

## $\delta - b$ -OPEN SETS AND $\delta - b$ -CONTINUOUS FUNCTIONS

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**ABSTRACT.** The aim of this paper is to introduce the concept of  $\delta - b$ -open set together with its corresponding operators  $\delta - b$ -interior and  $\delta - b$ -closure. A few relations between these operators and the operators defined before are established. In this paper, the concept of  $\delta - b$ -continuity has been introduced with the aid of  $\delta - b$ -open sets. Some basic properties of this mapping have also been studied.

2000 *Mathematics Subject Classification:* 54C10.

*Keywords:*  $\delta - b$ -open sets,  $\delta - b$ -continuity,  $\delta - b$ -open functions.

### 1. INTRODUCTION

Veličko [1] introduced the concept of  $\delta$ -open sets as a generalization of open sets. After him many others like Raychoudhury and Mukherjee [2], Noiri [3], Hatir and Noiri [4] further generalised the concept and introduced the notion of  $\delta$ -preopen,  $\delta$ -semiopen and  $\delta - \beta$ -open sets. In this paper we have introduced the notions of  $\delta - b$ -open sets and  $\delta - b$ -continuity. The class of  $\delta - b$ -continuous functions contains both the classes of  $\delta$ -precontinuous and  $\delta$ -semicontinuous functions and is contained in the class of all  $\delta - \beta$ -continuous functions. We obtained characterizations of  $\delta - b$ -continuous functions and analysed some of the basic properties of the function. The relationships between  $\delta - b$ -continuity and separation axioms have also been investigated.

### 2. PRELIMINARIES

Throughout the present paper,  $X$  and  $Y$  are always topological spaces on which no separation axioms are assumed unless explicitly stated. Let  $A$  be a subset of  $X$ . The interior of  $A$ , the closure of  $A$ , the  $\delta$ -interior of  $A$ , the  $\delta$ -closure, the semi-interior, the semi-closure, the pre-interior and the pre-closure of  $A$  are denoted by  $\text{int}(A)$ ,  $\text{cl}(A)$ ,  $\text{int}_\delta(A)$ ,  $\text{cl}_\delta(A)$ ,  $\text{sint}(A)$ ,  $\text{scl}(A)$ ,  $\text{pint}(A)$  and  $\text{pcl}(A)$  respectively. A subset

$A$  of  $X$  is said to be regular open (resp. regular closed) [5] if  $A = \text{int}(\text{cl}(A))$  (resp.  $A = \text{cl}(\text{int}(A))$ ). The  $\delta$ –interior [2] of a subset  $A$  of  $X$  is the union of all regular open sets of  $X$  contained in  $A$ . A subset  $A$  is called  $\delta$ –open [1] if  $A = \text{int}_\delta(A)$ , i.e., a set is  $\delta$ –open if it is the union of regular open sets. The complement of a  $\delta$ –open set is called  $\delta$ –closed, alternatively, a subset  $A$  of  $X$  is called  $\delta$ –closed [1] if  $A = \text{cl}_\delta(A)$ , where  $\text{cl}_\delta(A) = \{x \in X : A \cap \text{int}(\text{cl}(U)) \neq \emptyset, U \text{ is open in } X \text{ and } x \in U\}$ .

**Definition 1.** A subset  $A$  of  $X$  is called

- (a) Preopen [6] if  $A \subset \text{int}(\text{cl}(A))$ ,
- (b) Semiopen [7] if  $A \subset \text{cl}(\text{int}(A))$ ,
- (c)  $\beta$ –open [8] if  $A \subset \text{cl}(\text{int}(\text{cl}(A)))$ ,
- (d)  $\delta$ –preopen [2] if  $A \subset \text{int}(\text{cl}_\delta(A))$ ,
- (e)  $\delta$  –  $\beta$ –open [4] if  $A \subset \text{cl}(\text{int}(\text{cl}_\delta(A)))$ ,
- (f)  $\delta$ –semiopen [3] if  $A \subset \text{cl}(\text{int}_\delta(A))$ ,
- (g)  $b$ –open [9] if  $A \subset \text{int}(\text{cl}(A)) \cup \text{cl}(\text{int}(A))$ ,
- (h)  $\delta$  –  $b$ –open if  $A \subset \text{int}(\text{cl}_\delta(A)) \cup \text{cl}(\text{int}_\delta(A))$

The family of all  $\delta$  –  $b$ –open (resp.  $\delta$ –preopen,  $\delta$ –semiopen,  $\delta$  –  $\beta$ –open) sets of  $X$  is denoted by  $\delta BO(X)$  (resp.  $\delta PO(X)$ ,  $\delta SO(X)$ ,  $\delta \beta O(X)$ ).

**Definition 2.** Let  $A$  be a subset of a topological space  $X$ .

- (a) The complement of a  $\delta$  –  $b$ –open (resp.  $\delta$ –preopen,  $\delta$ –semiopen,  $\delta$  –  $\beta$ –open) set is called  $\delta$  –  $b$ –closed (resp.  $\delta$ –preclosed [2],  $\delta$ –semclosed [3],  $\delta$  –  $\beta$ –closed [4]).
- (b) The union of all  $\delta$  –  $b$ –open (resp.  $\delta$ –preopen,  $\delta$ –semiopen,  $\delta$  –  $\beta$ –open) sets contained in  $A$  is called the  $\delta$  –  $b$ –interior (resp.  $\delta$ –preinterior [10],  $\delta$ –seminterior [3],  $\delta$  –  $\beta$ –interior [4]) of  $A$  and is denoted by  $\text{bint}_\delta(A)$  (resp.  $\text{pint}_\delta(A)$ ,  $\text{sint}_\delta(A)$ ,  $\text{\beta int}_\delta(A)$ ).
- (c) The intersection of all  $\delta$  –  $b$ –closed (resp.  $\delta$  – preclosed,  $\delta$ –semclosed,  $\delta$  –  $\beta$ –closed) sets containing  $A$  is called the  $\delta$  –  $b$ –closure (resp.  $\delta$ –preclosure [2],  $\delta$ –semclosure [3],  $\delta$  –  $\beta$ –closure [4]) of  $A$  and is denoted by  $\text{bcl}_\delta(A)$  (resp.  $\text{pcl}_\delta(A)$ ,  $\text{scl}_\delta(A)$ ,  $\text{\beta cl}_\delta(A)$ ).

