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ALMOST OPTIMAL LOCAL WELL-POSEDNESS FOR MODIFIED BOUSSINESQ EQUATIONS

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ABSTRACT. In this article, we investigate a class of modified Boussinesq equations, for which we provide first an alternate proof of local well-posedness in the space $(H^s \cap L^\infty) \times (H^s \cap L^\infty)(\mathbb{R})$ $(s \ge 0)$ to the one obtained by Constantin and Molinet [7]. Secondly, we show that the associated flow map is not smooth when considered from $H^s \times H^s(\mathbb{R})$ into $H^s(\mathbb{R})$ for s < 0, thus providing a threshold for the regularity needed to perform a Picard iteration for these equations.

1. INTRODUCTION

1.1. Background. Our goal is to study the initial value problem (IVP)

$$u_{tt} - u_{xx} - u_{xxtt} = (f(u))_{xx}, \quad u = u(t, x) \in \mathbb{R}_+ \times \mathbb{R} \to \mathbb{R}, u(0, x) = u_0(x), \quad u_t(0, x) = u_1(x),$$
(1.1)

for which the differential equation is known in the literature as a modified Boussinesq (imBq) equation. Initially, Makhankov [10] derived the equation with $f(u) = u^2$ in the context of ion-sound wave propagation and mentioned the one with $f(u) = u^3$ as modeling nonlinear Alfvén waves. Later, Clarkson, LeVeque, and Saxton [6] discovered that the equations with either $f(u) = u^3/3$ or $f(u) = u^5/5$ describe the propagation of longitudinal deformation waves in an elastic rod. For related parabolic models, please see work by Chen and Liu [4].

The imBq equation is also known as an improved frequency dispersion version of the classical Boussinesq equation

$$u_{tt} - u_{xx} - u_{xxxx} = (u^2)_{xx},$$

derived in relation to shallow water waves. The latter has the dispersive relation

$$\omega^2 = k^2 - k^4,$$

which leads to a nonphysical instability when k > 1. This is not the case for the imBq equation, whose dispersive relation is given by

$$\omega^2 = \frac{k^2}{1+k^2}.$$

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In the same context, another well-known improved frequency dispersion version of the classical Boussinesq equation is the "good" or "well-posed" Boussinesq equation

$$u_{tt} - u_{xx} + u_{xxxx} = (f(u))_{xx}, \tag{1.2}$$

which was found to describe electromagnetic waves in nonlinear dielectrics, magnetoelastic waves in antiferromagnets, and shape-memory alloys.

Past investigations concerning the IVP (1.1) mainly focused on two directions. The first one concentrated on the existence and uniqueness of various types of local solution (e.g., strong, classical), as well as on sufficient conditions for the existence or the blow-up in finite time of such global solutions. We mention here work by Constantin and Molinet [7], who looked at the equation

$$u_{tt} - u_{xxtt} = (F(u))_{xx}, \quad F \in C^{\infty}(\mathbb{R}), \quad F(0) = 0,$$
 (1.3)

and showed that the associated IVP is locally well-posed (LWP) for $(u(0), u_t(0)) \in (H^s \cap L^\infty)(\mathbb{R}) \times (H^s \cap L^\infty)(\mathbb{R})$, with $s \ge 0$ being arbitrary. Moreover, the same paper contains both continuation criterions for local-in-time solutions to be extended into global ones and conditions on F which guarantee either global solutions or blow-up in finite time for certain data profiles. Similar results were obtained by Wang and Chen [14] for the multidimensional problem (i.e, $x \in \mathbb{R}^n$, $n \ge 2$, and every ∂_x^2 is replaced by Δ).

The other type of question that was studied in connection to the IVP (1.1) is the existence and scattering of global small amplitude solutions. A very formal description of this question is as follows: what are the values of p > 1 for which global, small H^s solutions to (1.1), with $|f(u)| \simeq |u|^p$, scatter? Cho and Ozawa [5] gave an almost optimal answer to this question both for (1.1) and the IVP for the "good" Boussinesq equation (1.2). We refer the interested reader to this article and references therein for a comprehensive discussion of this issue.

