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# On Coincidence and Common Fixed Point for Nonlinear Generalized Hybrid Contractions

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#### Abstract

The purpose of this paper is to prove some coincidence point theorems for non-linear hybrid contraction involving two pairs of single-valued and multivalued mappings on complete metric space.

**Keywords:** Coincidentally commuting mapping, Hybrid Contraction, Multi-Valued Mappings, Metrical fixed point.

# 1 Introduction

Nadler [8] was the first mathematician who obtained a set-valued version of Banach contraction principle. Since then there is multitude of metrical fixed point theorem for set valued mappings which are indeed extension of various singled-valued metrical fixed point theorems. The work of Asina-Massa-Rous [1], Circ [3], Bos and Mukherjee [2], Reich [11] [12], Kaulkud and Pai [7] are special mention in this context. Hausdorff metric is ordinary distance functions between points and set.

# 2 Preliminaries and Notations

A nonempty subset S of a metric space (X, d) is said to be proximinal if for each  $x \in X$  there exists a point  $y \in S$  such that d(x, y) = d(x, S). It is well known that every compact set is proximinal. We denote  $CB(X) = \{S : S \text{ is closed bounded subset of } X\},\\PB(X) = \{S : S \text{ is proximinal bounded subet of } X\},\\C(X) = \{S : S \text{ is compact subset of } X\}$ 

Since every proximinal set is closed, we have  $C(X) \subseteq PB(X) \subseteq CB(X)$ . Kaneko and Sessa [6]extended the notion of weak commutativity for singlevalued mappings to the settings of single-valued and multi-valued mappings whereas for compatible mappings the same is done by Singh et al [13]. Now we need to recall relevant definitions.

**Definition 2.1** [6] The mappings T and F are said to be weakly commuting it for all  $x \in X$ ,  $fTx \in CB(X)$  and  $H(Tfx, fTx) \leq d(fx, Tx)$ , where H is the Hausdorff metric defined on CB(X).

The Hausdorff H on CB(X) induced by the metric d is defined as

 $H(A,B) = max \{ sup_{x \in A} \ d(x, B), \ sup_{y \in B} \ d(y,A) \}$ 

for all  $A, B \in CB(X)$ , where  $d(x, A) = \inf_{y \in A} d(x, y)$ .

It is well known that (CB(X), H) is a metric space, and if a metric space (X, d) is complete, then so is (CB(X), H).

**Definition 2.2** [6] The mappings T and F are said to compatible if and only if  $fTx \in CB(X)$  for  $x \in X$  and  $H(Tfx_n, fTx_n) \to 0$  as  $n \to \infty$ , whenever  $\{x_n\} \subset X$  such that  $Tx_n \to M \in CB(X)$  and  $fx_n \to t \in M$  as  $n \to \infty$ .

Kaneko and Sessa [6] has furnish an example which shows that compatibility does not implies weak commutativity. Pathak [9] introduced the concept of weak compatible mappings for a hybrid pair of single-valued and multi-valued mappings as follows:

**Definition 2.3** [9] The mappings f and T are said to be f-weak compatible if  $fT(X) \in CB(X)$  for all  $x \in X$  and the following limits exists and satisfy the relevant inequality.

 $\lim_{n \to \infty} H(fTx_n, Tfx_n) \le \lim_{n \to \infty} H(Tfx_n, Tx_n),$  $\lim_{n \to \infty} d(fTx_n, fx_n) \le \lim_{n \to \infty} H(Tfx_n, Tx_n),$ 

where  $\{x_n\}$  is a sequence in X such that  $f(x_n) \to t$  and  $Tx_n \to M \in CB(X)$  as  $n \to \infty$ .

Compatible pairs are weakly compatible but not conversely. Examples supporting this fact can be found in Pathak [9]

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**Definition 2.4** [4] Let K be a non empty subsets of a metric space (X, d)where  $F : K \to CB(X)$  and  $T : K \to X$ . Then the pair (F,T) is said to weakly commuting if for every x, y in K such that  $x \in Fy$  and  $Ty \in K$ , imply that  $d(Tx, FTy) \in d(Ty, Fy)$ .

**Definition 2.5** [4] Let (X, d) be a metric space. A mappings  $T : X \to CB(X)$  is said to be continuous at  $x_0 \in X$  if for any  $\in > 0$  there exists a  $\delta > 0$  such that  $H(Tx, Tx_0) < \in$  whenever  $d(x, x_0) < \delta$ . If T is continuous at every point of X, then we say that T is continuous on X.