**Lemma 1.** [4] For a subset  $A$  of a topological space  $X$ , the following properties hold:

- (a)  $\text{pint}_\delta(A) = A \cap \text{int}(\text{cl}_\delta(A))$ ;  $\text{pcl}_\delta(A) = A \cup \text{cl}(\text{int}_\delta(A))$ ,
- (b)  $\text{sint}_\delta(A) = A \cap \text{cl}(\text{int}_\delta(A))$ ;  $\text{scl}_\delta(A) = A \cup \text{int}(\text{cl}_\delta(A))$ ,
- (c)  $\text{\beta int}_\delta(A) = A \cap \text{cl}(\text{int}(\text{cl}_\delta(A)))$ ;  $\text{\beta cl}_\delta(A) = A \cup \text{int}(\text{cl}(\text{int}_\delta(A)))$ .

### 3. $\delta$ – $b$ –OPEN SETS

**Theorem 2.**  $\delta PO(X) \cup \delta SO(X) \subset \delta BO(X) \subset \delta \beta O(X)$ .

**Remark 1.** *The inclusions can not be replaced with equalities as shown by the following examples.*

**Example 1.** *Let  $X = \{a, b, c, d, e\}$  and let  $\tau = \{X, \emptyset, \{a\}, \{e\}, \{a, e\}, \{c, d\}, \{a, c, d\}, \{c, d, e\}, \{a, c, d, e\}\}$ . Then  $A = \{a, b, d\}$  is  $\delta$  –  $b$ –open but neither  $\delta$ –preopen nor  $\delta$ –semiopen.*

**Example 2.** *Let  $X = \{a, b, c, d\}$  and let  $\tau = \{X, \emptyset, \{a\}, \{c\}, \{a, c\}, \{a, b\}, \{a, b, c\}\}$ . Then  $A = \{a, d\}$  is  $\delta$  –  $\beta$ –open but not  $\delta$  –  $b$ –open.*

**Theorem 3.** *Let  $A \in \delta BO(X)$  such that  $\text{int}_\delta(A) = \emptyset$ , then  $A \in \delta PO(X)$ .*

**Theorem 4.** *A subset  $A$  of  $X$  is  $\delta$ – $b$ –closed if and only if  $\text{cl}(\text{int}_\delta(A)) \cap \text{int}(\text{cl}_\delta(A)) \subset A$ .*

**Theorem 5.** *Arbitrary union (intersection) of  $\delta$  –  $b$ –open (resp.  $\delta$  –  $b$ –closed) sets is  $\delta$  –  $b$ –open (resp.  $\delta$  –  $b$ –closed).*

**Remark 2.** *The intersection of two  $\delta$  –  $b$ –open sets may not be  $\delta$  –  $b$ –open. This can be shown by the following example.*

**Example 3.** *Let  $X = \{a, b, c\}$  and  $\tau = \{X, \emptyset, \{a\}, \{b\}, \{a, b\}\}$ . Then  $A = \{a, c\}$  and  $B = \{b, c\}$  are both  $\delta$  –  $b$ –open sets, but  $A \cap B = \{c\}$  is not  $\delta$  –  $b$ –open.*

**Theorem 6.** *The following properties hold for the  $\delta$  –  $b$ –closures of subsets  $A, B$  of  $X$ .*

- (a)  $A$  is  $\delta$  –  $b$ –closed in  $X$  if and only if  $A = \text{bcl}_\delta(A)$ ,
- (b)  $\text{bcl}_\delta(A) \subset \text{bcl}_\delta(B)$  whenever  $A \subset B \subset X$ ,
- (c)  $\text{bcl}_\delta(A)$  is  $\delta$  –  $b$ –closed in  $X$ ,
- (d)  $\text{bcl}_\delta(\text{bcl}_\delta(A)) = \text{bcl}_\delta(A)$ ,
- (e)  $x \in \text{cl}_\delta(A)$  if  $A \cap U \neq \emptyset$  for every  $\delta$  –  $b$ –open set  $U$  containing  $x$ .

**Theorem 7.** *The following properties hold for the  $\delta$  –  $b$ –interiors of subsets  $A, B$  of  $X$ .*

- (a)  $\text{bint}_\delta(A) \subset \text{bint}_\delta(B)$  whenever  $A \subset B \subset X$ ,

(b)  $bint_\delta(B)$  is  $b$ –open in  $X$ ,

(c)  $bint_\delta(bint_\delta(A)) = bint_\delta(A)$ .

**Theorem 8.** *Let  $A, B \subset X$  be such that  $A$  is  $\delta$  –  $b$ –open and  $B$  is  $\delta$  –  $b$ –closed. Then there exist a  $\delta$  –  $b$ –open set  $H$  and a  $\delta$  –  $b$ –closed set  $K$  such that  $A \cap B \subset K$  and  $H \subset A \cup B$ .*

*Proof.* Let  $K = bcl_\delta(A) \cap B$  and  $H = A \cup bint_\delta(B)$ . Then  $K$  is  $\delta$  –  $b$ –closed and  $H$  is  $\delta$  –  $b$ –open. Also  $A \cap B \subset bcl_\delta(A) \cap B = K$  and  $H = A \cup bint_\delta(B) \subset A \cup B$ .

**Theorem 9.** *For a subset  $A$  of a space  $X$ , the following are equivalent.*

(a)  $A$  is  $\delta$  –  $b$ –open.

(b)  $A = pint_\delta(A) \cup sint_\delta(A)$ .

(c)  $A \subset pcl_\delta(pint_\delta(A))$ .

*Proof.*

(a) $\Rightarrow$ (b): Let  $A$  be  $\delta$  –  $b$ –open. Then  $A \subset cl(int_\delta(A)) \cup int(cl_\delta(A))$ . Now  $pint_\delta(A) \cup sint_\delta(A) = [A \cap int(cl_\delta(A))] \cup [A \cap cl(int_\delta(A))] = A \cap [int(cl_\delta(A)) \cup cl(int_\delta(A))] = A$ .

