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# EXISTENCE OF POSITIVE SOLUTIONS FOR DIRICHLET PROBLEMS OF SOME SINGULAR ELLIPTIC EQUATIONS

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ABSTRACT. When an unbounded domain is inside a slab, existence of a positive solution is proved for the Dirichlet problem of a class of semilinear elliptic equations similar to the singular Emden-Fowler equation. The proof is based on a super and sub-solution method. A super solution is constructed by Perron's method together with a family of auxiliary functions.

### 1. INTRODUCTION AND MAIN RESULTS

Let  $\Omega$  be an unbounded domain in  $\mathbb{R}^n$   $(n \geq 3)$  with  $C^{2,\alpha}$   $(0 < \alpha < 1)$  boundary. We assume that  $\Omega$  is inside a slab of width 2M:

$$\Omega \subset S_M = \{ (\mathbf{x}, y) \in \mathbb{R}^n : |y| < M \}$$

where  $\mathbf{x} = (x_1, x_2, \dots, x_{n-1})$  and throughout the paper, y will be identified with  $x_n$ .

We consider the existence of positive solutions for the Dirichlet problem

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} u = p(\mathbf{x}, y) u^{-\gamma} \quad \text{on } \Omega; \quad u = 0 \quad \text{on } \partial\Omega; \tag{1.1}$$

where  $(a_{ij})$  is a positive definite matrix in which each entry is a local Hölder continuous function on  $\overline{\Omega}$ ,  $p(\mathbf{x}, y)$  is a also local Hölder continuous on  $\overline{\Omega}$ ,  $\gamma > 0$  is a constant.

The main result of the paper is as follows.

#### Theorem 1.1. Assume

- (1)  $p(\mathbf{x}_0, y_0) > 0$  for some  $(\mathbf{x}_0, y_0) \in \Omega$ ;
- (2) there is a positive constant C such that

$$0 \le p(\mathbf{x}, y) \le C(|\mathbf{x}| + 1)^{\gamma} \quad \text{for} \quad (\mathbf{x}, y) \in \Omega;$$
(1.2)

(3)  $\operatorname{Trace}(a_{ij}) = 1$  and there is a constant  $c_1 > 0$ , such that

$$a_{nn}(\mathbf{x}, y) \ge c_1 \quad on \ \Omega. \tag{1.3}$$

Then (1.1) has a positive solution  $u \in C^2(\Omega) \cap C^0(\overline{\Omega})$ .

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singular semilinear equations, unbounded domains, Perron's method, super solutions.

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When the principal part in (1.1) is the Laplace operator, (1.1) becomes a boundary value problem for the singular Emden-Fowler equation

$$-\Delta u = p(\mathbf{x}, y)u^{-\gamma} \quad \text{on } \Omega; \quad u = 0 \quad \text{on } \partial\Omega.$$
(1.4)

The singular Emden-Fowler is related to the theory of heat conduction in electrical conduction materials and in the studies of boundary layer phenomena for viscous fluids [2, 16]. The existence of positive solutions of the equation on exterior domains (including  $\mathbb{R}^n$ ) has been considered by quite a number of authors (for example, see [4, 5, 8, 11, 12, 15], and references therein). The main approach used to prove existence is to construct super and sub- solutions. To construct super solutions, one needs to assume that  $p(\mathbf{x}, y)$  decays near infinity in an appropriate rate. A super solution is usually found in the class of radial symmetric functions. If  $\Omega$  is an exterior domain (not inside a slab),  $\gamma > 0$  and there is C such that  $p(\mathbf{x}, y) \geq \frac{C}{(1+|\mathbf{x}|^2+y^2)}$ for  $|\mathbf{x}|^2 + y^2$  large, then (1.4) has no positive solutions ([11]). On the other hand, if there are constants  $\sigma > 1$  and C, such that  $0 \le p(\mathbf{x}, y) \le \frac{C}{(1+|\mathbf{x}|^2+y^2)^{\sigma}}$  for  $|\mathbf{x}|^2 + y^2$ large, (1.4) has a positive solution ([8]). When  $\Omega$  is an unbounded domain inside a slab, the situation is quite different. The traditional way to construct a super solution by finding an appropriate radial symmetric function is no longer valid since the domain now is inside a slab (the generality of the coefficient matrix  $(a_{ij})$  also makes finding a radial symmetric super solution impossible). In this paper, we combine an idea from [13] and a family of auxiliary functions constructed in [10] to construct a super solution which is then used to prove the existence of a positive solution of (1.1).

Actually the procedure in the paper can be applied to prove the existence of a positive solution for the Dirichlet problem of more general elliptic equations. A statement for the general case will be given in the last section of the paper. Here we just state a special case of the general result.

#### Theorem 1.2. Assume

- (1)  $p(\mathbf{x}_0, y_0) > 0$  for some  $(\mathbf{x}_0, y_0) \in \Omega$ ;
- (2) there is a positive constant C such that

$$0 \le p(\mathbf{x}, y) \le C e^{|\mathbf{x}|} \quad \text{for} \quad (\mathbf{x}, y) \in \Omega, \tag{1.5}$$

(3)  $\operatorname{Trace}(a_{ij}) = 1$ , and there is a constant  $c_1 > 0$ , such that

$$a_{nn}(\mathbf{x}, y) \ge c_1 \quad \text{on} \quad \Omega.$$
 (1.6)

 $Then \ the \ problem$ 

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} u = p(\mathbf{x}, y) e^{-u} \quad on \ \Omega; \quad u = 0 \quad on \ \partial\Omega \tag{1.7}$$

has a positive solution  $u \in C^2(\Omega) \cap C^0(\overline{\Omega})$ .

This paper is organized as follows. In Section 2, we construct a family of auxiliary functions that are defined on a family of subdomains of  $\Omega$ . In Section 3, we combine the family of auxiliary functions constructed in Section 2 and an idea from [13] to prove that (1.1) has a positive supper solution. In Section 4, we prove that (1.1) has a positive solution by the procedure used in [8]. In Section 5, we discuss the general case.

#### 2. A FAMILY OF AUXILIARY FUNCTIONS

In this section, we will construct families of sub-domains  $\Omega_{\mathbf{x}_0}$  of  $\Omega$  and functions  $T_{\mathbf{x}_0} + z$  (see definitions below) so that

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij}(T_{\mathbf{x}_0} + z) \ge p(\mathbf{x}, y) (T_{\mathbf{x}_0} + z)^{-\gamma} \quad \text{on } \Omega_{\mathbf{x}_0}$$
(2.1)

and the graphs of the functions  $T_{\mathbf{x}_0} + z$  have special relative positions (see below).

Our construction is based on the construction of a family of auxiliary functions used in [10] (the construction in [10] was adapted from [9] which in turn was inspired from [6] and [14]). We consider the operator

$$Qu = \sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} u$$

We first extend  $a_{ij}$   $(1 \le i, j \le n)$  to be continuous functions on  $\overline{S_M}$  in such a way that we still have  $\operatorname{Trace}(a_{ij}) = 1$  and

$$a_{nn}(\mathbf{x}, y) \ge c_1 \quad \text{on } S_M. \tag{2.2}$$

In the rest of the paper, we will use  $c_m$  (for some integer  $m \ge 2$ ) to denote a constant depending only on  $c_1$  and M. Once a constant  $c_m$  is used in a formula, it will represent the same constant if the same notation appears again in the paper.