**Definition 2.6** [5] A pair of mappings (S,T) is said to be coincidently commuting (resp. weakly compatible) if they commute at coincidence points.

**Lemma 2.7** [8] Let  $A, B \in CB(X)$  and k > 1. Then for each  $a \in A$ , there exists a point  $b \in B$  such that  $d(a, b) \leq kH(A, B)$ .

### 3 Main Result

In this section we give some coincidence and fixed points theorems for nonlinear hybrid generalized contractions using the notion of weak compatible mappings introduce by Pathak et al [10].

**Theorem 3.1** Let S, T be two multi-valued continuous mappings of a complete metric space (X, d) in CB(X), whereas I, J be two continuous self mappings of X. Suppose that (S, I) and (T, J) are compatible mappings with  $S(X) \subset J(X)$  and  $T(X) \subset I(X)$  satisfying

$$H(Sx, Ty) \le h[aL(Ix, Jy) + (1 - a)N(Ix, Jy)]$$
(3.1.1),

for all x, y in X,  $(0 \le h < 1, 0 \le a \le 1)$ , where

$$L(Ix, Jy) = max\{d(Ix, Jy), d(Ix, Sx), d(Jy, Ty), \frac{1}{2}[d(Ix, Ty) + d(Jy, Sx)]\}$$
 and

$$N(Ix, Jy) = [max\{d^{2}(Ix, Jy), d(Ix, Sx)d(Jy, Ty), d(Ix, Ty)d(Jy, Sx), \frac{1}{2}[d(Ix, Sx)d(Jy, Sx)], \frac{1}{2}[d(Ix, Ty)d(Jy, Ty)\}]^{\frac{1}{2}}$$

Then there exists a point  $t \in X$  such that  $It = Jt \in St \cap Tt$ , i.e. the point t is a coincidence point of I, J, S and T.

**Proof:** Assume  $k = \frac{1}{\sqrt{h}}$ . Let  $x_0 \in X$  and  $y_1$  be an arbitrary point in  $Sx_0$ . Then there is  $x_1 \in X$  such that  $Jx_1 = y_1$  which is possible as  $S(X) \subset J(X)$ . By

Lemma 2.7 we can find a  $y_2 \in Tx_1$  such that  $d(y_1, y_2) \leq kH(Sx_0, Tx_1)$ . Let us set  $y_2 = Ix_2$  as  $T(X) \subset I(X)$ . Thus in general one can choose  $y_{2n+2} = Ix_{2n+2} \in Tx_{2n+1}$  and  $y_{2n+1} = Jx_{2n+1} \in Sx_{2n}$  such that  $d(y_{2n+2}, dy_{2n+1}) \leq kH(Sx_{2n}, Tx_{2n+1})$  for n = 1, 2, 3.....If h = 0, the result is obvious, hence we consider the case when  $h \neq 0$ . Now, for  $n \geq 1$  we have

 $d(y_{2n+2}, y_{2n+1}) = d(Jx_{2n+1}, Ix_{2n+2}) \le kH(Sx_{2n}, Tx_{2n+1})$ 

$$\leq \sqrt{h[aL(Ix_{2n}, Jx_{2n+1}) + (1-a)N(Ix_{2n}, Jx_{2n+1})]}$$

where

$$L(Ix_{2n}, Jx_{2n+1}) = max\{d(Ix_{2n}, Jx_{2n+1}), d(Ix_{2n}, Sx_{2n})\}$$

$$d(Jx_{2n+1}, Tx_{2n+1}), \frac{1}{2}[d(Ix_{2n}, Tx_{2n+1}) + d(Jx_{2n+1}, Sx_{2n})]\}$$
  
$$\leq max\{d(y_{2n}, y_{2n+1}), d(y_{2n+1}, d(y_{2n+2}))\}$$

and

$$N(Ix_{2n}, Jx_{2n+1}) \le [max\{d^2(Ix_{2n}, Jx_{2n+1}), d(Ix_{2n}, Sx_{2n})d(Jx_{2n+1}, Tx_{2n+1}), d(Ix_{2n}, Tx_{2n+1})d(Jx_{2n+1}, Tx_{2n+1}), d(Ix_{2n}, Tx_{2n+1})d(Jx_{2n}, Tx_{2n+1})d(Jx_{2n}, Tx_{2n+1})d(Jx_{2n})d(Jx_{2n}, Tx_{2n})d(Jx$$

