

# Existence and exponential stability of solutions for laminated viscoelastic Timoshenko beams

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**Abstract.** In this paper, we consider a laminated Timoshenko beams with a viscoelastic damping. We prove well-posedness by using Faedo-Galerkin method and establish an exponential decay result by introducing a suitable Lyapunov functional.

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**Key words:** Timoshenko; laminated beam; Lyapunov function; exponential decay.

## 1 Introduction

Hansen and Spies [5] introduced a mathematical model for 2-layered beams with structural damping due to the interfacial slip. The model is as follows

$$(1.1) \quad \begin{cases} \rho w_{tt}(x, t) + G(\psi - w_x)_x = 0, \\ I_\rho(3S_{tt} - \psi_{tt}) - G(\psi - w_x) - D(3S_{xx} - \psi_{xx}) = 0, \\ I_\rho S_{tt}(x, t) + G(\psi - w_x) + \frac{4}{3}\gamma S + \frac{4}{3}\beta S_t - DS_{xx} = 0. \end{cases}$$

where  $w(x, t)$  is the transversal displacement,  $\psi(x, t)$  denotes the rotational displacement and  $S(x, t)$  is proportional to the amount of slip along the interface at time  $t$  and longitudinal spatial variable  $x$ . The coefficients  $\rho, G, I_\rho, D, \gamma, \beta$  represent density, shear stiffness, mass moment of inertia, flexural rigidity, adhesive stiffness, and adhesive damping parameter, respectively.

In this paper, we consider a laminated viscoelastic Timoshenko beams. We use the notion of effective rotation angle  $\xi = 3S - \psi$  in (1.1) with  $\frac{4}{3}\gamma = 0$  and  $\frac{4}{3}\beta = \mu$ . Then adding the viscoelastic terms, we have, for  $(x, t) \in (0, 1) \times (0, +\infty)$

$$(1.2) \quad \begin{cases} \rho w_{tt}(x, t) + G(3S - \xi - w_x)_x = 0, \\ I_\rho \xi_{tt}(x, t) - G(3S - \xi - w_x) - D\xi_{xx} + \int_0^t \varpi_1(r) \xi_{xx}(t-r) dr = 0, \\ I_\rho S_{tt}(x, t) + G(3S - \xi - w_x) - DS_{xx} + \mu S_t + \int_0^t \varpi_2(r) S_{xx}(t-r) dr = 0. \end{cases}$$

Under the boundary conditions

$$(1.3) \quad \begin{cases} w(0, t) = \xi(0, t) = S(0, t) = 0, & t > 0, \\ \xi_x(1, t) = S_x(1, t) = 0, & t > 0, \\ 3S(1, t) - \xi(1, t) - w_x(1, t) = 0, & t > 0, \end{cases}$$

and the initial conditions

$$(1.4) \quad (w, \xi, S)|_{t=0} = (w_0, \xi_0, S_0), \quad (w_t, \xi_t, S_t)|_{t=0} = (w_1, \xi_1, S_1).$$

In the absence of the viscoelastic term (that is, if  $\varpi_1 = \varpi_2 = 0$ ), with constant delay and boundary feedbacks B. Feng [2] considered the following Timoshenko system

$$(1.5) \quad \begin{cases} \rho w_{tt}(x, t) + G(3S - \xi - w_x)_x + a_1 w_t(x, t - \tau) = 0, \\ I_\rho \xi_{tt}(x, t) - G(3S - \xi - w_x) - D\xi_{xx} + a_2 \xi_t(x, t - \tau) = 0, \\ I_\rho S_{tt}(x, t) + G(3S - \xi - w_x) - DS_{xx} + a_3 S_t(x, t - \tau) = 0, \end{cases}$$

where  $(x, t) \in (0, L) \times (0, \infty)$  and under the following boundary conditions

$$(1.6) \quad \begin{aligned} G(3s(L, t) - \xi(L, t) - w_x(L, t)) &= \alpha w_t(L, t), \quad t > 0, \\ D\xi_x(L, t) &= -\mu \xi_t(L, t), \quad 3DS_x(L, t) = -\nu S_t(L, t) \quad t > 0, \\ w(0, t) &= \xi(0, t) = S(0, t) = 0, \quad t > 0. \end{aligned}$$

The author proved the global well-posedness of solutions and exponential decay of energy to the system. (See [4, 3])

In [9] M. I. Mustafa considered the following system

$$(1.7) \quad \begin{cases} \rho \varphi_{tt}(x, t) + G(\psi - \varphi_x)_x = 0, \\ I_\rho (3\omega - \psi)_{tt}(x, t) - G(\psi - \varphi_x) \\ \quad - D(3\omega - \psi)_{xx} + \int_0^t g(t-s)(3\omega - \psi)_{xx}(s)ds = 0, \\ I_\rho \omega_{tt}(x, t) + G(\psi - \varphi_x) + \frac{4}{3}\gamma\omega + \frac{4}{3}\beta\omega_t - DS_{xx} = 0, \end{cases}$$

in  $(0, 1) \times (0, +\infty)$ , the author proved the well-posedness and for a wider class of relaxation functions, a generalized stability result for this system is established. (See [6, 8, 10, 11])

In the present paper, the well-posedness of the problem is analyzed in Section 3 using the Faedo-Galerkin method. In Section 4, we prove the exponential decay of the energy when time goes to infinity.