(b) $\Rightarrow$ (c):  $A = pint_\delta(A) \cup sint_\delta(A) = pint_\delta(A) \cup [A \cap cl(int_\delta(A))] \subset pint_\delta(A) \cup cl(int_\delta(A)) = pcl_\delta(pint_\delta(A))$

(c) $\Rightarrow$ (a):  $A \subset pcl_\delta(pint_\delta(A)) = pint_\delta(A) \cup cl(int_\delta(A)) \subset (A \cap cl(int_\delta(A))) \cup int(cl_\delta(A))$ . Therefore,  $A$  is  $\delta$  –  $b$ –open.

**Lemma 10.** [2] *Let  $A$  be a subset of a space  $X$ . Then*

(a)  $cl_\delta(A) \cap G \subset cl_\delta(A \cap G)$ , for any  $\delta$ –open set  $G$  in  $X$ ,

(b)  $int_\delta(A \cup F) \subset int_\delta(A) \cup F$ , for any  $\delta$ –closed set  $F$  in  $X$ .

**Theorem 11.** *For a subset  $A$  of a space  $X$ , the following properties hold.*

(a)  $bcl_\delta(A) = scl_\delta(A) \cap pcl_\delta(A)$ ,

(b)  $bint_\delta(A) = sint_\delta(A) \cup pint_\delta(A)$ ,

(c)  $bcl_\delta(X \setminus A) = X \setminus bint_\delta(A)$ ,

(d)  $x \in bcl_\delta(A)$  if and only if  $A \cap U \neq \emptyset$  for every  $U \in \delta BO(X)$  containing  $x$ .

*Proof.* (a) Since  $\text{bcl}_\delta(A)$  is  $\delta$ – $b$ –closed, therefore,  $\text{int}(\text{cl}_\delta(\text{bcl}_\delta(A))) \cap \text{cl}(\text{int}_\delta(\text{bcl}_\delta(A))) \subset \text{bcl}_\delta(A)$ . This implies that  $A \cup [\text{int}(\text{cl}_\delta(A)) \cap \text{cl}(\text{int}_\delta(A))] \subset \text{bcl}_\delta(A)$ .

Thus  $\text{scl}_\delta(A) \cap \text{pcl}_\delta(A) \subset \text{bcl}_\delta(A)$ .

To prove the reverse inclusion, we have,  $\text{scl}_\delta(A) \cap \text{pcl}_\delta(A)$  is a  $\delta$  –  $b$ –closed set containing  $A$ . Hence,  $\text{bcl}_\delta(A) \subset \text{scl}_\delta(A) \cap \text{pcl}_\delta(A)$ .

(b) Since  $\text{bint}_\delta(A)$  is  $\delta$  –  $b$ –open, therefore,  $\text{int}(\text{cl}_\delta(\text{bint}_\delta(A))) \cup \text{cl}(\text{int}_\delta(\text{bint}_\delta(A))) \supset \text{bint}_\delta(A)$ . This implies that  $A \cap [\text{int}(\text{cl}_\delta(A)) \cap \text{cl}(\text{int}_\delta(A))] \supset \text{bint}_\delta(A)$ . Thus  $\text{sint}_\delta(A) \cup \text{pint}_\delta(A) \supset \text{bint}_\delta(A)$ .

To prove the reverse inclusion, we have,  $\text{sint}_\delta(A) \cup \text{pint}_\delta(A)$  is a  $\delta$  –  $b$ –open set containing  $A$ . Hence,  $\text{sint}_\delta(A) \cup \text{pint}_\delta(A) \subset \text{bint}_\delta(A)$ .

(c) We have,  $\text{bcl}_\delta(X \setminus A) = \text{scl}_\delta(X \setminus A) \cap \text{pcl}_\delta(X \setminus A) = [X \setminus \text{sint}_\delta(A)] \cap [X \setminus \text{pint}_\delta(A)] = X \setminus [\text{sint}_\delta(A) \cup \text{pint}_\delta(A)] = X \setminus \text{bint}_\delta(A)$

(d) Let  $x \in \text{bcl}_\delta(A)$ . Thus  $x \in \text{cl}_\delta(A)$ . Hence,  $A \cap U \neq \emptyset$  for every  $U \in \delta BO(X)$  containing  $x$ .

Conversely, let  $A \cap U \neq \emptyset$  for every  $U \in \delta BO(X)$  containing  $x$ . Let  $x \in X \setminus \text{bcl}_\delta(A) = \text{bint}_\delta(X \setminus A)$ . Therefore, there exists  $U \in \delta BO(X)$  containing  $x$  such that  $U \subset X \setminus A$ . This implies,  $A \cap U = \emptyset$ . Which is a contradiction. Hence,  $x \in \text{bcl}_\delta(A)$ .

**Theorem 12.** A set  $A$  in  $X$  is  $\delta$  –  $b$ –open if and only if  $U \cap A \in \delta BO(X)$ , for every regular open (equivalently  $\delta$ –open) set  $U$  of  $X$ .

*Proof.* Let  $A \in \delta BO(X)$ . Therefore,  $U \cap A \subset U \cap [\text{int}(\text{cl}_\delta(A)) \cup \text{cl}(\text{int}_\delta(A))]$   
 $\subset [\text{int}(U) \cap \text{int}(\text{cl}_\delta(A))] \cup \text{cl}(U \cap \text{int}_\delta(A)) = \text{int}(U \cap \text{cl}_\delta(A)) \cup \text{cl}(\text{int}_\delta(U) \cap \text{int}_\delta(A)) \subset$   
 $\text{int}(\text{cl}_\delta(U \cap A)) \cup \text{cl}(\text{int}_\delta(U \cap A))$ . Thus,  $U \cap A \in \delta BO(X)$ .

Conversely, let  $U \cap A \in \delta BO(X)$ , for every regular open set  $U$  of  $X$ . Since,  $X$  is regular open, therefore,  $X \cap A = A \in \delta BO(X)$ .