1.2. Description and statement of main results. One topic which is usually studied in relation to evolution equations, especially dispersive ones, is the ill-posedness (IP) of the associated IVP. To our best knowledge, such an inquiry has not been conducted yet for (1.1). The goal of this article is to do just that, in the case when $f(u) = \pm u^p$ and p > 1 is an integer. Our results are in the same spirit with the ones originally obtained by Bourgain [3] and Tzvetkov [13] for the KdV equation and then also derived for other dispersive equations (e.g., Molinet and Ribaud [11], Bona and Tzvetkov [2], Geba, Himonas, and Karapetyan [8]).

They establish loss of smoothness for the flow map, which is defined for a fixed time t as

$$(u_0, u_1) \mapsto S(t)(u_0, u_1) := u(t).$$

The loss of regularity occurs when the domain of the flow map is chosen to be $H^s \times H^s(\mathbb{R})$, with s < 0 being arbitrary. To argue for the optimality claimed in the title, we show that (1.1) is LWP in $(H^s \cap L^{\infty}) \times (H^s \cap L^{\infty})(\mathbb{R})$ when $s \ge 0$, by running a contraction argument for one of its integral formulations. In particular, this implies that the flow map is smooth as a map from $(H^s \cap L^{\infty}) \times (H^s \cap L^{\infty})(\mathbb{R})$ to $(H^s \cap L^{\infty})(\mathbb{R})$ for all times in the interval of existence. It is not clear that this conclusion can be drawn, at least easily, from the analysis done by Constantin and Molinet in [7]. There, equation (1.3) is recast in the form of an ODE system in Banach spaces and the LWP is obtained by classical Picard iteration.

reason for the inclusion of our LWP argument is that it contains some new harmonic analysis facts that may be of independent interest.

Following this, we derive the integral version of the IVP (1.1), which is the central object of study from this point onward. This is obtained by first rewriting the imBq equation as

$$u_{tt} + P(D)u = -P(D)f(u), \quad P(D) := \mathcal{F}_{\xi}^{-1} \frac{\xi^2}{1+\xi^2} \mathcal{F}_x, \quad (1.4)$$

and then applying Duhamel's principle to infer

$$u(t) = L(u_0, u_1)(t) - \int_0^t L(0, P(D)(f(u(\tau))))(t - \tau) d\tau, \qquad (1.5)$$

where

$$\widehat{L(v_0, v_1)(t)(\xi)} := \cos(t\lambda(\xi)) \,\widehat{v}_0(\xi) + \frac{\sin(t\lambda(\xi))}{\lambda(\xi)} \,\widehat{v}_1(\xi),$$

$$\lambda(\xi) := \frac{|\xi|}{\langle \xi \rangle} = \frac{|\xi|}{(1+\xi^2)^{1/2}}.$$
 (1.6)

We can now state our main results.

Theorem 1.1. Consider the integral equation (1.5) with $f(u) = \pm u^p$ and p > 1 being an arbitrary integer.

(i) (LWP) If
$$s \ge 0$$
 and $(u_0, u_1) \in (H^s \cap L^\infty) \times (H^s \cap L^\infty)(\mathbb{R})$, then there exist

$$T = T(\|(u_0, u_1)\|_{(H^s \cap L^\infty) \times (H^s \cap L^\infty)(\mathbb{R})}) > 0$$

and a unique solution u satisfying

$$u \in C([0,T], (H^s \cap L^\infty)(\mathbb{R})).$$

Moreover,

$$S(t): (H^s \cap L^\infty) \times (H^s \cap L^\infty)(\mathbb{R}) \to (H^s \cap L^\infty)(\mathbb{R}), \quad S(t)(u_0, u_1) := u(t),$$

is smooth for all $t \in [0, T]$.

(ii) (IP) If s < 0, then there exists T > 0 such that $S(t) : H^s \times H^s(\mathbb{R}) \to H^s(\mathbb{R})$ does not admit a p-th order Fréchet derivative at zero for all 0 < t < T.

The LWP part of this theorem will be addressed in the next section, whereas the argument for IP will occupy the final section.