## 2 Preliminaries and statement of main results

In this section, we present some materials that will be used to prove our main results. We denote  $V = \{v \in H^1(0, 1) : v(0) = 0\}$ . For the relaxation functions  $\varpi_1, \varpi_2$ , we assume

(A1)  $\varpi_i \in C^1(\mathbb{R}_+, \mathbb{R}_+)$  (for  $i = 1, 2$ ) satisfying

$$\begin{aligned} \varpi_1(0) &> 0, \quad 0 < \beta_1(t) := D - \int_0^t \varpi_1(r)dr \quad \text{and} \quad 0 < \beta_1^0 := D - \int_0^\infty \varpi_1(r)dr, \\ \varpi_2(0) &> 0, \quad 0 < \beta_2(t) := D - \int_0^t \varpi_2(r)dr \quad \text{and} \quad 0 < \beta_2^0 := D - \int_0^\infty \varpi_2(r)dr. \end{aligned}$$

(A2) There exist non-increasing functions  $\chi_i(t) \in C^1(\mathbb{R}_+, \mathbb{R}_+)$  such that

$$\varpi'_i(t) \leq -\chi_i(t)\varpi_i(t), \quad \forall t \geq 0 \quad \text{and} \quad \int_0^\infty \chi_i(t)dt = +\infty, \quad \text{for } i = 1, 2.$$

(A3) The wave speeds are equal that is  $\frac{\rho}{G} = \frac{I_\rho}{D}$

**Remark 2.1.** The hypotheses (A1)-(A3) imply that

$$(2.1) \quad \begin{cases} \beta_1^0 \leq \beta_1(t) \leq D, \\ \beta_2^0 \leq \beta_2(t) \leq D. \end{cases}$$

Let us introduce the following notations

$$\begin{aligned} (\varpi_i * h)(t) &:= \int_0^t \varpi_i(t-r)h(r)dr, \\ (\varpi_i \circ h)(t) &:= \int_0^t \varpi_i(t-r)|h(t) - h(r)|^2dr, \end{aligned}$$

**Lemma 2.1.** *For any  $\varpi, h \in C^1(\mathbb{R})$ , the following equation holds*

$$2[\varpi * h]h' = \varpi' \circ h - \varpi(t)|h|^2 - \frac{d}{dt} \left( \varpi \circ h - \int_0^t \varpi(s)ds|h|^2 \right).$$

The existence and uniqueness result is stated as follows

**Theorem 2.2.** *Assume that (A1 – A3) hold. Then given  $(w_0, \xi_0, S_0) \in H^2(0, 1) \cap V$ ,  $(w_1, \xi_1, S_1) \in V$ , there exists a unique regular solution  $w, \xi, S$  of problem (1.2) such that*

$$(w, \xi, S) \in C([0, +\infty[, H^2(0, 1) \cap V) \cap C^1([0, +\infty[, V)).$$

For any regular solution of (1.2), we define the energy as

$$\begin{aligned} (2.2) \quad \mathcal{E}(t) &= \frac{1}{2} \int_0^1 (\rho w_t^2(x, t) + I_\rho \xi_t^2(x, t))dx \\ &+ 3I_\rho S_t^2(x, t) + G|3S - \xi - w_x|^2 + \beta_1(t)\xi_x^2 + \beta_2(t)S_x^2 dx \\ &+ \frac{1}{2} \int_0^1 (\varpi_1 \circ \xi_x)dx + \frac{3}{2} \int_0^1 (\varpi_2 \circ S_x)dx. \end{aligned}$$

Our decay result reads as follows

**Theorem 2.3.** Let  $(w, \xi, S)$  be the solution of (1.2). Assume that (A1) – (A3) hold. Then there exist two positive constants  $C$  and  $d$ , such that

$$(2.3) \quad \mathcal{E}(t) \leq Ce^{-d \int_0^t \chi(r) dr}, \quad \forall t \geq 0.$$

### 3 Well-posedness of the problem

In this section, we will prove the existence and uniqueness of problem (1.2) by using Faedo-Galerkin method.

*Proof.* We divide the proof of Theorem 2.2 into two steps: the Faedo-Galerkin approximation and the energy estimates. (See [1])

Step 1 : **Faedo-Galerkin approximation.**

We construct approximations of the solution  $(w, \xi, S)$  by the Faedo-Galerkin method as follows. For  $n \geq 1$ , let  $V_n = \text{span} \{v_1, \dots, v_i\}$  be a Hilbert basis of the space  $H^2(0, 1) \cap V$ .