$$d(Ix_{2n}, Tx_{2n+1})d(Jx_{2n+1}, Sx_{2n}), \frac{1}{2}(d(Ix_{2n}, Sx_{2n})d(Jx_{2n+1}, Sx_{2n})),$$

$$\frac{1}{2}d(Ix_{2n}, Tx_{2n+1})d(Jx_{2n+1}, Tx_{2n+1})\}]^{\frac{1}{2}}$$

$$\leq [max\{d^{2}(y_{2n}, y_{2n+1}), d(y_{2n}, y_{2n+1})d(y_{2n+1}, y_{2n+2}), 0, 0,$$

$$\frac{1}{2}((d(y_{2n}, y_{2n+1}) + d(y_{2n+1}, y_{2n+2}))d(y_{2n+1}, y_{2n+2})\}]^{\frac{1}{2}}.$$

$$\leq [max\{d^2(y_{2n}, y_{2n+1}), d(y_{2n}, y_{2n+1})d(y_{2n+1}, y_{2n+2}), d^2(y_{2n+1}, y_{2n+2})\}]^{\frac{1}{2}}.$$

Suppose on contrary that  $d(y_{2n+1}, y_{2n+2}) > \sqrt{hd(y_{2n}, y_{2n+1})}$  for some  $n \in N$ . Then we have  $d(y_{2n+1}, y_{2n+2}) < d(y_{2n+1}, y_{2n+2})$  which is contradiction and so

$$d(y_{2n+1}, y_{2n+2}) \le \sqrt{hd(y_{2n+1}, y_{2n})}$$
(3.1.2)

Similarly one can show that

$$d(y_{2n+1}, y_{2n}) \le \sqrt{hd(y_{2n}, y_{2n-1})}$$

which in general yields that

 $d(y_{n+1}, y_n) \leq \sqrt{hd(y_n, y_{n-1})}$  for all n establishing that the sequence  $y_n$  described by

is a Cauchy sequence and get limit t in X. Hence the sequences  $\{Ix_{2n}\}$  and  $\{Jx_{2n+1}\}$  which are subsequences of  $\{y_n\}$  also converge to the point t. Also by the fact that  $H(Sx_{2n}, Tx_{2n+1}) \leq hd(Ix_{2n}, Jx_{2n+1})$  together with (3.1.3)one can conclude that

$$\{Sx_0, Tx_1, Sx_2, Tx_2, \dots, Tx_{2n-1}, Sx_{2n}, Tx_{2n+1}, \dots, \{3.1.4\}\}$$

is a Cauchy sequence in (CB(X), H). Hence he sequences  $\{Sx_{2n}\}$  and  $\{Tx_{2n+1}\}$  converge to some M in CB(X). Now, one can have

$$d(t, M) \le d(t, Ix_{2n}) + d(Ix_{2n}, M) \le d(t, Ix_{2n}) + H(Tx_{2n-1}, M) \to 0 \text{ as } n \to \infty,$$

establishing that  $t \in M$  as M is closed. Now, by the weak compatibility of (S, I), one can write

$$\lim_{n \to \infty} H(ISx_{2n}, SIx_{2n}) \le \lim_{n \to \infty} H(SIx_{2n}, Sx_{2n})$$
(3.1.5)

$$\lim_{n \to \infty} d(ISx_{2n}, Ix_{2n}) \le \lim_{n \to \infty} H(SIx_{2n}, Sx_{2n})$$
(3.1.6)

Using the above mentioned inequality, we obtained

$$\lim_{n \to \infty} \mathrm{d}(IIx_{2n}, Ix_{2n}) \leq \lim_{n \to \infty} \mathrm{d}(IIx_{2n}, ISx_{2n}) + \lim_{n \to \infty} \mathrm{d}(ISx_{2n}, Ix_{2n})$$

$$\leq \lim_{n \to \infty} d(IIx_{2n}, ISx_{2n}) + \lim_{n \to \infty} H(SIx_{2n}, Sx_{2n}) \tag{3.1.7}$$