**Definition 3.** A subset  $A$  of a space  $X$  is called a  $\delta$  –  $b$ –neighbourhood of  $x$  in  $X$  if there exists  $U \in \delta BO(X)$  such that  $x \in U \subset A$ .

**Theorem 13.** If  $U$  is a  $\delta$ –open subset of a space  $X$  and  $V \in \delta BO(X)$ , then  $U \cap V \in \delta BO(U)$ .

*Proof.* We have,  $U \cap V \subset U \cap [\text{int}(\text{cl}_\delta(A)) \cup \text{cl}(\text{int}_\delta(A))]$   
 $= [U \cap \text{int}(\text{cl}_\delta(V))] \cup [U \cap \text{cl}(\text{int}_\delta(V))] \subset \text{int}_U(U \cap \text{cl}_\delta(V)) \cup [U \cap \text{cl}(U \cap \text{int}_\delta(V))] \subset$   
 $\text{int}_U(U \cap \text{cl}_\delta(U \cap V)) \cup \text{cl}_U(U \cap \text{int}_\delta(V)) = \text{int}_U(\text{cl}_{\delta U}(U \cap V)) \cup \text{cl}_U(\text{int}_\delta(U \cap V)) \subset$   
 $\text{int}_U(\text{cl}_{\delta U}(U \cap V)) \cup \text{cl}_U(\text{int}_{\delta U}(U \cap V))$ . Therefore,  $U \cap V \in \delta BO(U)$ .

4.  $\delta$  –  $b$ –CONTINUOUS FUNCTION

**Definition 4.** A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\delta$  –  $b$ –continuous (resp.  $\delta$ –precontinuous,  $\delta$ –semicontinuous [3],  $\delta$  –  $\beta$ –continuous [4]) if for each  $V \in \sigma$ ,  $f^{-1}(V)$  is  $\delta$  –  $b$ –open (resp.  $\delta$ –preopen,  $\delta$ –semiopen,  $\delta$  –  $\beta$ –open) in  $X$ .

**Remark 3.** Every  $\delta$ –precontinuous as well as every  $\delta$ –semicontinuous function is  $\delta$  –  $b$ –continuous function also every  $\delta$  –  $b$ –continuous function is  $\delta$  –  $\beta$ –continuous. But none of these relations can be reversed as given by the following examples.

**Example 4.** The function  $f : (X, \tau) \rightarrow (Y, \sigma)$ , where  $(X, \tau)$  is the topological space given in Example 1 and  $Y = \{a, b\}$ ,  $\sigma = \{Y, \emptyset, \{a\}\}$ , defined by  $f(a) = f(b) = f(d) = a$ ,  $f(c) = f(e) = b$  is  $\delta$  –  $b$ –continuous but it is neither  $\delta$ –precontinuous nor  $\delta$ –semicontinuous.

**Example 5.** The function  $f : (X, \tau) \rightarrow (Y, \sigma)$ , where  $(X, \tau)$  is the topological space given in Example 3.2. and  $Y = \{a, b\}$ ,  $\sigma = \{Y, \emptyset, \{a\}\}$ , defined by  $f(a) = f(d) = a$ ,  $f(c) = f(e) = b$  is  $\delta$  –  $\beta$ –continuous but not  $\delta$  –  $b$ –continuous.

**Definition 5.** [11] A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\delta$ –continuous if for each  $x \in X$  and for each  $V \in \sigma$  containing  $f(x)$ , there exists  $U \in \tau$  containing  $x$  such that  $f(\text{int}(\text{cl}(U))) \subset \text{int}(\text{cl}(V))$ .

**Remark 4.**  $\delta$ –continuity and  $\delta$  –  $b$ –continuity are independent of each other as given by the following example.

**Example 6.** Let  $X = Y = \{a, b, c\}$  and let  $\tau = \{X, \emptyset, \{a\}, \{b\}, \{a, b\}\}$ ,  $\sigma = \{Y, \emptyset, \{b, c\}\}$ . Then the function  $f : (X, \tau) \rightarrow (Y, \sigma)$  defined by  $f(a) = c$ ,  $f(b) = b$ ,  $f(c) = a$  is  $\delta$ –continuous but not  $\delta$  –  $b$ –continuous whereas the identity function  $i : (Y, \sigma) \rightarrow (X, \tau)$  defined by  $i(x) = x$  for all  $x \in Y$  is  $\delta$  –  $b$ –continuous but not  $\delta$ –continuous.

**Definition 6.** Let  $A$  be a subset of a space  $X$ . Then  $\delta$  –  $b$ –frontier of  $A$  is defined by  $\text{bfr}_\delta(A) = \text{bcl}_\delta(A) \cap \text{bcl}_\delta(X \setminus A) = \text{bcl}_\delta(A) \setminus \text{bint}_\delta(A)$ .

**Theorem 14.** The following statements are equivalent for a function  $f : X \rightarrow Y$ .

- (a)  $f$  is  $\delta$  –  $b$ –continuous,
- (b) For each  $x \in X$  and each open set  $V$  of  $Y$  containing  $f(x)$ , there exists  $U \in \delta BO(X)$  containing  $x$  such that  $f(U) \subset V$ ,
- (c) For each closed subset  $W$  of  $Y$ ,  $f^{-1}(W)$  is  $\delta$  –  $b$ –closed.
- (d) For each subset  $A$  of  $X$ ,  $f(\text{bcl}_\delta(A)) \subset \text{cl}(f(A))$ .

(e) For each subset  $B$  of  $Y$ ,  $bcl_\delta(f^{-1}(B)) \subset f^{-1}(cl(B))$ .

(f) For each subset  $B$  of  $Y$ ,  $f^{-1}(int(B)) \subset bint_\delta(f^{-1}(B))$ .

(g) For each subset  $B$  of  $Y$ ,  $bfr_\delta(f^{-1}(B)) \subset f^{-1}(fr(B))$ .

*Proof.* (a) $\Leftrightarrow$ (b) and (a) $\Leftrightarrow$ (c) are straightforward.