2. LWP ARGUMENT

In proving the LWP claim, we rely on the classical approach of verifying that the right-hand side of (1.5), when seen as a functional in u (with the data u_0 and u_1 being fixed), is a contraction on a suitably chosen closed ball of a Banach space.

For this purpose, we are first concerned with the mapping properties of the multiplier operators P(D) (defined in (1.4)) and

$$Q_t(D) := \mathcal{F}_{\xi}^{-1} \cos(t\lambda(\xi)) \mathcal{F}_x, \quad R_t(D) := \mathcal{F}_{\xi}^{-1} \frac{\sin(t\lambda(\xi))}{\lambda(\xi)} \mathcal{F}_x, \tag{2.1}$$

where $t \in \mathbb{R}$ is arbitrary, yet fixed. Given the trivial bounds

$$0 \le \lambda^2(\xi) = \frac{\xi^2}{1+\xi^2} < 1, \quad |\cos(t\lambda(\xi))| \le 1, \quad \left|\frac{\sin(t\lambda(\xi))}{\lambda(\xi)}\right| \le |t|,$$

Plancherel's formula implies

$$\|P(D)v\|_{H^s} \le \|v\|_{H^s}, \quad \|Q_t(D)v\|_{H^s} \le \|v\|_{H^s}, \quad \|R_t(D)v\|_{H^s} \le |t|\|v\|_{H^s}.$$
(2.2)

From here on, for a functional space Y, we write $Y = Y(\mathbb{R})$ as the majority of such norms refers to this particular situation.

Next, which is one of the novelties in our paper, we show that the symbols of these operators are also Fourier multipliers on L^{∞} in the sense of Bergh-Löfström [1, Def. 6.1.1]. By comparison, Constantin and Molinet [7] proved that P(D) maps $H^s \cap L^{\infty}$ into itself for all $s \geq 0$. In arguing for this claim, we rely on a number of facts, some of which are contained in the book by Bergh and Löfström. One of them is [1, Exercise 16 on page 164] which states that the homogeneous Besov space $\dot{B}_{2,1}^{n/2}(\mathbb{R}^n)$ is a subspace of the normed space of Fourier multipliers on $L^{\infty}(\mathbb{R}^n)$. A second fact (Inferred from [1, Theorem 6.3.1] and from Shatah-Struwe [12, Section 3.2].) is the equivalence between the original seminorm for $\dot{B}_{2,1}^{n/2}(\mathbb{R}^n)$ and

$$\|w\|_{\dot{B}^{n/2}_{2,1}(\mathbb{R}^n)}^* := \int_{\mathbb{R}^n} \frac{\|w(\cdot+h) - w(\cdot)\|_{L^2(\mathbb{R}^n)}}{|h|^{n+\frac{1}{2}}} \, dh.$$

We will also use the following integration result, which is a special case of Ginibre-Tsutsumi-Velo [9, Lemma 4.2],

$$\int_{\mathbb{R}} \frac{1}{\langle z-a \rangle^2 \langle z-b \rangle^4} \, dz \lesssim \frac{1}{\langle a-b \rangle^2}, \quad (\forall) \, a, b \in \mathbb{R}.$$
(2.3)

Lemma 2.1. The symbols

1

$$m_1(\xi) = \lambda^2(\xi), \quad m_2(\xi) = e^{\pm it\lambda(\xi)}, \quad m_3(\xi) = \sin(t\lambda(\xi))/\lambda(\xi)$$

are all Fourier multipliers on L^{∞} and

$$\|P(D)v\|_{L^{\infty}} \lesssim \|v\|_{L^{\infty}},\tag{2.4}$$

$$\|Q_t(D)v\|_{L^{\infty}} \lesssim |t| \|v\|_{L^{\infty}}, \quad \|R_t(D)v\|_{L^{\infty}} \lesssim \max\{|t|, |t|^3\} \|v\|_{L^{\infty}}.$$
(2.5)

Proof. Based on the facts listed above, it is clear that the lemma is proved if we show that

$$||m_1||_{\dot{B}_{2,1}^{1/2}} \lesssim 1, ||m_2||_{\dot{B}_{2,1}^{1/2}} \lesssim |t|, ||m_3||_{\dot{B}_{2,1}^{1/2}} \lesssim \max\{|t|, |t|^3\}.$$