Since S and I are continuous, making  $n \to \infty, (3.1.5), (3.1.6), (3.1.7)$  we get

$$H(I(M), St) \leq H(St, M)$$
 and  $d(It, t) \leq H(St, M)$ 

Similarly using the continuity and weak compatibility of the pair (T, J) one can show that

$$H(J(M),Tt) \leq H(Tt,M)$$
 and  $d(Jt,t) \leq H(Tt,M)$ 

Now

$$d(Jt, Tt) \leq d(Jt, JIx_{2n}) + d(JIx_{2n}, Tt) \\\leq d(Jt, JIx_{2n}) + H(JTx_{2n-1}, Tt) \\\leq d(Jt, JIx_{2n}) + H(JTx_{2n-1}, TJx_{2n-1}) + d(TJx_{2n-1}, Tt)$$

Which on letting  $n \rightarrow \infty$ , reduces to

$$d(Jt, Tt) \le H(Tt, M)$$

Now using (3.1.1) we have

$$H(Sx_{2n}, Tt) \le h[aL(Ix_{2n}, Jt) + (1-a)N(Ix_{2n}, Jt)],$$

Where

$$L(Ix_{2n}, Jt) \le max\{d(Ix_{2n}, Jt), d(Ix_{2n}, Sx_{2n}), d(Jt, Tt), \frac{1}{2}[d(Ix_{2n}, Tt) + d(Jt, Ix_{2n}) + d(Ix_{2n}, Sx_{2n})]\}$$

which on letting  $n \to \infty$ , reduce to

$$\begin{split} \lim_{n \to \infty} L(Ix_{2n}, Jt) &\leq \max\{H(Tt, M), 0, H(Tt, M), \frac{1}{2}[H(Tt, M) + H(Tt, M) + 0]\} \\ &= H(M, Tt) \end{split}$$

and

$$N(Ix_{2n}, Jt) \le \max\{d^2(Ix_{2n}, Jt), d(Ix_{2n}, Sx_{2n})d(Jt, Tt), \\ d(Ix_{2n}, Tt)[d(Jt, Ix_{2n}) + d(Ix_{2n}, Sx_{2n})],$$

$$\frac{1}{2}d(Ix_{2n}, Sx_{2n})[d(Jt, Ix_{2n}) + d(Ix_{2n}, Sx_{2n})], \frac{1}{2}[d(Ix_{2n}, Tt)d(Jt, Tt)]^{\frac{1}{2}}.$$

which on letting  $n \to \infty$ , reduces to

$$\begin{split} \lim_{n \to \infty} N(Ix_{2n}, Jt) &\leq [max\{d^2(t, Jt), d(t, M)d(Jt, Tt), d(t, Tt)[d(Jt, t) + d(t, M)], \\ &\frac{1}{2}d(t, M)[d(Jt, t) + d(t, M)], \frac{1}{2}[d(t, Tt)d(Jt, Tt)\}]^{\frac{1}{2}} \\ &\leq [max\{H^2(Tt, M), 0, H(Tt, M)[H(Tt, M) + 0], 0, \frac{1}{2}H^2(Tt, M)\}]^{\frac{1}{2}}, \end{split}$$

$$\leq H(M, Tt) \tag{3.1.8}$$

Thus

$$H(M,Tt) = \lim_{n \to \infty} H(Sx_{2n},Tt)$$

$$\leq h[a \ lim_{n \to \infty} L(Ix_{2n}, Jt) + (1-a)lim_{n \to \infty} N(Ix_{2n}, Jt)]$$
$$\leq h[aH(M, Tt) + (1-a)H(M, Tt)] = hH(M, Tt)$$

which implies that H(M, Tt) = 0. Therefore d(Jt, Tt) = 0 which in turn yields  $Jt \in Tt$  as Tt is closed. Similarly, one can also show that  $It \in St$ .

Now it remains to show that It = Jt. For this we consider

$$d(It, Jt) \le d(It, SIx_{2n}) + H(SIx_{2n}, TJx_{2n-1}) + d(TJx_{2n-1}, Jt)$$
  
$$\le d(It, SIx_{2n}) + d(TJx_{2n-1}, Jt) + h[a maxd(I^{2}x_{2n}, J^{2}x_{2n-1}), d(I^{2}x_{2n}, SIx_{2n}),$$

$$d(J^{2}x_{2n-1}, TJx_{2n-1}), \frac{1}{2}[d(I^{2}x_{2n}, Jt) + d(Jt, TJx_{2n-1}) + d(J^{2}x_{2n-1}, It) + d(It, SIx_{2n})]$$