It was proved in [10] (also see Appendix I) that there are positive decreasing functions  $\chi(t)$ ,  $h_a(t)$  and a positive increasing function A(t) ( $\chi(t)$  depending on  $c_1$  only,  $h_a(t)$  and A(t) depending on  $c_1$  and M only), such that for any number K, there is a number  $H_0$ , depending only on K, M and  $c_1$ , such that for  $H \ge H_0$ , we have (for 0 < t < 2M)

$$A(H) \le h_a^{-1}(t) \le A(H)e^{\chi(H)}, \quad 22MH \le c_1 A(H)e^{\chi(H)} \le 66MH,$$
 (2.3)

$$8K \le A(H)e^{\chi(H)}, \quad 0 < \chi(H) < 1,$$
(2.4)

and the non-negative function

$$z = z_{\mathbf{x}_0} = A(H)e^{\chi(H)} - \{(h_a^{-1}(y+M))^2 - |\mathbf{x} - \mathbf{x}_0|^2\}^{1/2}$$
(2.5)

satisfies

$$Qz \le \frac{-3c_1}{22eMH} \quad \text{in } \Omega_{\mathbf{x}_0, H, K}, \tag{2.6}$$

$$z \ge K$$
 on  $\partial\Omega_{\mathbf{x}_0, H, K} \cap \{|y| < M\}, \quad z(\mathbf{x}_0, y) \le \frac{2M}{H}$  for  $|y| \le M,$  (2.7)

where

$$\Omega_{\mathbf{x}_0,H,K} = \{ (\mathbf{x}, y) : |y| < M, |\mathbf{x} - \mathbf{x}_0| < \sqrt{\frac{2K}{A(H)e^{\chi(H)}}} h_a^{-1}(y+M) \}.$$
(2.8)

(For verifications of (2.3)-(2.4) and (2.6)-(2.7), see Appendix I.)

Now we set

$$K = 100, \quad H = H_0 + 4M, \quad \Omega_{\mathbf{x}_0} = \Omega_{\mathbf{x}_0, H, K}.$$
 (2.9)

Then (2.6)-(2.7) becomes

$$Qz \le -c_2 \quad \text{in } \Omega_{\mathbf{x}_0},\tag{2.10}$$

$$z \ge 100 \quad \text{on } \partial\Omega_{\mathbf{x}_0} \cap \{|y| < M\}, \quad z(\mathbf{x}_0, y) \le 1 \quad \text{for } |y| \le M.$$
 (2.11)

Now we construct a family of auxiliary functions as follows. If  $(x, y) \in \Omega$ , from (2, 2) and (2, 2) are been

If  $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_0}$ , from (2.3) and (2.8), we have

$$|\mathbf{x} - \mathbf{x}_0| < \sqrt{200A(H)e^{\chi(H)}} \le \sqrt{13200MH/c_1} = c_4$$

For C defined in (1.2), we set

$$T_{\mathbf{x}_0} = \left(\frac{C}{c_2}\right)^{1/\gamma} (|\mathbf{x}_0| + c_4 + 1).$$
(2.12)

Then we have that on  $\Omega_{\mathbf{x}_0}$ ,

$$p(\mathbf{x}, y)(T_{\mathbf{x}_0} + z)^{-\gamma} \le C(|\mathbf{x}| + 1)^{\gamma} T_{\mathbf{x}_0}^{-\gamma} \le \frac{C(|\mathbf{x}_0| + c_4 + 1)^{\gamma}}{T_{\mathbf{x}_0}^{\gamma}} = c_2.$$

Thus

$$-Q(T_{\mathbf{x}_0} + z) \ge c_2 \ge p(\mathbf{x}, y)(T_{\mathbf{x}_0} + z)^{-\gamma} \quad \text{on } \Omega_{\mathbf{x}_0}.$$
 (2.13)

When  $\mathbf{x}_0$  changes, we obtain families of auxiliary functions  $T_{\mathbf{x}_0} + z$  and domains  $\Omega_{\mathbf{x}_0}$  satisfying (2.1).

To be able to use the family of auxiliary functions, we need to investigate relative positions of the graphs of these auxiliary functions.

For two points  $\mathbf{x}_0$  and  $\mathbf{x}_1$  in  $\mathbb{R}^{n-1}$ , when  $\Omega_{\mathbf{x}_1}$  either covers the whole segment of the set  $\{(\mathbf{x}_0, y) | | y| \leq M\}$  or does not intersect with the set, from (2.3) and (2.8), we have either

$$|\mathbf{x}_1 - \mathbf{x}_0| \le \sqrt{200A(H)e^{-\chi(H)}}$$
 or  $|\mathbf{x}_1 - \mathbf{x}_0| \ge \sqrt{200A(H)e^{\chi(H)}}$ . (2.14)

Then when  $\Omega_{\mathbf{x}_1}$  covers part of some neighborhood of  $\{(\mathbf{x}_0, y) : |y| \leq M\}$ , we have

$$\sqrt{195A(H)e^{-\chi(H)}} \le |\mathbf{x}_1 - \mathbf{x}_0| \le \sqrt{205A(H)e^{\chi(H)}}.$$
(2.15)

Let  $\mathbf{x}_1$  and  $\mathbf{x}_0$  satisfy (2.15) and  $\delta_0$  be a small positive number such that  $2\delta_0 < \sqrt{195A(H)e^{-\chi(H)}}$ . If  $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_1}$  for some y and  $|\mathbf{x} - \mathbf{x}_0| \le \delta_0$ , by (2.3), (2.5) and (2.15), we have

$$\begin{split} &T_{\mathbf{x}_{1}} + z_{\mathbf{x}_{1}}(\mathbf{x}, y) \\ &\geq T_{\mathbf{x}_{1}} + A(H)e^{\chi(H)} - \{A(H)^{2}e^{2\chi(H)} - |\mathbf{x} - \mathbf{x}_{1}|\}^{1/2} \\ &\geq T_{\mathbf{x}_{1}} + A(H)e^{\chi(H)} - \{A(H)^{2}e^{2\chi(H)} - (\sqrt{195A(H)e^{-\chi(H)}} - \delta_{0})^{2}\}^{1/2} \\ &\geq T_{\mathbf{x}_{1}} + A(H)e^{\chi(H)} \\ &- \{A(H)^{2}e^{2\chi(H)} - 195A(H)e^{-\chi(H)} + 2\delta_{0}\sqrt{195A(H)e^{-\chi(H)}}\}^{1/2} \\ &\geq T_{\mathbf{x}_{1}} + A(H)e^{\chi(H)} \Big(1 - \Big(1 - \frac{195}{A(H)e^{3\chi(H)}} + \frac{2\delta_{0}\sqrt{195A(H)e^{-\chi(H)}}}{A(H)^{2}e^{2\chi(H)}}\Big)^{1/2}\Big) \\ &(\text{by the inequality } \sqrt{1 - t} \leq 1 - \frac{1}{2}t \text{ for } 0 < t < 1 \text{ and } (2.4)) \\ &\geq T_{\mathbf{x}_{1}} + A(H)e^{\chi(H)} \Big(\frac{195}{2A(H)e^{3\chi(H)}} - \frac{2\delta_{0}\sqrt{195A(H)e^{-\chi(H)}}}{2A(H)^{2}e^{2\chi(H)}}\Big) \\ &= T_{\mathbf{x}_{1}} + \frac{195}{2e^{2\chi(H)}} - \frac{\delta_{0}\sqrt{195A(H)e^{-\chi(H)}}}{A(H)e^{\chi(H)}} > T_{\mathbf{x}_{1}} + 10 - \frac{\delta_{0}\sqrt{195A(H)e^{-\chi(H)}}}{A(H)e^{\chi(H)}}. \end{split}$$

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Thus there is a  $\delta_0$  small such that for all  $|\mathbf{x} - \mathbf{x}_0| \leq \delta_0$  with  $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_1}$ , if  $\mathbf{x}_1$  and  $\mathbf{x}_0$  satisfy (2.15), we have

$$T_{\mathbf{x}_1} + z_{\mathbf{x}_1}(\mathbf{x}, y) \ge T_{\mathbf{x}_1} + 8.$$
 (2.16)