A direct application of the Cauchy-Schwarz inequality yields

$$||w(\cdot + h) - w(\cdot)||_{L^2} \le |h| ||w'||_{L^2}$$

and straightforward computations provide us with the bounds

$$|m_1'(\xi)| \lesssim rac{1}{\langle \xi
angle^3}, \quad |m_2'(\xi)| \lesssim rac{|t|}{\langle \xi
angle^3}, \quad |m_3'(\xi)| \lesssim rac{|t|^3}{\langle \xi
angle^3}.$$

Then we infer that

$$\begin{split} &\int_{|h|\leq 2} \frac{\|m_1(\cdot+h) - m_1(\cdot)\|_{L^2}}{|h|^{3/2}} \, dh \lesssim 1, \\ &\int_{|h|\leq 2} \frac{\|m_2(\cdot+h) - m_2(\cdot)\|_{L^2}}{|h|^{3/2}} \, dh \lesssim |t|, \\ &\int_{|h|\leq 2} \frac{\|m_3(\cdot+h) - m_3(\cdot)\|_{L^2}}{|h|^{3/2}} \, dh \lesssim |t|^3. \end{split}$$

All what is left to discuss is the scenario when $|h| \ge 2$. In this case, since

 $|\xi|+|\xi+h|\ge |h|,$

it follows that

$$\max\{|\xi|, |\xi+h|\} \simeq \max\{\langle\xi\rangle, \langle\xi+h\rangle\}.$$
(2.6)

Coupled with

$$\lambda(\xi+h) - \lambda(\xi) = \frac{h(2\xi+h)}{\langle \xi+h \rangle \langle \xi \rangle (|\xi+h| \langle \xi \rangle + |\xi| \langle \xi+h \rangle)},$$
(2.7)

this implies

$$|\lambda(\xi+h) - \lambda(\xi)| \lesssim |h| \max\left\{\frac{1}{\langle \xi+h \rangle \langle \xi \rangle^2}, \frac{1}{\langle \xi+h \rangle^2 \langle \xi \rangle}\right\}.$$

As a consequence of (2.3), we deduce

$$\int_{|h|\ge 2} \frac{\|\lambda(\cdot+h) - \lambda(\cdot)\|_{L^2}}{|h|^{3/2}} \, dh \lesssim 1.$$
(2.8)

On the other hand, from $0 \le \lambda(\xi) < 1$, we have

$$|m_1(\xi + h) - m_1(\xi)| \le 2|\lambda(\xi + h) - \lambda(\xi)|.$$
(2.9)

We also have

$$|m_2(\xi+h) - m_2(\xi)| = 2|\sin(t(\lambda(\xi+h) - \lambda(\xi))/2)| \le |t||\lambda(\xi+h) - \lambda(\xi)|. \quad (2.10)$$

For m_3 , we can write

$$m_3(\xi+h) - m_3(\xi) = \frac{\sin(t\lambda(\xi+h)) - \sin(t\lambda(\xi))}{\lambda(\xi+h)} + \sin(t\lambda(\xi)) \left(\frac{1}{\lambda(\xi+h)} - \frac{1}{\lambda(\xi)}\right)$$

which leads to

$$|m_3(\xi+h) - m_3(\xi)| \le \frac{2|t||\lambda(\xi+h) - \lambda(\xi)|}{\lambda(\xi+h)}.$$

By symmetry, we obtain

$$|m_3(\xi+h) - m_3(\xi)| \le \frac{2|t||\lambda(\xi+h) - \lambda(\xi)|}{\max\{\lambda(\xi+h), \lambda(\xi)\}}.$$

From (2.6), we infer $\max\{\lambda(\xi+h), \lambda(\xi)\} \simeq 1$, and, subsequently,

$$|m_3(\xi+h) - m_3(\xi)| \lesssim |t||\lambda(\xi+h) - \lambda(\xi)|.$$

Estimates (2.8)-(2.10) imply

$$\begin{split} &\int_{|h|\geq 2} \frac{\|m_1(\cdot+h) - m_1(\cdot)\|_{L^2}}{|h|^{3/2}} \, dh \lesssim 1, \\ &\int_{|h|\geq 2} \frac{\|m_2(\cdot+h) - m_2(\cdot)\|_{L^2}}{|h|^{3/2}} \, dh \lesssim |t|, \\ &\int_{|h|\geq 2} \frac{\|m_3(\cdot+h) - m_3(\cdot)\|_{L^2}}{|h|^{3/2}} \, dh \lesssim |t|, \end{split}$$

and the proof of the lemma is complete.