(c) $\Rightarrow$ (d): For any subset  $A$  of  $X$ ,  $f^{-1}(cl(f(A)))$  is  $\delta$  –  $b$ –closed and contains  $A$ . Thus  $bcl_\delta(A) \subset f^{-1}(cl(f(A)))$ , so that  $f(bcl_\delta(A)) \subset f(f^{-1}(cl(f(A)))) \subset cl(f(A))$ .

(d) $\Rightarrow$ (e): Let  $B$  be any subset of  $Y$ . Then  $f(bcl_\delta(f^{-1}(B))) \subset cl(f(f^{-1}(B))) \subset cl(B)$ . Hence  $bcl_\delta(f^{-1}(B)) \subset f^{-1}(cl(B))$ .

(e) $\Rightarrow$ (c): Let  $W$  be a closed subset of  $Y$ .

Then  $bcl_\delta(f^{-1}(B)) \subset f^{-1}(cl(B)) = f^{-1}(B)$ . Thus  $f^{-1}(B)$  is  $\delta$  –  $b$ –closed in  $X$ . Hence,  $f$  is  $\delta$  –  $b$ –continuous.

(a) $\Rightarrow$ (f): Let  $B$  be any subset of  $Y$ . Then  $f^{-1}(int(B)) \in \delta BO(X)$ .

Thus  $f^{-1}(int(B)) = bint_\delta(f^{-1}(int(B))) \subset bint_\delta(f^{-1}(B))$ .

(f) $\Rightarrow$ (a): Let  $V \in \sigma$ . Then  $f^{-1}(V) = f^{-1}(int(V)) \subset bint_\delta(f^{-1}(V))$ . Therefore,  $f^{-1}(V) \in \delta BO(X)$ . Hence,  $f$  is  $\delta$  –  $b$ –continuous.

(d) $\Rightarrow$ (g): Let  $B$  be a subset of  $Y$ .

We have,  $bfr_\delta(f^{-1}(B)) = bcl_\delta(f^{-1}(B)) \cap bcl_\delta(X \setminus f^{-1}(B))$   
 $\subset f^{-1}(cl(B)) \cap bcl_\delta(f^{-1}(Y \setminus B)) \subset f^{-1}(cl(B)) \cap f^{-1}(cl(Y \setminus B)) = f^{-1}(fr(B))$ .

(g) $\Rightarrow$ (c): Let  $W$  be a closed subset of  $Y$ . Then  $bfr_\delta(f^{-1}(W)) \subset f^{-1}(fr(W)) \subset f^{-1}(W)$ . Thus  $f^{-1}(W)$  is  $\delta$  –  $b$ –closed in  $X$ . Hence,  $f$  is  $\delta$  –  $b$ –continuous.

**Theorem 15.** *The set of all points of  $X$  at which a function  $f : X \rightarrow Y$  is not  $\delta$  –  $b$ –continuous is identical with the union of the  $\delta$  –  $b$ –frontiers of the inverse images of the open sets containing  $f(x)$ .*

*Proof.* Let  $x \in X$  and let  $f$  be not  $\delta$  –  $b$ –continuous at  $x$ . Therefore, there exists an open set  $V$  in  $Y$  containing  $f(x)$  such that  $U \cap (X \setminus f^{-1}(V)) \neq \emptyset$  for every  $U \in \delta BO(X)$  containing  $x$ . This implies  $x \in bcl_\delta(X \setminus f^{-1}(V))$  and  $x \in f^{-1}(V)$ . Thus  $x \in bfr_\delta(f^{-1}(V))$ .

Conversely, suppose that  $f$  is  $\delta$  –  $b$ –continuous at  $x \in X$  and let  $V$  be an open set containing  $f(x)$ . Therefore, there exists  $U \in \delta BO(X)$  containing  $x$  such that  $U \subset f^{-1}(V)$ . This implies that  $x \in bint_\delta(f^{-1}(V))$  and hence,  $x \in X \setminus bfr_\delta(f^{-1}(V))$ .

**Remark 5.** *The composition of two  $\delta$  –  $b$ –continuous functions may not be  $\delta$  –  $b$ –continuous as shown by the following example.*

**Example 7.** Let  $X = Y = Z = \{a, b, c\}$  and let  $\tau = \{X, \emptyset, \{a\}, \{b\}, \{a, b\}\}$ ,  $\sigma = \{Y, \emptyset, \{a\}, \{b, c\}\}$ ,  $\gamma = \{Z, \emptyset, \{a\}, \{b\}, \{a, c\}, \{a, c\}\}$ . Then the functions  $f : (X, \tau) \rightarrow (Y, \sigma)$  and  $g : (Y, \sigma) \rightarrow (Z, \gamma)$  defined by  $f(a) = g(a) = c, f(b) = g(b) = c, f(c) = g(c) = b$  are  $\delta$  –  $b$ –continuous but their composition  $g \circ f$  is not  $\delta$  –  $b$ –continuous.

**Theorem 16.** Let  $f : X \rightarrow Y$  and  $g : Y \rightarrow Z$ . If  $f : X \rightarrow Z$  is  $\delta$  –  $b$ –continuous and  $g$  is continuous, then  $g \circ f$  is  $\delta$  –  $b$ –continuous.

*Proof.* Straightforward.

**Definition 7.** A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\delta$  –  $b$ –open if  $f(V) \in \delta BO(Y)$  for each  $V \in \delta BO(X)$ .

**Theorem 17.** A function  $f : X \rightarrow Y$  is  $\delta$  –  $b$ –open if and only if  $f^{-1}(\text{bcl}_\delta(B)) \subset \text{bcl}_\delta(f^{-1}(B))$  for each subset  $B$  of  $Y$ .

*Proof.* Let  $f$  be  $\delta$  –  $b$ –open and let  $x \in f^{-1}(\text{bcl}_\delta(B))$ . Let  $G$  be a  $\delta$  –  $b$ –open set in  $X$  containing  $x$ . Therefore,  $f(G)$  is  $\delta$  –  $b$ –open in  $Y$  containing  $f(x)$ . As a result  $B \cap f(G) \neq \emptyset$  and so  $f^{-1}(B) \cap G \neq \emptyset$ . Thus  $x \in \text{bcl}_\delta(f^{-1}(B))$ . Hence,  $f^{-1}(\text{bcl}_\delta(B)) \subset \text{bcl}_\delta(f^{-1}(B))$ .