Further for all  $\mathbf{x}_0$  and  $\mathbf{x}_1$  satisfying (2.15),

$$\begin{split} T_{\mathbf{x}_{0}} + 2 &\leq T_{\mathbf{x}_{1}} + T_{\mathbf{x}_{0}} - T_{\mathbf{x}_{1}} + 2 \\ &\leq T_{\mathbf{x}_{1}} + \left(\frac{C}{c_{2}}\right)^{\frac{1}{\gamma}} (|\mathbf{x}_{0}| - |\mathbf{x}_{1}|) + 2 \\ &\leq T_{\mathbf{x}_{1}} + \left(\frac{C}{c_{2}}\right)^{\frac{1}{\gamma}} |\mathbf{x}_{1} - \mathbf{x}_{0}| + 2 \\ &\leq T_{\mathbf{x}_{1}} + \left(\frac{C}{c_{2}}\right)^{\frac{1}{\gamma}} \sqrt{205A(H)e^{\chi(H)}} + 2 \\ &\leq T_{\mathbf{x}_{1}} + \left(\frac{C}{c_{2}}\right)^{\frac{1}{\gamma}} c_{5} + 2 \end{split}$$

where  $c_5 = \sqrt{205A(H)e^{\chi(H)}}$ . Thus if we assume that C in (1.2) satisfies

$$C \le 6^{\gamma} c_5^{-\gamma} c_2, \tag{2.17}$$

we have that for all  $\mathbf{x}_0$  and  $\mathbf{x}_1$  satisfying (2.15),

$$T_{\mathbf{x}_0} + 2 \le T_{\mathbf{x}_1} + 8. \tag{2.18}$$

From (2.8) and (2.11), we can choose a number  $\delta_2(\mathbf{x}_0) > 0$  such that for all  $\mathbf{x} \in \mathbb{R}^{n-1}$  with  $|\mathbf{x}_0 - \mathbf{x}| \leq \delta_2(\mathbf{x}_0)$ , we have  $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_0}$  for all |y| < M, and

$$T_{\mathbf{x}_0} + z_{\mathbf{x}_0}(\mathbf{x}, y) \le T_{\mathbf{x}_0} + 2.$$
 (2.19)

Now if we set  $\delta_{\mathbf{x}_0} = \min\{\delta_0, \delta_2(\mathbf{x}_0)\}$ , from (2.16), (2.18) and (2.19), we have

$$T_{\mathbf{x}_0} + z_{\mathbf{x}_0}(\mathbf{x}, y) \le T_{\mathbf{x}_1} + z_{\mathbf{x}_1}(\mathbf{x}, y)$$
(2.20)

for all  $\mathbf{x}_0$  and  $\mathbf{x}_1$  satisfying (2.15),  $|\mathbf{x}_0 - \mathbf{x}| \leq \delta_{\mathbf{x}_0}$  and  $(\mathbf{x}, y) \in \Omega_{\mathbf{x}_1}$ .

Finally we define a family of open subsets of  $\Omega$  that will be needed in next section.

For each point  $(\mathbf{x}_0, y_0) \in \overline{\Omega}$ , we define an open set  $O(\mathbf{x}_0, y_0)$  as follows:

- (1) If  $(\mathbf{x}_0, y_0) \in \Omega$ , we choose a ball *B* with center  $(\mathbf{x}_0, y_0)$  and a radius less than  $\delta_{\mathbf{x}_0}$  so that  $B \subset \Omega$ . We then set  $O(\mathbf{x}_0, y_0) = B$ ;
- (2) If  $(\mathbf{x}_0, y_0) \in \partial\Omega$ , since  $\Omega$  has  $C^{2,\alpha}$  boundary, there is a ball B with center  $(\mathbf{x}_0, y_0)$  and a radius less than  $\delta_{\mathbf{x}_0}$ , such that there is a  $C^{2,\alpha}$  diffeomorphism  $\Phi$  satisfying

$$\Phi(B \cap \Omega) \subset \mathbb{R}^n_+, \quad \Phi(B \cap \partial \Omega) \subset \partial \mathbb{R}^n_+; \quad \Phi(\mathbf{x}_0, y_0) = \mathbf{0}.$$

Now we choose a domain J with  $C^3$  boundary with following properties: (a)  $J \subset \Phi(B \cap \Omega)$ ; (b)  $\partial J \cap \partial \mathbb{R}^n_+$  is a neighborhood of **0** in  $\partial \mathbb{R}^n_+$ . Certainly there are many different J's having those properties. One example is given in the Appendix II at the end of paper to illustrate how to construct such a domain J.

Now we set  $O(\mathbf{x}_0, y_0) = \Phi^{-1}(J)$ . It is easy to see that  $O(\mathbf{x}_0, y_0) \subset B \cap \Omega$ ,  $O(\mathbf{x}_0, y_0)$  has a  $C^{2,\alpha}$  boundary and  $\partial O(\mathbf{x}_0, y_0) \cap \partial \Omega$  is a neighborhood of  $(\mathbf{x}_0, y_0)$  in  $\partial \Omega$ . Let  $\Pi$  be the collection of all such open sets  $O(\mathbf{x}_0, y_0)$  defined in (1) and (2).

#### 3. A SUPER SOLUTION OF (1.1)

In this section, using the family of auxiliary functions  $T_{\mathbf{x}_0} + z$  constructed in Section 2 and an idea from [13] (that basically says that the Perron's method still works if we can find a family of appropriate auxiliary functions that works like a super solution), we will show that there is a positive function  $u \in C^2(\Omega) \cap C^0(\overline{\Omega})$ , satisfies

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} u = p(\mathbf{x}, y) u^{-\gamma} \quad \text{on } \Omega, \quad u = \tau \quad \text{on } \partial\Omega.$$

for some constant  $\tau > 0$ . Then u will be a super solution of (1.1).

If  $u = c_0 v$  for some constant  $c_0$ , v will satisfy

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} v = c_0^{-\gamma - 1} p(\mathbf{x}, y) v^{-\gamma} \quad \text{on } \Omega, \quad v = \tau/c_0 \quad \text{on } \partial\Omega.$$

Thus without loss of generality, we may assume C in (1.2) satisfying (2.17). Then all constructions in Section 2 are valid.

Let v > 0 be a function on  $\overline{\Omega}$ , for a point  $(\mathbf{x}_0, y_0) \in \overline{\Omega}$ , we define a new function  $M_{(\mathbf{x}_0, y_0)}(v)$ , called the lift of v over  $O(\mathbf{x}_0, y_0)$  as follows:

$$\begin{aligned} M_{(\mathbf{x}_0, y_0)}(v)(\mathbf{x}, y) &= v(\mathbf{x}, y) \quad \text{if} \quad (\mathbf{x}, y) \in \Omega \setminus O(\mathbf{x}_0, y_0) \\ M_{(\mathbf{x}_0, y_0)}(v)(\mathbf{x}, y) &= w(\mathbf{x}, y) \quad \text{if} \quad (\mathbf{x}, y) \in O(\mathbf{x}_0, y_0) \end{aligned}$$

where  $w(\mathbf{x}, y)$  is the positive solution of the boundary-value problem

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w = p(\mathbf{x}, y) w^{-\gamma} \quad \text{in } O(\mathbf{x}_0, y_0), \quad w = v \quad \text{on } \partial O(\mathbf{x}_0, y_0).$$
(3.1)

It is easy to see (3.1) has a unique positive solution in  $C^2(O(\mathbf{x}_0, y_0)) \cap C^0(\overline{O(\mathbf{x}_0, y_0)})$ . Indeed  $m_1 = \min\{v(\mathbf{x}, y) : (\mathbf{x}, y) \in \partial O(\mathbf{x}_0, y_0)\}$  is a sub-solution since  $p(\mathbf{x}, y)$  is non-negative,  $m_2 + T_{\mathbf{x}_0} + z_{\mathbf{x}_0}$  is a super solution by (2.1), where  $m_2 = \max\{v(\mathbf{x}, y) : (\mathbf{x}, y) \in \partial O(\mathbf{x}_0, y_0)\}$ . Then we can conclude the existence of a desired solution (for example, see [1] or [3]). Uniqueness of positive solutions of (3.1) follows from a standard argument.

Set  $\tau = (C/c_2)^{1/\gamma}c_4$  (see (2.12) for the source of the constants).

We define a class  $\Xi$  of functions as follows: a function v is in  $\Xi$  if

(1)  $v \in C^0(\overline{\Omega}), v > 0$  on  $\overline{\Omega}$  and  $v \leq \tau$  on  $\partial\Omega$ ;

- (2) For any  $(\mathbf{x}_0, y_0) \in \overline{\Omega}, v \leq M_{(\mathbf{x}_0, y_0)}(v);$
- (3)  $v \leq T_{\mathbf{x}_0} + z_{\mathbf{x}_0}$  on  $\Omega_{\mathbf{x}_0} \cap \Omega$  for any  $(\mathbf{x}_0, y_0) \in \overline{\Omega}$ .