$$+(1-a)[max\{d^{2}(I^{2}x_{2n}, J^{2}x_{2n-1}), d(I^{2}x_{2n}, SIx_{2n})d(J^{2}x_{2n-1}, TJx_{2n-1}), \\ (d(I^{2}x_{2n}, J^{2}x_{2n-1})+d(J^{2}x_{2n-1}, TJx_{2n-1}))(d(J^{2}x_{2n-1}, I^{2}x_{2n})+d(I^{2}x_{2n}, SIx_{2n})), \\ \frac{1}{2}d(I^{2}x_{2n}, SIx_{2n})d(J^{2}x_{2n-1}, SIx_{2n}), \\ \frac{1}{2}[d(I^{2}x_{2n}, J^{2}x_{2n-1})+d(J^{2}x_{2n-1}, TJx_{2n-1})]d(J^{2}x_{2n-1}, TJx_{2n-1})\})]^{\frac{1}{2}}$$

which on letting  $n \to \infty$ , reduces

 $d(It, Jt) \le hd(It, Jt)$ 

yielding thereby It = Jt

Thus we have shown that  $It = Jt \in St \cap Tt$  establishing that t is a coincidence point of I, J, S and T.

This completes the proof.

In order to obtain a fixed point result corresponding to Theorem 3.1 one requires additional hypotheses. In this regard the following lemma from Pathak et al[10] is useful.

**Lemma 3.2** [10] Let  $S, T : X \to CB(X)$  and  $I, J : X \to X$  be continuous mappings if  $Iw = Jw \in Tw \cap Sw$  for some  $w \in X$  and Theorem 3.1 holds for all x, y in X, then JTw = TJw, and ISw = SIw.

**Proof:** Let  $x_n = w$  for all  $n \in N$ . Hence if  $Iw=Jw \in Tw \cap Sw$ , then by weak compatibility of (S, I) and (T, J) one can have

$$H(ISw, SIw) \le H(SIw, Sw)$$
(3.2.1),  
$$H(JTw, TJw) \le H(TJw, Tw),$$

 $d(I^2w,Jw) \leq d(I^2w,ISw) + d(ISw,Iw) + d(Iw,Jw) \leq H(SIw,Sw),$ 

and similarly

$$d(Iw, J^2w) \le H(SIw, Sw).$$

Now

H(SIw, Sw) = H(SIw, Tw)

$$\leq h[aL(I^2w, Jw) + (1-a)N(I^2w, Jw)]$$
(3.2.2)

where

$$\begin{split} L(I^2w, Jw) &= max\{d(I^2w, Jw), d(I^2w, SIw), d(Jw, Tw), \frac{1}{2}[d(I^2w, Tw) + d(Jw, SIw)]\}\\ &\leq max\{H(SIw, Sw), H(SIw, Sw), 0, H(SIw, Sw)\}, \end{split}$$

and

$$\begin{split} N(I^2w,Jw) &= [max\{d^2(I^2w,Jw),d(I^2w,SIw)d(Jw,Tw),d(I^2w,Tw)d(Jw,SIw),\\ &\frac{1}{2}[d(I^2w,SIw)d(Jw,SIw),\frac{1}{2}[d(I^2w,Tw)d(Jw,Tw)\}]^{\frac{1}{2}}\\ &\leq [max\{H^2(SIw,Sw),0,H^2(SIw,Sw),\frac{1}{2}H^2(SIw,Sw),0,\}]^{\frac{1}{2}}, \end{split}$$

= H(SIw, Sw)which in turn yields that

$$H(SIw, Sw) = H(SIw, Tw) \le h[a.H(SIw, Sw) + (1-a)H(SIw, Sw)]$$

= hH(SIw, Sw)

which is a contradiction. Therefore, we have SIw = Sw. Hence from (3.2.1) SIw = ISw

Similarly we can show that TJw = JTw. Now we formulate a fixed point theorem as follows: **Theorem 3.3** Let S, T, I and J satisfy all the conditions of Theorem 3.1. Assume that for each  $x \in X$  either

$$(i)Ix \neq I^2x \Rightarrow Ix \notin Sx(resp, Jx \neq J^2x \Rightarrow Jx \notin Tx$$

 $(ii)Ix \in Sx \Rightarrow I^n x \to w for some \ w \in X(respJx \in Tx \Rightarrow J^n x \to w')$ 

for some  $w' \in X$ , then S, T, I and J have a common fixed point in X.