Conversely, let  $f^{-1}(\text{bcl}_\delta(B)) \subset \text{bcl}_\delta(f^{-1}(B))$  for each subset  $B$  of  $Y$ . Let  $A$  be  $\delta$  –  $b$ –open in  $X$  and let  $C = Y \setminus f(A)$ . Now,  $A \cap f^{-1}(\text{bcl}_\delta(C) \cap f(A)) \subset A \cap f^{-1}(\text{bcl}_\delta(C)) \subset A \cap \text{bcl}_\delta(f^{-1}(C)) \subset A \cap (X \setminus A) = \emptyset$ . This implies that  $f^{-1}(\text{bcl}_\delta(C) \cap f(A)) = \emptyset$ . As a result  $\text{bcl}_\delta(C) \cap f(A) = \emptyset$  and so  $\text{bcl}_\delta(C) \subset C$ . Therefore,  $C$  is  $\delta$  –  $b$ –closed and hence,  $f(A) \in \delta BO(Y)$ .

**Theorem 18.** Let  $f : X \rightarrow Y$  and  $g : Y \rightarrow Z$ . If  $g \circ f : X \rightarrow Z$  is  $\delta$  –  $b$ –continuous and  $f$  is a  $\delta$  –  $b$ –open surjection, then  $g$  is  $\delta$  –  $b$ –continuous.

*Proof.* Let  $V$  be open in  $Z$ . Since  $g \circ f$  is  $\delta$  –  $b$ –continuous, therefore,  $(g \circ f)^{-1}(V) = f^{-1}(g^{-1}(V)) \in \delta BO(X)$ . Since,  $f$  is a  $\delta$  –  $b$ –open surjection, therefore,  $f(f^{-1}(g^{-1}(V))) = g^{-1}(V) \in \delta BO(Y)$ . Hence,  $g$  is  $\delta$  –  $b$ –continuous.

**Remark 6.** The term “surjection” can not be dropped from the above theorem as shown by the following example.

**Example 8.** Let  $X = Y = Z = \{a, b, c\}$  and let  $\tau = \{X, \emptyset, \{a\}, \{b, c\}\}$ ,  $\sigma = \{Y, \emptyset, \{a\}, \{b\}, \{a, b\}\}$ ,  $\gamma = \{Z, \emptyset, \{a\}, \{b\}, \{a, b\}, \{a, c\}\}$ . Then function  $f : (X, \tau) \rightarrow (Y, \sigma)$  defined by  $f(a) = a, f(b) = f(c) = b$  is  $\delta$  –  $b$ –open whereas  $g : (Y, \sigma) \rightarrow (Z, \gamma)$  defined by  $g(a) = b, g(b) = c, g(c) = a$  is not  $\delta$  –  $b$ –continuous. But  $g \circ f$  is  $\delta$  –  $b$ –continuous.

Definition 8 and Definition 9 can be given as in [12, 13].

**Definition 8.** A net  $\{x_\lambda : \lambda \in \Lambda\}$  in a topological space  $X$  is said to  $\delta$  –  $b$ –converge to  $x \in X$  if for every  $\delta$  –  $b$ –neighbourhood  $U$  of  $x$ , there is some  $\lambda_0 \in \Lambda$  such that  $x_\lambda \in U$  when  $\lambda \geq \lambda_0$ .

**Theorem 19.** A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\delta$  –  $b$ –continuous at  $x \in X$  if and only if for every net  $\{x_\lambda : \lambda \in \Lambda\}$  in  $X$  which  $\delta$  –  $b$ –converges to  $x$ , the net  $\{f(x_\lambda) : \lambda \in \Lambda\}$  converges to  $f(x)$ .

*Proof.* Let  $f$  be  $\delta$  –  $b$ –continuous at  $x$  and let  $\{x_\lambda : \lambda \in \Lambda\}$  be a net in  $X$  such that it  $\delta$  –  $b$ –converges to  $x$ . Let  $V \in \sigma$  contain  $f(x)$ . Therefore, there exists a  $\delta$  –  $b$ –open set  $U$  in  $X$  containing  $x$  such that  $f(U) \subset V$ . Now,  $\{x_\lambda : \lambda \in \Lambda\}$   $\delta$  –  $b$ –converges to  $x$  implies that there exists  $\lambda_0 \in \Lambda$  such that  $x_\lambda \in U$  for all  $\lambda \geq \lambda_0$ . This implies that  $f(x_\lambda) \in f(U) \subset V$  for all  $\lambda \geq \lambda_0$ . Thus  $\{f(x_\lambda) : \lambda \in \Lambda\}$  converges to  $f(x)$ .

Conversely, let  $f$  be not  $\delta$  –  $b$ –continuous at  $x \in X$ . Therefore, there exists an open neighbourhood  $V$  of  $f(x)$  such that  $f(U)$  is not a subset of  $V$  for every  $U \in \delta BO(X)$  containing  $x$ . Thus for every  $\delta$  –  $b$ –open neighbourhood  $U$  of  $x$  we can find  $x_U \in U$  such that  $f(x_U) \notin V$ . Let  $N(x)$  be the set of all  $\delta$  –  $b$ –neighbourhoods  $U$  of  $x$  in  $X$ . The set  $N(x)$  with the relation  $U_1 \leq U_2$  if and only if  $U_2 \subset U_1$ , form a directed set. Therefore, the net  $\{x_U : U \in N(x)\}$   $\delta$  –  $b$ –converges to  $x$  but  $\{f(x_U) : U \in N(x)\}$  does not converge to  $f(x)$  in  $Y$ . Which is a contradiction. Hence  $f$  is  $\delta$  –  $b$ –continuous at  $x \in X$ .