By the following well-known lemma, it is easy to check the function  $v = \tau$  is in  $\Xi$ . Thus  $\Xi$  is not empty.

**Lemma 3.1.** Let D be a bounded domain,  $f(\mathbf{x}, y, t)$  be a  $C^1$  function that is decreasing in t. If  $w_1$ ,  $w_2$  are in  $C^2(D) \cap C^0(\overline{D})$ ,  $w_1 \leq w_2$  on  $\partial D$ , and

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w_1 \le f(\mathbf{x}, y, w_1) \quad in \ D,$$
$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w_2 \ge f(\mathbf{x}, y, w_2) \quad in \ D$$

then  $w_1 \leq w_2$  on D.

Now we set

$$u(\mathbf{x}, y) = \sup_{v \in \Xi} v(\mathbf{x}, y), \quad (\mathbf{x}, y) \in \overline{\Omega}.$$

We will show that u is in  $C^2(\Omega) \cap C^0(\overline{\Omega})$  and satisfies

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} u = p(\mathbf{x}, y) u^{-\gamma} \quad \text{on } \Omega; \quad u = \tau \quad \text{on } \partial\Omega.$$

First we need some lemmas.

**Lemma 3.2.** If  $0 < v_1 \le v_2$ , then  $M_{(\mathbf{x}_0, y_0)}(v_1) \le M_{(\mathbf{x}_0, y_0)}(v_2)$  for any  $(\mathbf{x}_0, y_0) \in \overline{\Omega}$ . *Proof.* Let  $w_1, w_2$  be the positive solutions for the following problems

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w_k = p(\mathbf{x}, y) w_k^{-\gamma} \quad \text{in } O(\mathbf{x}_0, y_0)$$
$$w_k = v_k \quad \text{on } \partial O(\mathbf{x}_0, y_0), \quad k = 1, 2.$$

Since  $w_1 = v_1 \leq v_2 = w_2$  on  $\partial O(\mathbf{x}_0, y_0)$ ,  $p(\mathbf{x}, y)t^{-\gamma}$  is decreasing on t, from lemma 1, we see  $w_1 \leq w_2$  on  $O(\mathbf{x}_0, y_0)$ . On  $\Omega \setminus O(\mathbf{x}_0, y_0)$ ,  $M_{(\mathbf{x}_0, y_0)}(v_1) = v_1$ ,  $M_{(\mathbf{x}_0, y_0)}(v_2) = v_2$ . Thus  $M_{(\mathbf{x}_0, y_0)}(v_1) \leq M_{(\mathbf{x}_0, y_0)}(v_2)$ .

**Lemma 3.3.** If  $v_1 \in \Xi$ ,  $v_2 \in \Xi$ , then  $\max\{v_1, v_2\} \in \Xi$ .

*Proof.* If  $v_1 \in \Xi$ ,  $v_2 \in \Xi$ , it is clear that  $\max\{v_1, v_2\} \in C^0(\overline{\Omega})$ ,  $\max\{v_1, v_2\} > 0$  on  $\overline{\Omega}$  and  $\max\{v_1, v_2\} \leq \tau$  on  $\partial\Omega$ . It is also clear that  $\max\{v_1, v_2\} \leq T_{\mathbf{x}_0} + z_{\mathbf{x}_0}$  on  $\Omega_{\mathbf{x}_0} \cap \Omega$  for any  $(\mathbf{x}_0, y_0) \in \overline{\Omega}$ . Since

$$v_1 \le \max\{v_1, v_2\}, \quad v_2 \le \max\{v_1, v_2\}$$

we have (by lemma 2) that for any  $(\mathbf{x}_0, y_0) \in \overline{\Omega}$ ,

 $M_{(\mathbf{x}_0, y_0)}(v_1) \le M_{(\mathbf{x}_0, y_0)}(\max\{v_1, v_2\}), \quad M_{(\mathbf{x}_0, y_0)}(v_2) \le M_{(\mathbf{x}_0, y_0)}(\max\{v_1, v_2\}).$ Since  $v_1 \in \Xi$  and  $v_2 \in \Xi$  imply

$$v_1 \le M_{(\mathbf{x}_0, y_0)}(v_1), \quad v_2 \le M_{(\mathbf{x}_0, y_0)}(v_2),$$

we have

$$\max\{v_1, v_2\} \le M_{(\mathbf{x}_0, y_0)}(\max\{v_1, v_2\})$$

Thus  $\max\{v_1, v_2\} \in \Xi$ .

**Lemma 3.4.** If  $v \in \Xi$ , then  $M_{(\mathbf{x}_0, y_0)}(v) \in \Xi$  for any  $(\mathbf{x}_0, y_0) \in \overline{\Omega}$ .

*Proof.* By the definition of  $M_{(\mathbf{x}_0,y_0)}(v)$ , it is clear that  $M_{(\mathbf{x}_0,y_0)}(v) > 0$  on  $\overline{\Omega}$ ,  $M_{(\mathbf{x}_0,y_0)}(v) \in C^0(\overline{\Omega})$  and  $M_{(\mathbf{x}_0,y_0)}(v) \leq \tau$  on  $\partial\Omega$ .

For any  $(\mathbf{x}^*, y^*) \in \overline{\Omega}$ , we first show that

$$M_{(\mathbf{x}_0, y_0)}(v)(\mathbf{x}, y) \le M_{(\mathbf{x}^*, y^*)}(M_{(\mathbf{x}_0, y_0)}(v))(\mathbf{x}, y).$$
(3.2)

We only need to prove that (3.2) is true for  $(\mathbf{x}, y) \in O(\mathbf{x}^*, y^*)$ . Since

$$v \le M_{(\mathbf{x}_0, y_0)}(v)$$

we have (by lemma 2)

$$M_{(\mathbf{x}^*, y^*)}(v) \le M_{(\mathbf{x}^*, y^*)}(M_{(\mathbf{x}_0, y_0)}(v))$$

Then from  $v \leq M_{(\mathbf{x}^*, y^*)}(v)$  (by lemma 2 again), we have

$$v \le M_{(\mathbf{x}^*, y^*)}(M_{(\mathbf{x}_0, y_0)}(v)).$$

Thus for  $(\mathbf{x}, y) \in O(\mathbf{x}^*, y^*) \setminus O(\mathbf{x}_0, y_0)$ ,

$$M_{(\mathbf{x}_0, y_0)}(v)(\mathbf{x}, y) = v(\mathbf{x}, y) \le M_{(\mathbf{x}^*, y^*)}(M_{(\mathbf{x}_0, y_0)}(v))(\mathbf{x}, y).$$
(3.3)

That is, (3.2) is true on  $O(\mathbf{x}^*, y^*) \setminus O(\mathbf{x}_0, y_0)$ , Now for  $\Omega_1 = O(\mathbf{x}^*, y^*) \cap O(\mathbf{x}_0, y_0)$ , if we set

$$M_{(\mathbf{x}_0,y_0)}(v) = w_1, \quad M_{(\mathbf{x}^*,y^*)}(M_{(\mathbf{x}_0,y_0)}(v)) = w_2$$

we have

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w_1 = p(\mathbf{x}, y) w_1^{-\gamma} \quad \text{on } \Omega_1,$$
$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w_2 = p(\mathbf{x}, y) w_2^{-\gamma} \quad \text{on } \Omega_1.$$

On  $\partial\Omega_1$ ,  $w_1 \leq w_2$  on  $O(\mathbf{x}^*, y^*) \cap \partial O(\mathbf{x}_0, y_0)$  by (3.3) and  $w_1 \leq w_2$  on  $\partial O(\mathbf{x}^*, y^*) \cap O(\mathbf{x}_0, y_0)$  since (3.2) is true on  $\Omega \setminus O(\mathbf{x}^*, y^*)$ . Then lemma 1 implies  $w_1 \leq w_2$  on  $\Omega_1$ . Thus (3.2) is true on  $O(\mathbf{x}^*, y^*) \cap O(\mathbf{x}_0, y_0)$  and on  $O(\mathbf{x}^*, y^*)$ .