Now, we can start in earnest the LWP argument. For fixed u_0 and u_1 , we denote the right-hand side of (1.5) by $Z_{u_0,u_1}(u)$ and, using (1.4) and (2.1), we infer

$$Z_{u_0,u_1}(u) = Q_t(D)u_0 + R_t(D)u_1 - \int_0^t R_{t-\tau}(D)(P(D)(f(u(\tau)))) d\tau.$$

The well-known Moser-type estimate

$$\|vw\|_{H^s} \lesssim \|v\|_{H^s} \|w\|_{L^{\infty}} + \|v\|_{L^{\infty}} \|w\|_{H^s},$$

which is valid for all $s \ge 0$, implies that $H^s \cap L^{\infty}$ is an algebra in this case. If we assume $0 \le t \le T$ and use (2.2), (2.4), and (2.5), we deduce

$$\begin{aligned} \|Z_{u_0,u_1}(u)(t)\|_{H^s \cap L^{\infty}} &\lesssim \max\{1,t\} \|u_0\|_{H^s \cap L^{\infty}} + \max\{t,t^3\} \|u_1\|_{H^s \cap L^{\infty}} \\ &+ \int_0^t \max\{t-\tau,(t-\tau)^3\} \|f(u(\tau))\|_{H^s \cap L^{\infty}} \, d\tau. \end{aligned}$$

Choosing now f(u) as in Theorem 1.1, it follows that

$$\begin{aligned} \|Z_{u_0,u_1}(u)\|_{C([0,T];H^s\cap L^\infty)} &\lesssim \max\{1,T\}\|u_0\|_{H^s\cap L^\infty} + \max\{T,T^3\}\|u_1\|_{H^s\cap L^\infty} \\ &+ \max\{T^2,T^4\}\|u\|_{C([0,T];H^s\cap L^\infty)}^p. \end{aligned}$$

Therefore, by working with T < 1, and with the ball of radius R centered at the origin in the Banach space $C([0,T]; H^s \cap L^\infty)$, $B(0,R) \subset C([0,T]; H^s \cap L^\infty)$ we obtain that

$$u \in B(0,R) \mapsto Z_{u_0,u_1}(u) \in B(0,R)$$

if

$$R \simeq ||u_0||_{H^s \cap L^\infty} + ||u_1||_{H^s \cap L^\infty}$$
 and $T \lesssim R^{-\frac{p-1}{2}}$

Furthermore, using a similar argument, we derive

$$\begin{split} \|Z_{u_0,u_1}(u) - Z_{u_0,u_1}(\tilde{u})\|_{C([0,T];H^s \cap L^{\infty})} \\ &\lesssim T^2 \|u - \tilde{u}\|_{C([0,T];H^s \cap L^{\infty})} \left(\|u\|_{C([0,T];H^s \cap L^{\infty})}^{p-1} + \|\tilde{u}\|_{C([0,T];H^s \cap L^{\infty})}^{p-1} \right) \\ &\lesssim T^2 R^{p-1} \|u - \tilde{u}\|_{C([0,T];H^s \cap L^{\infty})}. \end{split}$$

Thus, with an eventual additional adjustment on the size of T, we conclude that $u \mapsto Z_{u_0,u_1}(u)$ is a contraction on the ball B(0, R) and, consequently, a unique solution to the integral equation (1.5) exists on the time interval [0, T]. The smoothness of the flow map follows then by an application of the analytic version of the implicit function theorem. With this, the LWP part of Theorem 1.1 has been proved.

3. IP ARGUMENT

As explained in the introduction, the scheme for proving IP consists in showing that a putative flow map, when acting from $H^s \times H^s$ into H^s , fails to be smooth for any s < 0. Our approach is very similar to the one used in [8], from which it borrows the main framework.