**Definition 9.** A net  $\{f_\alpha : \alpha \in \Delta\}$  in  $\delta BO(X, Y)$  is said to  $\delta$  –  $b$ –continuously converge to  $f \in \delta BO(X, Y)$  if for every net  $\{x_\lambda : \lambda \in \Lambda\}$  in  $X$  which  $\delta$  –  $b$ –converges to  $x \in X$ , the net  $\{f_\alpha(x_\lambda) : (\alpha, \lambda) \in \Delta \times \Lambda\}$  converges to  $f(x)$  in  $Y$ , where  $\delta BO(X, Y)$  denotes the set of all  $\delta$  –  $b$ –continuous functions of  $X$  to  $Y$ .

**Theorem 20.** A net  $\{f_\alpha : \alpha \in \Delta\}$  in  $\delta BO(X, Y)$   $\delta$  –  $b$ –continuously converges to  $f \in \delta BO(X, Y)$  if and only if for every  $x \in X$  and for every open neighbourhood  $V$  of  $f(x)$  in  $Y$ , there exists an element  $\alpha_0 \in \Delta$  and a  $\delta$  –  $b$ –open neighbourhood  $U$  of  $x$  in  $X$  such that  $f_\alpha(U) \subset V$  for every  $\alpha \geq \alpha_0, \alpha \in \Delta$ .

*Proof.* Let  $x \in X$  and let  $V$  be an open neighbourhood of  $f(x)$  in  $Y$  such that for every  $\alpha \in \Delta$  and for every  $\delta$  –  $b$ –open neighbourhood  $U$  of  $x \in X$ , there exists  $\alpha' \geq \alpha, \alpha \in \Delta$  such that  $f_{\alpha'}(U)$  is not a subset of  $V$ . Then for every  $\delta$  –  $b$ –open neighbourhood  $U$  of  $x$  in  $X$  we can choose a point  $x_U \in U$  such that  $f_{\alpha'}(x_U) \notin V$ . Therefore, the net  $\{x_U : U \in N(x)\}$   $\delta$  –  $b$ –converges to  $x$ , but the net  $\{f_\alpha(x_U) : (\alpha, U) \in \Delta \times N\}$  does not converge to  $f(x)$  in  $Y$ .

Conversely, let  $\{x_\lambda : \lambda \in \Lambda\}$  be a net in  $\delta BO(X, Y)$  which  $\delta$  –  $b$ –converges to  $x$  in  $X$  and an element  $\alpha_0 \in \Delta$  such that  $f_\alpha(U) \subset V$  for all  $\alpha \geq \alpha_0, \alpha \in \Delta$ . Since the net  $\{x_\lambda : \lambda \in \Lambda\}$   $\delta$  –  $b$ –converges to  $x$  in  $X$ , there exists  $\lambda_0 \in \Lambda$  such that  $x_\lambda \in U$  for all  $\lambda \in \Lambda, \lambda \geq \lambda_0$ . Let  $(\lambda_0, \alpha_0) \in \Delta \times \Delta$ . Then for every  $(\lambda, \alpha) \in \Delta \times \Delta, \lambda \geq \lambda_0, \alpha \geq \alpha_0$ ,

we have,  $f_\alpha(x_\lambda) \in f_\alpha(U) \subset V$ . Thus the net  $\{f_\alpha(x_\lambda) : (\alpha, \lambda) \in \Delta \times \Lambda\}$  converges to  $f(x)$  in  $Y$ .

**Theorem 21.** *If  $f : X \rightarrow Y$  is  $\delta$  –  $b$ –continuous and  $U$  is  $\delta$ –open in  $X$ , then  $f|_U : U \rightarrow Y$  is  $\delta$  –  $b$ –continuous.*

*Proof.* Let  $V$  be an open subset of  $Y$ . Since  $f$  is  $\delta$  –  $b$ –continuous,  $f^{-1}(V) \in \delta BO(X)$ . Now  $(f|_U)^{-1}(V) = f^{-1}(V) \cap U \in \delta BO(U)$ . Hence  $f|_U : U \rightarrow Y$  is  $\delta$  –  $b$ –continuous.

Let  $\{X_\alpha : \alpha \in \Lambda\}$  and  $\{Y_\alpha : \alpha \in \Lambda\}$  be any two families of spaces with the same index set  $\Lambda$ . Let  $f_\alpha : X_\alpha \rightarrow Y_\alpha$  be a function for each  $\alpha \in \Lambda$ . The product space  $\Pi\{X_\alpha : \alpha \in \Lambda\}$  will be denoted by  $\Pi X_\alpha$  and  $f : \Pi X_\alpha \rightarrow \Pi Y_\alpha$  denotes the product function defined by  $f(\{x_\alpha\}) = \{f_\alpha(x_\alpha)\}$  for each  $\{x_\alpha\} \in \Pi X_\alpha$ .

**Theorem 22.** *If a function  $f : X \rightarrow \Pi Y_\alpha$  is  $\delta$ – $b$ –continuous, then  $p_\alpha \circ f : X \rightarrow Y_\alpha$  is  $\delta$  –  $b$ –continuous for each  $\alpha \in \Lambda$ , where  $p_\alpha$  is the projection of  $\Pi Y_\alpha$  onto  $Y_\alpha$ .*

*Proof.* Let  $V_\alpha$  be an open set in  $Y_\alpha$ . Since  $p_\alpha$  is continuous, therefore,  $p_\alpha^{-1}(V_\alpha)$  is open in  $\Pi Y_\alpha$  and hence,  $f^{-1}(p_\alpha^{-1}(V_\alpha)) = (p_\alpha \circ f)^{-1}(V_\alpha) \in \delta BO(X)$ . This shows that  $p_\alpha \circ f$  is  $\delta$  –  $b$ –continuous for each  $\alpha \in \Lambda$ .