Now we prove that  $M_{(\mathbf{x}_0, y_0)}(v) \leq T_{\mathbf{x}_1} + z_{\mathbf{x}_1}$  on  $\Omega_{\mathbf{x}_1} \cap \Omega$  for all  $(\mathbf{x}_1, y_1) \in \overline{\Omega}$ .

By the definition of  $M_{(\mathbf{x}_0, y_0)}(v)$ , we only need to consider the graph of the function  $M_{(\mathbf{x}_0, y_0)}(v)$  over  $O(\mathbf{x}_0, y_0)$ . If  $O(\mathbf{x}_0, y_0)$  is covered completely by  $\Omega_{\mathbf{x}_1}$ , since  $v \leq T_{\mathbf{x}_1} + z_{\mathbf{x}_1}$  and  $T_{\mathbf{x}_1} + z_{\mathbf{x}_1}$  satisfies (2.1),  $T_{\mathbf{x}_1} + z_{\mathbf{x}_1}$  is a super solution of (3.1) on  $O(\mathbf{x}_0, y_0)$ . Then Lemma 3.1 implies  $M_{(\mathbf{x}_0, y_0)}(v) \leq T_{\mathbf{x}_1} + z_{\mathbf{x}_1}$  on  $O(\mathbf{x}_0, y_0)$ . In the case that  $O(\mathbf{x}_0, y_0)$  does not intersect with  $\Omega_{\mathbf{x}_1}$ , the conclusion is trivial. Now we consider the case that  $O(\mathbf{x}_0, y_0)$  is partially covered by  $\Omega_{\mathbf{x}_1}$ . Since  $O(\mathbf{x}_0, y_0)$  is covered by  $\Omega_{\mathbf{x}_0}$ , we always have

$$M_{(\mathbf{x}_0, y_0)}(v) \le T_{\mathbf{x}_0} + z_{\mathbf{x}_0} \quad \text{on } O(\mathbf{x}_0, y_0).$$
 (3.4)

Then by the choice of  $\delta_{\mathbf{x}_0}$ ,  $O(\mathbf{x}_0, y_0)$ , and the fact that  $O(\mathbf{x}_0, y_0) \cap T_{\mathbf{x}_1}$  is not empty, we have that  $\mathbf{x}_0$  and  $\mathbf{x}_1$  satisfy (2.15), and for all  $(\mathbf{x}, y) \in O(\mathbf{x}_0, y_0) \cap \Omega_{\mathbf{x}_1}$ ,  $|\mathbf{x}_0 - \mathbf{x}| \leq \delta_{\mathbf{x}_0}$ . Then by (2.20), the graph of  $T_{\mathbf{x}_0} + z_{\mathbf{x}_0}$  over  $O(\mathbf{x}_0, y_0) \cap \Omega_{\mathbf{x}_1}$  is under the graph of  $T_{\mathbf{x}_1} + z_{\mathbf{x}_1}$ . Thus the conclusion follows from (3.4).

Now we are ready to prove that u has the desired properties.

Let  $(\mathbf{x}_0, y_0) \in \overline{\Omega}$ . By the definition of  $u(\mathbf{x}_0, y_0)$ , there is a sequence of functions  $v_k$  in  $\Xi$  such that

$$u(\mathbf{x}_0, y_0) = \lim_{k \to \infty} v_k(\mathbf{x}_0, y_0).$$

By lemma 3 and the fact that  $v = \tau$  is in  $\Xi$ , replacing  $v_k$  by  $\max\{v_k, \tau\}$  if it is necessary, we may assume that  $v_k \ge \tau$  on  $\Omega$ . We replace  $v_k$  by  $M_{(\mathbf{x}_0, y_0)}(v_k)$ . Then we have a sequence of functions  $w_k$  satisfying

$$u(\mathbf{x}_{0}, y_{0}) = \lim_{k \to \infty} w_{k}(\mathbf{x}_{0}, y_{0}),$$
$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w_{k} = p(\mathbf{x}, y) w_{k}^{-\gamma} \quad on \quad O(\mathbf{x}_{0}, y_{0}),$$
$$w_{k} = v_{k} \quad on \quad \partial O(\mathbf{x}_{0}, y_{0}).$$

Since for all k,

$$\tau \leq v_k \leq w_k \leq T_{\mathbf{x}_0} + z_{\mathbf{x}_0} \quad \text{on } O(\mathbf{x}_0, y_0).$$

By [7, Theorem 9.11] and an approximation of the boundary value by smooth functions, we see that there is a subsequence of  $w_k$ , for convenience still denoted by  $w_k$ , converges to a  $C^2(O(\mathbf{x}_0, y_0)) \cap C^0(\overline{O(\mathbf{x}_0, y_0)})$  function w(x) in  $C^2(O(\mathbf{x}_0, y_0)) \cap C^0(\overline{O(\mathbf{x}_0, y_0)})$ . Thus w(x) satisfies

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w = p(\mathbf{x}, y) w^{-\gamma} \quad on \quad O(\mathbf{x}_0, y_0)$$

and  $u(\mathbf{x}_0, y_0) = w(\mathbf{x}_0, y_0)$ . We claim that u = w on  $O(\mathbf{x}_0, y_0)$ . Indeed, if there is another point  $(\mathbf{x}_2, y_2) \in O(\mathbf{x}_0, y_0)$  such that  $u(\mathbf{x}_2, y_2)$  is not equal to  $w(\mathbf{x}_2, y_2)$ , then  $u(\mathbf{x}_2, y_2) > w(\mathbf{x}_2, y_2)$ . Then there is a function  $u_0 \in \Xi$ , such that

 $w(\mathbf{x}_2, y_2) < u_0(\mathbf{x}_2, y_2) \le u(\mathbf{x}_2, y_2).$ 

Now the sequence  $\max\{u_0, M_{(\mathbf{x}_0, y_0)}(v_k)\}$  satisfying

$$v_k \le \max\{u_0, M_{(\mathbf{x}_0, y_0)}(v_k)\} \le u.$$

Then similar to the way we obtain w,  $M_{(\mathbf{x}_0, y_0)}(\max\{u_0, M_{(\mathbf{x}_0, y_0)}(v_k)\})$  will produce a function  $w_1$  satisfying

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w_1 = p(\mathbf{x}, y) w_1^{-\gamma} \quad \text{on } O(\mathbf{x}_0, y_0),$$
  
$$w \le w_1 \quad on \quad O(\mathbf{x}_0, y_0), \quad w(\mathbf{x}_2, y_2) < u_0(\mathbf{x}_2, y_2) \le w_1(\mathbf{x}_2, y_2),$$
  
$$w(\mathbf{x}_0, y_0) = w_1(\mathbf{x}_0, y_0) = u(\mathbf{x}_0, y_0).$$

That is,  $w_1(\mathbf{x}, y) - w(\mathbf{x}, y)$  is non-negative, not identically zero on  $O(\mathbf{x}_0, y_0)$  and achieves its minimum value zero inside  $O(\mathbf{x}_0, y_0)$ . However, from the equations satisfied by w and  $w_1$ , we have that on  $O(\mathbf{x}_0, y_0)$ ,

$$-\sum_{i,j=1}^{n} a_{i,j}(\mathbf{x}, y) D_{ij}(w_1 - w) + \gamma p(\mathbf{x}, y)(w + \theta(w_1 - w))^{-\gamma - 1}(w_1 - w) = 0$$

for some continuous function  $\theta$ . Then by the standard maximum principle (for example, see [7, Theorem 3.5]), we get a contradiction. Thus u = w on  $O(\mathbf{x}_0, y_0)$ . Therefore  $u \in C^2(\Omega)$  and

$$-\sum_{i,j=1}^{n} a_{i,j}(\mathbf{x}, y) D_{ij} u = p(\mathbf{x}, y) u^{-\gamma} \quad \text{on } \Omega.$$

When  $(\mathbf{x}_0, y_0) \in \partial\Omega$ ,  $\partial O(\mathbf{x}_0, y_0) \cap \partial\Omega$  is a neighborhood of  $(\mathbf{x}_0, y_0)$  in  $\partial\Omega$ . Since  $\max\{\tau, v_k\} = \tau$  on  $\partial\Omega$ ,  $u = \tau$  on  $\partial\Omega$  and  $w = \tau$  on  $\partial O(\mathbf{x}_0, y_0) \cap \partial\Omega$ . Since w is continuous up to the boundary of  $O(\mathbf{x}_0, y_0)$ , u is continuous on  $\partial O(\mathbf{x}_0, y_0) \cap \partial\Omega$  from inside  $O(\mathbf{x}_0, y_0)$ . Thus  $u \in C^0(\overline{\Omega})$  and  $u = \tau$  on  $\partial\Omega$ .

