\nabla_X R)(Y, Z, U, V) = A(X)R(Y, Z, U, V) + \omega(Y)R(X, Z, U, V) + \omega(Z)R(Y, X, U, V) + \omega(U)R(Y, Z, X, V)$$
(3)
+ $\omega(V)R(Y, Z, U, X),$

and

$$(\nabla_X S)(Y,Z) = A(X)S(Y,Z) + \omega(Y)S(X,Z) + \omega(Z)S(Y,X), \qquad (4)$$

where $g(X, \alpha) = A(X)$.

2 Example of Weakly Symmetric Manifold

Example 2.1. Let g be a metric in manifold \mathbb{R}^n defined by

$$ds^{2} = \varphi(dx^{1})^{2} + K_{\alpha\beta}dx^{\alpha}dx^{\beta} + 2dx^{1}dx^{n}, \qquad (5)$$

where $[K_{\alpha\beta}]$ is a non-singular symmetric matrix with entries as constants such that α, β varies from 2 to (n-1) and φ is a function of x^1, x^2, \dots, x^{n-1} . Roter [7] found the non-zero components of the Christoffel symbols Γ_{jk}^i , curvature tensor R_{hijk} and the Ricci tensor R_{ij} as follows

$$\Gamma_{11}^{\beta} = -\frac{1}{2} K^{\alpha\beta} \varphi_{\cdot\alpha}, \quad \Gamma_{11}^{n} = \frac{1}{2} \varphi_{\cdot1}, \quad \Gamma_{1\alpha}^{n} = \frac{1}{2} \varphi_{\cdot\alpha}, \tag{6}$$

and

$$R_{1\alpha\beta1} = \frac{1}{2}\varphi_{\cdot\alpha\beta}, \qquad \qquad R_{11} = \frac{1}{2}K^{\alpha\beta}\varphi_{\cdot\alpha\beta}, \qquad (7)$$

where "." denotes the partial differentiation and $[K^{\alpha\beta}]$ is the inverse matrix of $[K_{\alpha\beta}]$. If we take $K_{\alpha\beta}$ as $\delta_{\alpha\beta}$ (= $\{ \begin{smallmatrix} 1 & if\alpha=\beta \\ 0, & oherwise \end{smallmatrix} \}$) and $\varphi = K_{\alpha\beta}x^{\alpha}x^{\beta}f(x^{1})$ then φ becomes

$$\varphi = \sum_{\alpha=2}^{n-1} (x^{\alpha})^2 f(x^1),$$
(8)

where f is an arbitrary non-zero function of x^1 . From (8), we easily get

$$\varphi_{\cdot\alpha\alpha} = 2f(x^1), \quad \varphi_{\cdot\alpha\beta} = 0, \alpha \neq \beta.$$
 (9)

Equations (7) and (9) imply that the non-zero components of curvature tensor R_{hijk} and their derivatives $R_{hijk,l}$ respectively are

$$R_{1\alpha\alpha1} = f(x^1),\tag{10}$$

and

$$R_{1\alpha\alpha1.1} = \frac{d}{dx^1} f(x^1).$$
 (11)

Now, from equation (3), the condition of weakly symmetric manifold for the non-zero components of the curvature tensor R_{hijk} becomes

$$R_{1\alpha\alpha1.1} = A_1 R_{1\alpha\alpha1} + \omega_1 R_{1\alpha\alpha1} + \omega_\alpha R_{1\alpha\alpha1} + \omega_\alpha R_{1\alpha\alpha1} + \omega_1 R_{1\alpha\alpha1}.$$
(12)

If we take

$$A_i = \begin{cases} \phi(x^1), & i=1\\ 0, & otherwise, \end{cases}$$
(13)

and

$$\omega_{i} = \begin{cases} \frac{1}{2} \left[\frac{\frac{d}{dx^{1}} f(x^{1})}{f(x^{1})} - \phi(x^{1}) \right], & i = 1 \\ 0, & otherwise, \end{cases}$$
(14)

then by the use of (14), equation (12) reduces to

$$R_{1\alpha\alpha1.1} = (A_1 + 2\omega_1)R_{1\alpha\alpha1}.$$
 (15)

Now, from (10), (13) and (14), we easily get the right hand side of (15)

$$(A_1 + 2\omega_1)R_{1\alpha\alpha 1} = \frac{d}{dx^1}f(x^1).$$
 (16)

Hence, from (11) and (16), we can say that this is an example of weakly symmetric manifold.