**Proof:** By Theorem 3.1 there exists a point z in X such that  $Iz = Jz \in Sz \cap Tz$ . Since  $Iz \in Sz$ , Lemma 3.2 yields ISz = SIz. If (i) holds,  $Iz = I^2z \in ISz = SIz$ . Thus w = Iz is the fixed point of I and S.

If (ii) holds, then it is clear that Iw = w as I is continuous. Now we assert that  $I^n z \in SI^{n-1}z$  for each n. To verify this, we consider  $I^2 z = IIz \in ISz = SIz$ . Using Lemma3.2 (w = Iz) we can have  $I^3 z = II^2 z \in I(ISz) = SI^2 z$ . Thus inductively we get  $I^n z = SI^{n-1}z$  and hence the continuity implies that

$$d(w, Sw) \le d(w, I^n z) + d(I^n z, Sw)$$

$$\leq d(w, I^n z) + d(SI^{n-1}z, Sw$$

which tends to zero as  $n \to \infty$ . Hence  $w = Iw \in Sw$  as Sw is closed. Similarly one can show that  $w' = Jw' \in Tw'$ .

Now using contraction condition, one can obtains

$$\begin{aligned} d(w,w') &= d(Iw,Jw') \\ &= H(Sw,Tw') \\ &\leq h[ad(Iw,Jw') + (1-a)d(Iw,Jw')] \\ &\leq hd(w,w') \\ &\text{implying thereby } w = w' \end{aligned}$$

Thus we prove have that  $w = Iw = Jw \in Sw \cap Tw$ . Hence w is a common fixed point of S,T,I and J.

If we replace weak compatibility[6],[10] by weak commutativity due to Hadzic-Gajic [4], then the continuity of S and T can be relaxed and no additional hypotheses are needed to ensure the existence of coincidence point which appears to be a noted improvement over Theorem 3.1.

**Theorem 3.4** Let S, T, I, J, X and CB(X) be the same as in Theorem 3.1. If we replace the weak compatibility with weak commutativity in Theorem 3.1 with I and J continuous then there is a point t in X such that  $It = Jt \in St \cap Tt$ .

**Proof:** Proceeding as in Theorem 3.1, we can show that the subsequences  $Ix_{2n}, Jx_{2n+1}$  converge to some t in X whereas the sequences  $Sx_{2n}, Tx_{2n+1}$  converge to some M in CB(X).

Since J is continuous, sequence  $JIx_{2n}$  converges Jt. Now, using the weak commutativity of (T, J), we have  $Ix_{2n} \in Tx_{2n-1}$  and so

$$d(JIx_{2n}, TJx_{2n-1}) = d(JTx_{2n-1}, TJx_{2n-1}) \le d(Jx_{2n-1}, Tx_{2n-1}) \le d(Ix_{2n}, Jx_{2n-1})$$

which on letting  $n \to \infty$ , reduce to

$$d(Jt, TJx_{2n-1}) \to 0$$

Similarly, using the continuity of I and weak commutativity of (S, I), we can show that

$$d(It, SIx_{2n}) \to 0 \text{ as } n \to \infty.$$

Now consider

$$\begin{aligned} &d(It, Jt) \leq d(It, SIx_{2n}) + H(SIx_{2n}, TJx_{2n-1}) + d(TJx_{2n-1}, Jt) \\ &\leq d(It, SIx_{2n}) + d(Jt, TJx_{2n-1}) + h\{[a \max d(I^2x_{2n}, J^2x_{2n-1}), d(I^2x_{2n}, SIx_{2n}), d(I^2x_{2n}, SIx_{$$

 $d(J^2x_{2n-1},TJx_{2n-1}),\frac{1}{2}[d(I^2x_{2n},Jt)+d(Jt,TJx_{2n-1})+d(J^2x_{2n-1},It)+d(It,SIx_{2n})]\}$ 

+
$$(1-a)[max\{d^2(I^2x_{2n}, J^2x_{2n-1}), d(I^2x_{2n}, SIx_{2n})d(J^2x_{2n-1}, TJx_{2n-1}),$$

$$[d(I^{2}x_{2n}, TJx_{2n-1})d(J^{2}x_{2n-1}, SIx_{2n})], \frac{1}{2}d(I^{2}x_{2n}, SIx_{2n})d(J^{2}x_{2n-1}, SIx_{2n}),$$

$$\frac{1}{2}[I^2x_{2n}, TJx_{2n-1})d(J^2x_{2n-1}, TJx_{2n-1})\})]^{\frac{1}{2}}$$

which on letting  $n \to \infty$ , reduces

$$d(It, Jt) \leq hd(It, Jt)$$
, yielding thereby  $It = Jt$ .