### 4. Proof of Existence

Using the super solution u constructed in Section 3, we can prove the existence of a positive solution of (1.1) exactly in the same way as that in [8] (the generality of the principal term of the elliptic operator will not cause any extra difficulty). We just sketch the proof here.

Since  $\Omega$  is an unbounded domain with  $C^{2,\alpha}$  boundary, we can choose a sequence of subdomains of  $\Omega$ , denoted by  $\Omega_m$ ,  $m = 1, 2, 3, \ldots$ , such that

(1)  $\Omega_m \subset \Omega_{m+1} \subset \Omega$  for all m;

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- (2)  $\cup \Omega_m = \Omega;$
- (3) each  $\Omega_m$  is a bounded domain with  $C^{2,\alpha}$  boundary;
- (4)  $dist(0, \partial \Omega \setminus \partial \Omega_m) \to \infty$  as  $m \to \infty$ .

We can find a number  $\mu$ , such that for each large m, the eigenvalue problem

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w = \lambda(\mu p(\mathbf{x}, y)) w \quad \text{on } \Omega_m, \quad w = 0 \quad \text{on } \partial \Omega_m$$

has a first eigenvalue  $\lambda_1 < 1$  with its first eigenfunction  $\phi_m$ . We can assume  $\max \phi_m = 1$ . Choose  $\delta_m$  such that  $\delta_m \leq \frac{1}{2}\tau$  and

$$up(\mathbf{x}, y)t \le p(\mathbf{x}, y)t^{-\gamma}$$
 for  $(\mathbf{x}, y) \in \Omega_m$ ,  $0 < t < \delta_m$ 

Then

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w = p(\mathbf{x}, y) w^{-\gamma} \quad \text{on } \Omega_m, \quad w = 0 \quad \text{on } \partial\Omega_m$$
(4.1)

has a pair of super and sub solutions  $u(\mathbf{x}, y), \delta_m \phi_m$ . Thus (4.1) has a solution  $w_m$ that can be proved to satisfy

$$\begin{aligned} 0 < w_m < u \quad \text{on } \Omega_m, \\ \frac{1}{2} \delta_s \phi_s \leq w_m \quad \text{on } \Omega_m \end{aligned}$$

for all m > s. Finally we take limit of  $w_m$  to get a desired solution.

## 5. The General Case

Now we consider the boundary-value problem

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} u = g(\mathbf{x}, y, u) \quad \text{on } \Omega, \quad u = 0 \quad \text{on } \partial\Omega.$$
(5.1)

In addition to the assumptions on  $(a_{ij})$  and  $\Omega$  given at the beginning of the paper, we assume the following conditions.

(1) Trace  $a_{ij}$  = 1;

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- (2) There is a constant  $c_1 > 0$  such that  $a_{nn} \ge c_1$  on  $\overline{\Omega}$ ;
- (3) There is a family of increasing positive functions T = T(t) satisfying (with  $T_{\mathbf{x}} = T(|\mathbf{x}|))$ 

  - (a)  $|T_{\mathbf{x}_0} T_{\mathbf{x}}| \leq |\mathbf{x}_0 \mathbf{x}|/c_5;$ (b)  $g(\mathbf{x}, y, T_{\mathbf{x}_0} + z_{\mathbf{x}_0}) \leq c_2$  on  $\Omega_{\mathbf{x}_0}$  ( $\Omega_{\mathbf{x}_0}, z_{\mathbf{x}_0}$  and  $c_2$  are defined in Section 2);
- (4)  $g(\mathbf{x}, y, t)$  is non-negative, in  $C^1(\overline{\Omega} \times \mathbb{R}^n_+)$  and decreasing on t.
- (5)  $\lim_{t \to 0^+} \frac{g(\mathbf{x}, y, t)}{t} \geq v_0(\mathbf{x}, y)$  uniformly for  $(\mathbf{x}, y)$  in any bounded subset on  $\overline{\Omega}$ , where  $v_0(\mathbf{x}, y)$  is a non-negative function satisfying that when m is large, the eigenvalue problem

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w = \lambda v_0(\mathbf{x}, y) w \quad on \quad \Omega_m, \quad u = 0 \quad on \quad \partial \Omega_m.$$

has a first eigenvalue  $\lambda_1 < 1$ .

Then we have the following conclusion.

**Theorem 5.1.** Under the assumptions (1)-(5), (5.1) has a positive solution.

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*Proof.* We just sketch the proof here. Assumptions (1)–(3) assure that  $T_{\mathbf{x}_0} + z_{\mathbf{x}_0}$  is a family of auxiliary functions satisfying (2.1) on  $\Omega_{\mathbf{x}_0}$  and the graphs of these function have the desired relative positions as discussed in Section 2.

Assumption (4) assures that lemma 1 can be applied and the boundary value problem

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w = g(\mathbf{x}, y, w) \quad \text{in } O(\mathbf{x}_0, y_0), \quad w = v \text{ on } \partial O(\mathbf{x}_0, y_0)$$
(5.2)

has a unique positive solution for each positive function v on  $\overline{\Omega}$ . Thus the lift  $M_{(\mathbf{x}_0, y_0)}$  and the class  $\Xi$  of functions are well defined. The proofs of lemmas 2-4 and the existence of the super solution u are the same.

Finally the assumption (5) assures that the proof in Section 4 still works out like that in [8].  $\Box$ 

Now we apply theorem 3 to the case that  $g(\mathbf{x}, y, u) = p(\mathbf{x}, y)e^{-u}$ . We consider a modified problem:

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} u = \frac{p(\mathbf{x}, y) e^{-c_5 u}}{c_5} \quad \text{on } \Omega, \quad u = 0 \quad \text{on } \partial\Omega.$$
(5.3)

If we can find a positive solution u of (5.3), then  $c_5 u$  is a positive solution of (1.7). For (5.3), we set

$$T(t) = \frac{1}{c_5}(t+c_4) + \frac{1}{c_5}\ln\frac{C}{c_2c_5} + A$$

where A is a positive constant such that  $\frac{1}{c_5} \ln \frac{C}{c_5} + A > 1$ , C is defined in (1.5) and  $c_2$ ,  $c_4$ ,  $c_5$  are defined in Section 2. Then T(t) is increasing and the assumption (3)(a) is obviously satisfied for  $T_{\mathbf{x}} = T(|\mathbf{x}|)$ . For (3)(b), on  $\Omega_{\mathbf{x}_0}$ ,

$$\frac{1}{c_5} p(\mathbf{x}, y) e^{-c_5(T_{\mathbf{x}_0} + z_{\mathbf{x}_0})} \leq \frac{C}{c_5} e^{|\mathbf{x}|} e^{-c_5 T_{\mathbf{x}_0}} \\
\leq \frac{C}{c_5} e^{|\mathbf{x}_0| + c_4} e^{-c_5 T_{\mathbf{x}_0}} \\
= \frac{C}{c_5} e^{|\mathbf{x}_0| + c_4} e^{-|\mathbf{x}_0| - c_4 - \ln \frac{C}{c_2 c_5} - c_5 A} \\
= c_2 e^{-c_5 A} < c_2 .$$

Assumption (4) is obvious. For assumption (5), let  $\lambda_1$  be the first eigenvalue of the eigenvalue problem ( $\Omega_1$  is defined in Section 4)

$$-\sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij} w = \lambda p(\mathbf{x}, y) w \quad \text{on } \Omega_1, \quad w = 0 \quad \text{on } \partial \Omega_1.$$

Set  $v_0 = 2\lambda_1 p(\mathbf{x}, y)$ , then it is easy to see that

$$\lim_{t \to 0^+} \frac{p(\mathbf{x}, y)e^{-t}}{t} \ge v_0(\mathbf{x}, y) \quad \text{uniformly on } \overline{\Omega}.$$

It is also easy to see that  $v_0$  has the desired property. Thus assumption (5) is satisfied. Therefore we can conclude that Theorem 1.22 is true.