3 Example of Weakly Ricci Symmetric Manifold

Example 3.1. Since equation (7) implies that the non-zero component of Ricci tensor R_{ij} and its derivative $R_{ij,l}$ are

$$R_{11} = (n-2)f(x^1), (17)$$

and

$$R_{11.1} = (n-2)\frac{d}{dx^1}f(x^1).$$
(18)

Therefore, from equation (4), the condition of weakly Ricci symmetric manifold for non-zero component of Ricci tensor R_{ij} becomes

$$R_{11.1} = A_1 R_{11} + \omega_1 R_{11} + \omega_1 R_{11}.$$
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or

$$R_{11.1} = (A_1 + 2\omega_1)R_{11}.$$
(20)

From (13), (14) and (17), the right hand side of the equation (20) becomes

$$(A_1 + 2\omega_1)R_{11} = (n-2)\frac{d}{dx^1}f(x^1).$$
(21)

Therefore, from (18) and (21), we can say that this is an example of weakly Ricci symmetric manifold.

4 Example of Conformally Flat Weakly Symmetric Manifold

Example 4.1. We know that the Weyl conformal curvature tensor C on an n-dimensional manifold is defined as

$$C(X, Y, Z, T) = R(X, Y, Z, T) - \frac{1}{(n-2)} [S(Y,Z)g(X,T) - S(X,Z)g(Y,T) + S(X,T)g(Y,Z) - S(Y,T)g(X,Z)]$$
(22)
+ $\frac{r}{(n-1)(n-2)} [g(Y,Z)g(X,T) - g(X,Z)g(Y,T)].$

Now, from (5) we have $g_{ni} = g_{in} = 0$ for $i \neq 1$ but then $g^{11} = 0$ and hence the scalar curvature tensor $r = g^{ij} R_{ij} = g^{11} R_{11} = 0$. Therefore, equation (22) gives the non-zero component of the conformal curvature tensor C_{hijk} as follows

$$C_{1\alpha\alpha1} = R_{1\alpha\alpha1} - \frac{1}{(n-2)}g_{\alpha\alpha}R_{11}.$$
 (23)

Using (10) and (17) in (23) and taking $g_{\alpha\alpha} = 1$, we get

$$C_{1\alpha\alpha 1} = 0. \tag{24}$$

Hence, from equation (24) and example (2.1), we can say that this is an example of conformally flat weakly symmetric manifold

5 Example of Weakly Projective Symmetric Manifold

Example 5.1. It is well known that the projective curvature tensor P on an n-dimensional Riemannian manifold is defined by

$$P(X, Y, Z, U) = R(X, Y, Z, U) - \frac{1}{(n-1)} [S(Y, Z)g(X, U) - S(X, Z)g(Y, U)].$$
(25)

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Therefore, the non-zero component of the projective curvature tensor P_{hijk} becomes

$$P_{1\alpha\alpha1} = R_{1\alpha\alpha1} - \frac{1}{(n-1)}g_{\alpha\alpha}R_{11}.$$
 (26)

Using (10) and (17) in (26), we get

$$P_{1\alpha\alpha1} = \frac{1}{(n-1)}f(x^1),$$
(27)

and the derivative of projective curvature tensor becomes

$$P_{1\alpha\alpha1.1} = \frac{1}{(n-1)} \frac{d}{dx^1} f(x^1).$$
(28)

Now, the condition of weakly projective symmetric manifold, given by

$$(\nabla_X P)(Y, Z, U, V) = A(X)P(Y, Z, U, V) + B(Y)P(X, Z, U, V) + C(Z)P(Y, X, U, V) + D(U)P(Y, Z, X, V) + E(V)P(Y, Z, U, X),$$
(29)

reduces to

$$P_{1\alpha\alpha1.1} = A_1 P_{1\alpha\alpha1} + \omega_1 P_{1\alpha\alpha1} + \omega_\alpha P_{1\alpha\alpha1} + \omega_\alpha P_{1\alpha\alpha1} + \omega_1 P_{1\alpha\alpha1}, \qquad (30)$$

for non-zero component of projective curvature tensor P_{hijk} . From (14), above equation can be written as

$$P_{1\alpha\alpha 1.1} = (A_1 + 2\omega_1)P_{1\alpha\alpha 1}.$$
 (31)

Using (27) in (31), we have

$$P_{1\alpha\alpha1.1} = \frac{1}{(n-1)} (A_1 + 2\omega_1) f(x^1).$$
(32)

From (10) and (32), we can write

$$P_{1\alpha\alpha1.1} = \frac{1}{(n-1)} (A_1 + 2\omega_1) R_{1\alpha\alpha1}.$$
(33)

Using (16) in (33), we get

$$P_{1\alpha\alpha1.1} = \frac{1}{(n-1)} \frac{d}{dx^1} f(x^1).$$
(34)

Hence, from (28) and (34), we can say that this is an example of weakly projectively symmetric manifold.

6 Conclusion

From examples (2.1), (3.1), (4.1) and (5.1), it is clear that the Riemannian manifold \mathbb{R}^n with metric (5) defined by W. Roter [7] verify the properties of weakly symmetric manifold, weakly Ricci symmetric manifold, conformally flat weakly symmetric manifold and weakly projective symmetric manifold respectively.

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