**Definition 10.** *A topological space  $X$  is said to be  $\delta$ –Hausdorff if for any  $x, y (x \neq y) \in X$ , there exist disjoint  $\delta$ –open sets  $G, H$  such that  $x \in G$  and  $y \in H$ .*

**Lemma 23.** *If  $U \in \delta BO(X)$  and  $V$  is  $\delta$ –open in  $Y$ , then  $U \times V \in \delta BO(X \times Y)$ .*

**Theorem 24.** *If  $f : X \rightarrow Y$  is  $\delta$  –  $b$ –continuous,  $g : X \rightarrow Y$  is  $\delta$ –continuous and  $Y$  is Hausdorff, then the set  $\{x \in X : f(x) = g(x)\}$  is  $\delta$  –  $b$ –closed in  $X$ .*

*Proof.* Let  $A = \{x \in X : f(x) = g(x)\}$  and let  $x \in X \setminus A$ . Thus  $f(x) \neq g(x)$ . Since,  $Y$  is Hausdorff, therefore, there exists open sets  $G$  and  $H$  in  $Y$  such that  $f(x) \in G, g(x) \in H$  and  $G \cap H = \emptyset$ . This implies  $G \cap \text{int}(\text{cl}(H)) = \emptyset$ . Since,  $f$  is  $\delta$  –  $b$ –continuous, there exists  $U \in \delta BO(X)$  containing  $x$  such that  $f(U) \subset G$ . Since,  $g$  is  $\delta$ –continuous, there exists an open set  $V$  in  $X$  containing  $x$  such that  $f(\text{int}(\text{cl}(V))) \subset \text{int}(\text{cl}(H))$ . Let  $W = U \cap \text{int}(\text{cl}(V))$ . Now,  $W \in \delta BO(X)$  and  $f(W) \cap g(W) \subset f(U) \cap g(\text{int}(\text{cl}(V))) \subset G \cap \text{int}(\text{cl}(H)) = \emptyset$ . This implies  $W \cap A = \emptyset$ . Thus  $x \in X \setminus \text{bcl}_\delta(A)$ . Hence,  $A$  is  $\delta$  –  $b$ –closed.

**Theorem 25.** *If  $f : X \rightarrow Y$  is  $\delta$  –  $b$ –continuous and  $Y$  is a  $\delta$ –Hausdorff space, then the graph  $G_f = \{(x, f(x)) : x \in X\}$  is  $\delta$  –  $b$ –closed.*

*Proof.* Let  $(x, y) \notin G_f$ . Then  $f(x) \neq y$ . Since,  $Y$  is a  $\delta$ –Hausdorff space, therefore, there exist disjoint  $\delta$ –open sets  $G$  and  $H$  such that  $f(x) \in G$  and  $y \in H$ . Since  $f$  is  $\delta$  –  $b$ –continuous, there is a  $\delta$  –  $b$ –open set  $U$  containing  $x$  such that  $f(U) \subset G$ . Thus  $(x, y) \in U \times H \subset X \times Y \setminus G_f$ . As a result of which  $X \times Y \setminus G_f \in \delta BO(X \times Y)$  since, by Lemma 22,  $U \times H \in \delta BO(X \times Y)$ . Hence,  $G_f$  is  $\delta$  –  $b$ –closed.

**Definition 11.** A space  $X$  is called  $\delta$  –  $b$ –connected if  $X$  is not the union of two disjoint non-empty  $\delta$  –  $b$ –open sets.

**Theorem 26.** Let  $f : X \rightarrow Y$  be a  $\delta$  –  $b$ –surjection. If  $X$  is  $\delta$  –  $b$ –connected, then  $Y$  is connected.

*Proof.* Suppose that  $Y$  is not connected. Therefore, there exist disjoint open sets  $G$  and  $H$  such that  $Y = G \cup H$ . Since,  $f$  is  $\delta$  –  $b$ –continuous,  $f^{-1}(G)$  and  $f^{-1}(H)$  are  $\delta$  –  $b$ –open in  $X$ . On the other hand,  $f^{-1}(G)$  and  $f^{-1}(H)$  are non-empty disjoint sets and  $X = f^{-1}(G) \cup f^{-1}(H)$ . This shows that  $X$  is not  $\delta$  –  $b$ –connected which is a contradiction.

**Definition 12.** A space  $X$  is said to be

- (a)  $\delta$  –  $b$  –  $T_1$  if for each pair of distinct points  $x$  and  $y$  in  $X$ , there exist  $\delta$  –  $b$ –open sets  $G$  and  $H$  containing  $x$  and  $y$ , respectively, such that  $y \notin G$  and  $x \notin H$ .
- (b)  $\delta$  –  $b$ –Hausdorff if for each pair of distinct points  $x$  and  $y$  in  $X$ , there exist disjoint  $\delta$  –  $b$ –open sets  $G$  and  $H$  containing  $x$  and  $y$ , respectively.

**Theorem 27.** The following properties hold for a  $\delta$  –  $b$ –continuous injection  $f : X \rightarrow Y$ .

- (a) If  $Y$  is a Hausdorff space, then  $X$   $\delta$  –  $b$ –Hausdorff.
- (b) If  $Y$  is a  $T_1$ –space, then  $X$  is a  $\delta$  –  $b$  –  $T_1$  space.

*Proof.* (a) Let  $x, y (\neq x) \in X$ . Since,  $f$  is injective, therefore,  $f(x) \neq f(y)$  in  $Y$ . Since,  $Y$  is Hausdorff, therefore, there exist disjoint open sets  $G$  and  $H$  such that  $f(x) \in G$  and  $f(y) \in H$ . This implies that  $f^{-1}(G), f^{-1}(H)$  are disjoint  $\delta$  –  $b$ –open sets in  $X$  containing  $x, y$  respectively. Hence,  $X$  is  $\delta$  –  $b$ –Hausdorff.

(b) Let  $x, y (\neq x) \in X$ . Since,  $f$  is injective, therefore,  $f(x) \neq f(y)$  in  $Y$ . Since,  $Y$  is  $T_1$ , therefore, there exist open sets  $G$  and  $H$  containing  $x$  and  $y$  respectively such that  $f(x) \notin G$  and  $f(y) \notin H$ . This implies that  $f^{-1}(G), f^{-1}(H)$  are  $\delta$  –  $b$ –open sets in  $X$  containing  $x, y$  respectively such that  $x \notin f^{-1}(G)$  and  $y \notin f^{-1}(H)$ . Hence,  $X$  is a  $\delta$  –  $b$  –  $T_1$  space.

**Acknowledgements.** The author is thankful to Prof. Paritosh Bhattacharyya (retd.), Department of Mathematics, Kalyani University, West Bengal, India for his suggestions.

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