# 6. APPENDIX I: VERIFICATIONS OF (2.3), (2.4), (2.6), (2.7)

In this appendix, we verify (2.3)-(2.4) and (2.6)-(2.7) used in Section 2. All the

computations here are copied from [10]. Set  $\Phi_1(\rho) = \rho^{-2}$  if  $0 < \rho < 1$  and  $\Phi_1(\rho) = \frac{11}{c_1}$  if  $\rho \ge 1$ , and define a function  $\chi$ by

$$\chi(\alpha) = \int_{\alpha}^{\infty} \frac{d\rho}{\rho^3 \Phi_1(\rho)} \quad \text{for } \alpha > 0.$$

It is clear that  $\chi(\alpha)$  is a decreasing function with range  $(0, \infty)$ . Let  $\eta$  be the inverse of  $\chi$ . Then  $\eta$  is a positive, decreasing function with range  $(0, \infty)$ . Let  $c^* = 11/c_1$ . For  $\alpha > 1$ , we have

$$\chi(\alpha) = \int_{\alpha}^{\infty} \frac{d\rho}{\rho^3 \Phi_1(\rho)} = \int_{\alpha}^{\infty} \frac{d\rho}{c^* \rho^3} = \frac{1}{2c^*} \alpha^{-2}.$$
 (6.1)

Thus

$$\eta(\beta) = (2c^*\beta)^{-\frac{1}{2}} \quad for \quad 0 < \beta < (2c^*)^{-1}.$$
(6.2)

Let  $H \ge 2$ . Since  $\eta(\chi(H)) = H$  and  $\eta$  is decreasing, we have  $\eta(\beta) > H$  for  $0 < \beta < \chi(H)$ . We define a function A(H) by

$$A(H) = 2M (\int_{1}^{e^{\chi(H)}} \eta(\ln t) dt)^{-1}.$$
 (6.3)

For the rest of this article, we set a = A(H) and define

$$h_a(r) = \int_r^{ae^{\chi(H)}} \eta(\ln\frac{t}{a}) dt \quad \text{for } a \le r \le ae^{\chi(H)}.$$
(6.4)

Then

$$h_a(ae^{\chi(H)}) = 0, \quad h_a(a) = h_{A(H)}(A(H)) = 2M.$$
 (6.5)

For  $a < r \leq a e^{\chi(H)}$ ,

$$h'_{a}(r) = -\eta(\ln\frac{r}{a}) < 0, \ |h'_{a}(r)| > H, \quad h''_{a}(r) = \frac{1}{r}(\eta(\ln\frac{r}{a}))^{3}\Phi_{1}(\eta(\ln\frac{r}{a})).$$
(6.6)

Thus for  $a < r \leq a e^{\chi(H)}$ ,

$$\frac{h_a''(r)}{(h_a'(r))^2} = -\frac{h_a'(r)}{r} \Phi_1(-h_a'(r)).$$
(6.7)

Let  $h_a^{-1}$  be the inverse of  $h_a$ . Then  $h_a^{-1}$  is decreasing and

$$h_a^{-1}(0) = A(H)e^{\chi(H)}, \quad h_a^{-1}(2M) = A(H).$$
 (6.8)

Thus we have the first half of (2.3). Further for  $-M \leq y \leq M$ ,

$$(h_a^{-1})'(y+M) = \frac{1}{h_a'(h_a^{-1}(y+M))}$$

$$\begin{split} (h_a^{-1})''(y+M) &= (\frac{1}{h_a'(h_a^{-1}(y+M))})' \\ &= -\frac{h_a''(h_a^{-1}(y+M))(h_a^{-1})'(y+M)}{(h_a'(h_a^{-1}(y+M)))^2} \\ &= -\frac{h_a''(h_a^{-1}(y+M))}{(h_a'(h_a^{-1}(y+M)))^3} \\ &= \frac{1}{h_a^{-1}(y+M)} \Phi_1(-h_a'(h_a^{-1}(y+M))). \end{split}$$

Thus

$$(h_a^{-1})''(y+M)h_a^{-1}(y+M) = \Phi_1(-h_a'(h_a^{-1}(y+M))).$$
(6.9)

Now we choose an  $H_0 > 2$  such that for  $H \ge H_0$ ,

$$H_0 > \frac{1}{\sqrt{2c^*}} + 3M + 4 + \frac{24nc_1K}{M}, \quad \sqrt{\frac{4K}{A(H)e^{\chi(H)}}} \le \frac{1}{\sqrt{2}}.$$
 (6.10)

Then we have (2.4). For  $H > H_0$ , by (6.1), (6.2), we have

$$\begin{aligned} A(H)^{-1} &= (2M)^{-1} \int_{1}^{e^{\chi(H)}} \eta(\ln t) dt \\ &= (2M)^{-1} \int_{0}^{\chi(H)} \eta(m) e^{m} dm \\ &= (2M)^{-1} \int_{0}^{\chi(H)} \frac{e^{m}}{\sqrt{2c^{*}m}} dm \end{aligned}$$

From

$$\frac{1}{\sqrt{2c^*}} \int_0^{\chi(H)} \frac{1}{\sqrt{m}} dm \le \int_0^{\chi(H)} \frac{e^m}{\sqrt{2c^*m}} dm \le \frac{e^{\chi(H)}}{\sqrt{2c^*}} \int_0^{\chi(H)} \frac{1}{\sqrt{m}} dm \,,$$

we have

$$\frac{1}{c^*H} = \frac{2\sqrt{\chi(H)}}{\sqrt{2c^*}} \le \int_0^{\chi(H)} \frac{e^m}{\sqrt{2c^*m}} dm \le \frac{2e^{\chi(H)}\sqrt{\chi(H)}}{\sqrt{2c^*}} = \frac{e^{\frac{1}{2c^*H^2}}}{c^*H}.$$

Thus

$$2Mc^*H \ge A(H) \ge 2Mc^*He^{-\chi(H)} = 2Mc^*He^{-\frac{1}{2c^*H^2}}.$$
(6.11)

Thus we have the second half of (2.3) since  $c^* = 11/c_1$ . For  $\mathbf{x}_0 \in \mathbb{R}^{n-1}$ , and a fixed constant K, we define a domain  $\Omega_{\mathbf{x}_0,H,K}$  in  $(\mathbf{x}, y)$  space by (2.8) and define a function  $z = z(\mathbf{x}, y)$  by (2.5). Since  $h_a^{-1}(y + M) \ge 0$  for  $|y| \le M$ ,  $(\mathbf{x}_0, y) \in \Omega_{\mathbf{x}_0,H,K}$  for |y| < M. Further it is clear that the function  $z = z(\mathbf{x}, y) \text{ is well defined on } \Omega_{\mathbf{x}_0, H, K}.$ Now we verify the first half of (2.7), on  $\partial \Omega_{\mathbf{x}_0, H, K} \cap \{(\mathbf{x}, y) : |y| < M\},$ 

$$|\mathbf{x} - \mathbf{x}_0| = \sqrt{\frac{2K}{A(H)e^{\chi(H)}}}h^{-1}(y+M);$$

then from (6.8), we have

$$\begin{split} z &= A(H)e^{\chi(H)} - \{(h_a^{-1}(y+M))^2 - |\mathbf{x} - \mathbf{x}_0|^2\}^{1/2} \\ &= A(H)e^{\chi(H)} - h_a^{-1}(y+M)(1 - \frac{2K}{A(H)e^{\chi(H)}})^{1/2} \\ &\geq A(H)e^{\chi(H)} - A(H)e^{\chi(H)}(1 - \frac{2K}{A(H)e^{\chi(H)}})^{1/2} \\ &\geq A(H)e^{\chi(H)}(1 - (1 - \frac{2K}{2A(H)e^{\chi(H)}})) = K. \end{split}$$