From (1.5), we see that if $f(u) = \pm u^p$ then

$$S(t)(u_0, u_1) = L(u_0, u_1)(t) \mp \int_0^t L\Big(0, P(D)\Big((S(\tau)(u_0, u_1))^p\Big)\Big)(t - \tau) \, d\tau,$$

for all $t \in [0, T]$, where T > 0 is such that the flow map makes sense on [0, T] near the origin in $H^s \times H^s$. When the flow map is sufficiently regular, we can use this

equation to compute explicitly (by relying on implicit differentiation) its Fréchet derivatives at the origin. Precisely, we have

$$DS(t)_{(v_0,v_1)}(u_0,u_1) = L(v_0,v_1)(t)$$

$$\mp p \int_0^t L\Big(0, P(D)\Big(DS(\tau)_{(v_0,v_1)}(u_0,u_1)\big(S(\tau)(u_0,u_1)\big)^{p-1}\Big)\Big)(t-\tau) d\tau,$$

where $DS(t)_{(v_0,v_1)}(u_0, u_1)$ stands for the first order Fréchet derivative of the flow map at (u_0, u_1) , evaluated for (v_0, v_1) . Given that LWP ensures S(t)(0, 0) = 0, we deduce

$$DS(t)_{(v_0,v_1)}(0,0) = L(v_0,v_1)(t).$$

Arguing along the same lines, we derive

$$D^k S(t)_{(v_0^1, v_1^1), \dots, (v_0^k, v_1^k)}(0, 0) = 0, \quad \text{for } 1 < k < p,$$

and, eventually,

$$D^{p}S(t)_{(v_{0}^{1},v_{1}^{1}),...,(v_{0}^{p},v_{1}^{p})}(0,0) = \mp p! \int_{0}^{t} L\left(0, P(D)\left(L(v_{0}^{1},v_{1}^{1})(\tau)\cdots L(v_{0}^{p},v_{1}^{p})(\tau)\right)\right)(t-\tau) d\tau,$$
(3.1)

Hence, if the flow map had C^p regularity at the origin, the estimate

$$\|D^{p}S(t)_{(v_{0}^{1},v_{1}^{1}),\ldots,(v_{0}^{p},v_{1}^{p})}(0,0)\|_{H^{s}} \lesssim \prod_{j=1}^{p} \|(v_{0}^{j},v_{1}^{j})\|_{H^{s}\times H^{s}}$$

would hold uniformly for $t \in [0, T]$. However, when s < 0, we show that this bound fails by constructing a sequence $(u_0^N, u_1^N)_N \subset H^s \times H^s$ satisfying

$$\lim_{N \to \infty} \frac{\|D^p S(t)_{(u_0^N, u_1^N), \dots, (u_0^N, u_1^N)}(0, 0)\|_{H^s}}{\left(\|u_0^N\|_{H^s} + \|u_1^N\|_{H^s}\right)^p} = \infty, \quad \text{for } 0 < t < T.$$
(3.2)

For ease of notation, we use onward the abbreviation

$$A_p(u_0, u_1)(t) := D^p S(t)_{(u_0, u_1), \dots, (u_0, u_1)}(0, 0).$$

We work with the data

$$\widehat{u_0^N}(\xi) = \varphi_{B_N}(\xi) + \varphi_{-B_N}(\xi), \quad \widehat{u_1^N}(\xi) = -i\lambda(\xi) \, \left(\varphi_{B_N}(\xi) - \varphi_{-B_N}(\xi)\right), \quad (3.3)$$

where $(B_N)_{N\geq 1}$ is a sequence of subsets of \mathbb{R} and φ_A is the characteristic function of the set A. It is easy to check that

$$\overline{\widehat{u_0^N}(\xi)} = \widehat{u_0^N}(-\xi), \quad \overline{\widehat{u_1^N}(\xi)} = \widehat{u_1^N}(-\xi),$$

and, thus, our data are real-valued. By using (1.6) and (3.1), we infer that

$$L(u_0^{\widehat{N}}, u_1^{\widehat{N}})(t)(\xi) = e^{-it\lambda(\xi)}\varphi_{B_N}(\xi) + e^{it\lambda(\xi)}\varphi_{-B_N}(\xi)$$