Now

$$d(Jt, St) \le d(Jt, TJx_{2n-1}) + H(TJx_{2n-1}, St)$$

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$$\leq d(Jt, JTx_{2n-1}) + d(JTx_{2n-1}, TJx_{2n-1}) + H(ST, TJx_{2n-1}, )$$
  
$$\leq d(Jt, JTx_{2n-1}) + d(JTx_{2n-1}, TJx_{2n-1}) + h[a \max\{d(It, J^{2}x_{2n-1}), d(It, St)d(J^{2}x_{2n-1}, TJx_{2n-1}), \frac{1}{2}[d(It, TJx_{2n-1}) + d(J^{2}x_{2n-1}, St)]\}$$
  
$$+ (1-a)[\max d^{2}(I^{2}t, Jx_{2n-1}^{2}), d(It, St)d(J^{2}x_{2n-1}, TJx_{2n-1})]$$

$$d(It, TJx_{2n-1})d(J^2x_{2n-1}, St)], \frac{1}{2}d(It, St)d(J^2x_{2n-1}, St)$$

$$\frac{1}{2}d(It, TJx_{2n-1})d(J^2x_{2n-1}, TJx_{2n-1})]\}]^{\frac{1}{2}}$$

which on letting  $n \to \infty$ , reduce to

$$d(Jt, St) \le hd(Jt, St),$$

yielding thereby  $Jt \in St$ , as St is closed.

Similarly one can show that  $It \in Tt$ . Thus we have shown that  $It = Jt \in St \cap Tt$ .

#### Remark:

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(a) If we replace CB(X) by PB(X) (with  $ISx, JTx \in PB(X)$ ) and choose L(x, y) = d(Ix, Jy), a = 1 in Theorem 3.1 then we get an improve version of Corollary 2.2 of Pathak et al.[10] as it involves four mappings instead of two.

(b) If we choose a = 1 in Theorem, then we get sharpen version of Theorem 2 of [9] which in term generalizes the main result of Kaneko and Sessa[6]

**Related Example:** We present example to discuss the validity of the hypotheses of main results.

**Example:** Let  $X = [0, \infty)$  be endowed with the Euclidean metric d(x, y) = |x - y|.Let  $I(X) = \frac{3}{2}(x^4 + x^2)$ ,  $J(X) = \frac{3}{2}(x^2 + x)$ ,  $T(X) = [0, x^2 + 2]$ ,  $S(X) = [0, x^4 + 2]$  for each  $x \ge 0$ . Then I, J, S and T are continuous and I(X) = J(X) = T(X) = S(X). Since  $Sx_n, Tx_n \to [0, 3]$  and  $Ix_n, Jx_n \to 3$  if  $x_n \to 1$ . We observe by the verification that

$$\begin{aligned} &d(ISx_n, Ix_n) \to 0, & H(ISx_n, SIx_n) \to 52, & H(SIx_n, Sx_n) \to 80, \\ &d(JTx_n, Jx_n) \to 0, & H(JTx_n, TJx_n) \to 7, & H(TJx_n, Tx_n) \to 8, \end{aligned}$$

Therefore (S, I) and (T, J) are weak compatible but they are not compatible. Also since

$$H(Sx, Ty) = |x^{4} - y^{2}|$$

$$\frac{(x^{2}+y)}{(x^{2}+y+1)} |x^{2} - y| |x^{2} + y + 1|$$

$$\frac{2(x^{2} + y)3}{3(x^{2} + y + 1)2} |x^{4} - y^{2} + x^{2} - y|$$

$$\leq \frac{2}{3}d(Ix, Jy) = h[aL(Ix, Jy) + (1 - a)N(Ix, Jy)]$$

for all  $x, y \in X$ , where  $h \in [\frac{2}{3}, 1]$  and  $0 \le a \le 1$ . Thus all the conditions of Theorem 3.1 are satisfied and 0 is the unique common fixed point of S, T, I and J.

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