Here we have used (6.10) and the fact that  $\sqrt{1-t} \leq 1 - \frac{1}{2}t$  for 0 < t < 1. For the second half of (2.7), since  $h_a^{-1}(r)$  and  $\eta$  are decreasing functions, we have

$$\frac{-1}{h'_a(h_a^{-1}(y+M))} = \frac{1}{\eta(\ln(\frac{1}{a}h_a^{-1}(y+M)))} \\
\leq \frac{1}{\eta(\ln e^{\chi(H)})} \\
= \frac{1}{\eta(\chi(H))} = \frac{1}{H}, \quad \text{for } |y| \leq -M.$$
(6.12)

Then by (2.5), we have

$$\frac{\partial z}{\partial y}(\mathbf{x}_0, y) = \frac{-1}{h_a'(h_a^{-1}(y+M))} \le \frac{1}{H}, \quad \text{for } |y| \le -M.$$

Now the second half of (2.7) follows from this and

$$z(\mathbf{x}_0, -M) = A(H)e^{\chi(H)} - h_a^{-1}(0) = A(H)e^{\chi(H)} - A(H)e^{\chi(H)} = 0.$$

For (2.6), we set  $S = \{(h_a^{-1}(y+M))^2 - |\mathbf{x} - \mathbf{x}_0|^2\}^{1/2}$ . Then we have that for  $1 \le i \le n-1$ ,

$$\frac{\partial z}{\partial x_i} = \frac{1}{S}(x_i - x_{0i}), \quad \frac{\partial z}{\partial y} = -\frac{1}{S}h_a^{-1}(h_a^{-1})'.$$

By (6.10) and (6.11), on  $\Omega_{\mathbf{x}_0,H,K}$ , we have

$$\frac{1}{2}h_a^{-1}(y+M) \le S \le h_a^{-1}(y+M),$$

and

$$\frac{|\mathbf{x} - \mathbf{x}_0|}{S} \le 2\left(\frac{2K}{A(H)e^{\chi(H)}}\right)^{1/2} \le 2\left(\frac{2K}{2Mc^*H}\right)^{1/2}.$$

Thus, by (6.12), we have

$$|\frac{\partial z}{\partial x_i}| \le 2(\frac{c_1 K}{MH})^{1/2}, \quad |\frac{\partial z}{\partial y}| \le \frac{h_a^{-1}(y+M)}{S|h_a'(h_a^{-1}(y+M)|} \le \frac{2}{H}.$$
 (6.13)

Hence from (6.10), and the assumption that  $\operatorname{Trace} a_{ij} = 1$  (hence all eigenvalues of  $(a_{ij})$  are less than or equal to 1), we have

$$\left|\sum_{i,j=1}^{n} a_{ij} \frac{\partial z}{\partial x_i} \frac{\partial z}{\partial x_j}\right| \le |Dz|^2 \le 1.$$
(6.14)

Now we have  $\boldsymbol{n}$ 

$$Qz = \sum_{i,j=1}^{n} a_{ij}(\mathbf{x}, y) D_{ij}z$$
  
=  $\frac{1}{S} \sum_{i=1}^{n-1} a_{ii} + \frac{1}{S^3} \sum_{i,j=1}^{n-1} a_{ij}(x_i - x_i^0)(x_j - x_j^0) - \frac{1}{S^3} \sum_{i=1}^{n-1} a_{in}(x_i - x_i^0)h_a^{-1}(h_a^{-1})'$   
 $- \frac{1}{S} a_{nn}((h_a^{-1})^2 + h_a^{-1}(h_a^{-1})'') + \frac{1}{S^3} a_{nn}(h_a^{-1})^2((h_a^{-1})')^2$   
 $= \frac{1}{S} \left\{ 1 - a_{nn} + \sum_{i,j=1}^{n} a_{ij} \frac{\partial z}{\partial x_i} \frac{\partial z}{\partial x_j} - a_{nn}((h_a^{-1})^2 + h_a^{-1}(h_a^{-1})'') \right\} \text{ (since } a_{nn} > 0)$   
 $\leq \frac{1}{S} \left\{ 1 + \sum_{i,j=1}^{n} a_{ij} \frac{\partial z}{\partial x_i} \frac{\partial z}{\partial x_j} - a_{nn}h_a^{-1}(h_a^{-1})'' \right\}.$ 

By (2.2), (6.9), (6.11) and (6.14)) the above expression is bounded by

$$\frac{-9}{S} \le \frac{-9}{h_a^{-1}(y+M)} \le \frac{-9}{A(H)e^{\chi(H)}} \le \frac{-9}{2Mc^*He^{\frac{1}{2c^*H^2}}} \le \frac{-3c_1}{22eMH}.$$

This shows (2.6).

### 7. Appendix II: A Construction of the Domain J

In this part, we give a construction of the domain J used at the end of Section 2 in the definition of  $\Pi.$  Let

$$\mathbb{R}^{n}_{+} = \{(y_{1}, y_{2}, \dots, y_{n}) | y_{n} > 0\},\$$
$$J_{1} = \{(y_{1}, y_{n}) : y_{1} = \pm 1, |y_{n}| \le 1 \text{ or } y_{n} = \pm 1, |y_{1}| \le 1\}$$

That is,  $J_1$  is a square with side length 2 and center (0,0) in  $(y_1, y_n)$  plane. In polar coordinate we can write  $\partial J_1$  as

$$(y_1, y_n) = (k(\theta) \cos \theta, k(\theta) \sin \theta), \quad 0 \le \theta \le 2\pi,$$

where  $k(\theta)$  is a positive, continuous, periodic function of period  $2\pi$ ,  $k(\theta)$  is  $C^{\infty}$ except at  $\theta = \pm \frac{\pi}{4}, \pm \frac{3\pi}{4}$ . Then we can smooth out  $k(\theta)$  near those points to get a function  $k_1(\theta)$  such that  $k_1(\theta)$  is a positive,  $C^{\infty}$ , periodic function of period  $2\pi$ ,  $k_1(\theta) = k(\theta)$  except in some small neighborhoods of  $\theta = \pm \frac{\pi}{4}, \pm \frac{3\pi}{4}$ , and  $k_1(\theta) \le k(\theta)$ for all  $\theta$ . Indeed we can modify  $k(\theta)$  as follows:

Let s(t) be a  $C^{\infty}$  function satisfying

- (1) s(t) = 0 if  $t \le 1$ ;
- (2)  $0 < s(t) \le \frac{1}{8}$  if  $1 < t \le 2$ ; (3)  $s(t) \ge 0$  for all t;
- (4) s(t) = 1 if  $t \ge 4$ .

Fixed a positive constant  $\epsilon < \frac{\pi}{100}$ . Near  $\theta = \frac{\pi}{4}$ , we define

$$k_1(\theta) = k(\theta)s\big(\frac{1}{\epsilon}|\theta - \frac{\pi}{4}|\big) + \frac{1}{8}\big(1 - s(\frac{2}{\epsilon}|\theta - \frac{\pi}{4}|)\big).$$

Then using the fact that  $\max k(\theta) = \sqrt{2}$ ,  $\min k(\theta) = 1$ , we can verify that  $k_1(\theta)$  is positive, smooth and

$$k_1(\theta) = k(\theta)$$
 if  $|\theta - \frac{\pi}{4}| \ge 4\epsilon; \quad 0 < k_1(\theta) \le k(\theta).$ 

In a similar way, we can modify  $k(\theta)$  near other points  $-\pi/4$  and  $\pm 3\pi/4$ . Now let  $J_2$  be the domain in  $(y_1, y_n)$  plane bounded by the curve

 $(y_1, y_n) = (k_1(\theta) \cos \theta, k_1(\theta) \sin \theta), \quad 0 \le \theta \le 2\pi.$ 

We then rotate the set

$$\{(y_1, 0, \cdot, \cdot, \cdot, 0, y_n) : (y_1, y_n) \in J_2\}$$

with respect to  $y_n$  axis to get a domain  $J_3$ . Finally, J is obtained from  $J_3$  by appropriate translation and scaling.

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