and, subsequently,

$$A_{p}(\widehat{u_{0}^{N}}, \widehat{u_{1}^{N}})(t)(\xi) = \mp p! \lambda(\xi) \int_{0}^{t} \sin((t-\tau)\lambda(\xi)) \left\{ \int_{\eta_{1}+\dots+\eta_{p}=\xi} \prod_{j=1}^{p} \varphi_{\pm B_{N}}(\eta_{j}) \cdot e^{\mp i\tau\lambda(\eta_{j})} \right\} d\tau,$$

$$(3.4)$$

where the inner integral is

$$\int_{\eta_1 + \dots + \eta_p = \xi} f := \int_{\mathbb{R}^{p-1}} f(\eta_1, \dots, \eta_{p-1}, \xi - \eta_1 - \dots - \eta_{p-1}) \, d\eta_1 \dots d\eta_{p-1}$$

and, with its integrand, we assumed an Einstein summation convention for the symbol \pm ; i.e., if $\eta \in \pm B_N$, then the corresponding exponent is $\mp it\lambda(\eta)$.

Note the generic term in the time integral which yields $A_p(\widehat{u_0^N}, u_1^N)(t)(\xi)$ is of the type

$$\int_0^t \sin(\alpha(t-\tau)) e^{i\beta\tau} \, d\tau,$$

where

$$\alpha = \lambda(\xi), \quad \beta = -\epsilon_1 \lambda(a_1) - \epsilon_2 \lambda(a_2) - \dots - \epsilon_p \lambda(a_p),$$

$$\xi = \epsilon_1 a_1 + \epsilon_2 a_2 + \dots + \epsilon_p a_p, \quad \epsilon_j = \pm 1, \ a_j \in B_N, \quad \text{for } 1 \le j \le p.$$
(3.5)

Moreover, a direct computation reveals that for real parameters α and β we have

$$\operatorname{Re}\left\{\int_{0}^{t}\sin(\alpha(t-\tau))e^{i\beta\tau}\,d\tau\right\} = \begin{cases} \frac{\alpha}{\alpha^{2}-\beta^{2}}(\cos(\beta t)-\cos(\alpha t)), & \text{for } |\alpha| \neq |\beta|, \\ \frac{1}{2}t\sin(\alpha t), & \text{for } |\alpha| = |\beta|. \end{cases}$$
(3.6)

There are two key facts which allow us to argue for (3.2). The first one is the localization in frequency of our data, which is enforced by choosing

$$B_N = [N, N+1], \quad \forall N \ge 1.$$

Coupled with (3.3), this localization easily implies

$$\|u_0^N\|_{H^s} + \|u_1^N\|_{H^s} \simeq N^s.$$
(3.7)

The second important point is that we are interested only in the output of the function $A_p(u_0^N, u_1^N)(t)$ at preferred frequencies, depending on the parity of p. This enables us to have control on the relative size of the parameter β in (3.5), which in turn reduces the argument to obtaining good asymptotics for the generic term.

3.1. Argument for p even. In this case, we restrict our attention to the behavior of $A_p(u_0^{(N)}, u_1^{(N)})(t)$ on the interval [1/4, 1/2] and first deduce that

$$\|A_p(u_0^N, u_1^N)(t)\|_{H^s} \ge \|A_p(u_0^N, u_1^N)(t)\|_{H^s(\xi \in [\frac{1}{4}, \frac{1}{2}])} \simeq \|A_p(u_0^N, u_1^N)(t)\|_{L^2(\xi \in [\frac{1}{4}, \frac{1}{2}])}.$$
(3.8)

Next, from (3.5), we obtain that for N sufficiently large (depending on p) we must have an equal number of +1s and -1s in (3.5) for $\xi \in [1/4, 1/2]$ to be true. Thus, eventually relabelling the indices, we can write

$$\xi = a_1 - a_2 + \ldots + a_{p-1} - a_p, \quad \beta = \lambda(a_1) - \lambda(a_2) + \ldots + \lambda(a_{p-1}) - \lambda(a_p).$$

Following this, we use (2.7) to infer that

$$|\lambda(a) - \lambda(b)| \lesssim \frac{1}{N^3}, \quad \forall a, b \in B_N,$$
(3.9)

which leads to $|\beta| \leq 1/N^3$. We also notice that $\alpha = \lambda(\xi) \simeq 1$ if $\xi \in [1/4, 1/2]$. On the basis of (3.6), we derive that for such values of α and β ,

$$\operatorname{Re}\left\{\int_{0}^{t}\sin(\alpha(t-\tau))e^{i\beta\tau}\,d\tau\right\}\simeq\sin^{2}(\alpha t)+\operatorname{O}\left(\frac{1}{N^{6}}\right)$$

holds if 0 < t < 1 and N is large enough.

These facts tell us that, for fixed 0 < t < 1, the real part of $A_p(\widehat{u_0^N}, \widehat{u_1^N})(t)$ is correctly described by the real part of the generic term in (3.4). As a consequence, we obtain

$$\liminf_{N \to \infty} \|A_p(u_0^N, u_1^N)(t)\|_{L^2(\xi \in [\frac{1}{4}, \frac{1}{2}])} \gtrsim \left(\int_{1/4}^{1/2} \sin^4(\lambda(\xi)t) \, d\xi\right)^{1/2}$$

and, factoring in (3.7) and (3.8), we conclude that

$$\lim_{N \to \infty} \frac{\|A_p(u_0^N, u_1^N)(t)\|_{H^s}}{(\|u_0^N\|_{H^s} + \|u_1^N\|_{H^s})^p} = \infty, \quad \text{for } 0 < t < 1.$$

This proves (3.2) in the case when p is even.

3.2. Argument for p odd. For this scenario, we focus on how $A_p(u_0^N, u_1^N)(t)$ evolves on the interval [N, N+1] and, accordingly, proceed with

$$\|A_p(u_0^N, u_1^N)(t)\|_{H^s} \ge \|A_p(u_0^N, u_1^N)(t)\|_{H^s(\xi \in [N, N+1])}$$

$$\simeq N^s \|A_p(u_0^N, u_1^N)(t)\|_{L^2(\xi \in [N, N+1])}.$$
(3.10)

Arguing as in the even case, we deduce that the representation of $\xi \in [N, N+1]$ in (3.5) requires precisely one more +1 than -1s. Hence, we obtain

$$\xi = a_1 - a_2 + \dots - a_{p-1} + a_p, \quad \beta = \lambda(a_1) - \lambda(a_2) + \dots - \lambda(a_{p-1}) + \lambda(a_p),$$

following a possible relabeling of the indices.

Next, it is straightforward to derive

$$|\lambda(a) - 1| \simeq \frac{1}{N^2}, \quad \forall a \in B_N$$

This estimate and (3.9) imply

$$\alpha = 1 + O(\frac{1}{N^2}), \quad -\beta = 1 + O(\frac{1}{N^2}).$$

Invoking (3.6) again, we infer that

$$\operatorname{Re}\left\{\int_{0}^{t}\sin(\alpha(t-\tau))e^{i\beta\tau}\,d\tau\right\}\simeq t\sin(t)+\operatorname{O}\left(\frac{1}{N^{2}}\right)$$

is valid for 0 < t < 1 and N big enough.

As in the case when p is even, the real part of the generic term in (3.4) describes accurately the real part of $A_p(\widehat{u_0^N, u_1^N})(t)$ and, thus,

$$||A_p(u_0^N, u_1^N)(t)||_{L^2(\xi \in [N, N+1])} \simeq t \sin(t) + \mathcal{O}(\frac{1}{N^2}).$$

Now, we can use (3.7) and (3.10) to conclude that

$$\frac{\|A_p(u_0^N, u_1^N)(t)\|_{H^s}}{(\|u_0^N\|_{H^s} + \|u_1^N\|_{H^s})^p} \simeq \frac{t\sin(t) + \mathcal{O}(1/N^2)}{N^{s(p-1)}}, \quad \text{for } 0 < t < 1,$$

which yields (3.2) also in the odd case.

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