We choose sequences

$$(w_0^n), (w_1^n), (\xi_0^n), (\xi_1^n), (S_0^n), (S_1^n)$$

in  $V_n$  such that

$$(w_0^n, \xi_0^n, S_0^n, w_1^n, \xi_1^n, S_1^n) \rightarrow (w_0, \xi_0, S_0, w_1, \xi_1, S_1)$$

strongly in  $H^2(0, 1) \cap V$  as  $n \rightarrow \infty$ .

We search the approximate solutions

$$\begin{aligned} w^n(x, t) &= \sum_{i=1}^n f_i^n(t) v_i(x), \\ \xi^n(x, t) &= \sum_{i=1}^n h_i^n(t) v_i(x) \\ S^n(x, t) &= \sum_{i=1}^n k_i^n(t) v_i(x) \end{aligned}$$

to the finite dimensional Cauchy problem

$$(3.1) \quad \left\{ \begin{array}{l} \int_0^1 (\rho w_{tt}^n v_i - G(3S^n - \xi^n - w_x^n) v_{i,x}) dx = 0, \\ \int_0^1 (I_\rho \xi_{tt}^n v_i - G(3S^n - \xi^n - w_x^n) v_i + D\xi_x^n v_{i,x}) dx \\ \quad - \int_0^1 (\varpi_1(r) * \xi_x^n) v_{i,x} dx = 0, \\ \int_0^1 (I_\rho S_{tt}^n v_i + G(3S^n - \xi^n - w_x^n) v_i + DS_x^n v_{i,x} - \mu S_t^n v_i) dx \\ \quad - \int_0^1 (\varpi_2(r) * S_x^n) v_{i,x} dx = 0, \\ (w^n(0), \xi^n(0), S^n(0)) = (w_0^n, \xi_0^n, S_0^n), \\ (w_t^n(0), \xi_t^n(0), S_t^n(0)) = (w_1^n, \xi_1^n, S_1^n). \end{array} \right.$$

According to the standard theory of ordinary differential equations, the finite dimensional problem (3.1) has solution  $f_i^n(t), h_i^n(t), k_i^n(t)$  defined on  $[0, t)$ . The a priori estimates that follow imply that in fact  $t_n = T$ .

**Step 2: Energy estimates.**

Multiplying the first, the second and the third equation of (3.1) by  $(f_i^n(t))'$ ,  $(h_i^n(t))'$  and  $3(k_i^n(t))'$  respectively, we obtain

$$(3.2) \quad \begin{cases} \int_0^1 (w_{tt}^n w_t^n - G(3S^n - \xi^n - w_x^n)w_{xt}^n) dx = 0, \\ \int_0^1 (\xi_{tt}^n \xi_t^n - G(3S^n - \xi^n - w_x^n)\xi_t^n + D\xi_x^n \xi_{xt}^n) dx \\ \quad - \int_0^1 (\varpi_1(r) * \xi_x^n) \xi_{xt}^n dx = 0, \\ \int_0^1 3(S_{tt}^n S_t^n + 3G(3S^n - \xi^n - w_x^n)S_t^n + DS_x^n S_{xt}^n + 3\mu|S_t^n|^2) dx \\ \quad - \int_0^1 3(\varpi_2(r) * S_x^n) S_{xt}^n dx = 0. \end{cases}$$

Integrating (3.2) over  $(0, t)$ , then summing all the equations and using Lemma (2.1), we obtain

$$(3.3) \quad \begin{aligned} & \mathcal{E}_n(t) + 3\mu \int_0^t \int_0^1 |S_t^n|^2 dx dr - \frac{1}{2} \int_0^t \int_0^1 (\varpi'_1 \circ \xi_x^n) dx dr \\ & + \frac{1}{2} \int_0^t \int_0^1 \varpi_1(t) |\xi_x^n|^2 dx ds - \frac{3}{2} \int_0^t \int_0^1 (\varpi'_2 \circ S_x^n) dx dr \\ & + \frac{3}{2} \int_0^t \int_0^1 \varpi_2(t) |S_x^n|^2 dx ds \\ & = \mathcal{E}_n(0), \end{aligned}$$

where

$$(3.4) \quad \begin{aligned} \mathcal{E}_n(t) &= \frac{1}{2} \int_0^1 (\rho(w_t^n)^2(x, t) + I_\rho(\xi_t^n)^2(x, t) + dx \\ &+ 3I_\rho(S_t^n)^2(x, t) + G|3S^n - \xi^n - w_x^n|^2) dx \\ &+ \frac{1}{2} \int_0^1 (\beta_1(t)(\xi_x^n)^2 + \beta_2(t)(S_x^n)^2) dx \\ &+ \frac{1}{2} \int_0^1 (\varpi_1 \circ \xi_x^n) dx + \frac{3}{2} \int_0^1 (\varpi_2 \circ S_x^n) dx. \end{aligned}$$

Consequently, we have the following estimate

$$(3.5) \quad \begin{aligned} \mathcal{E}_n(t) &- \frac{1}{2} \int_0^t \int_0^1 (\varpi'_1 \circ \xi_x^n) dx dr + \frac{1}{2} \int_0^t \int_0^1 \varpi_1(t) |\xi_x^n|^2 dx ds \\ &- \frac{3}{2} \int_0^t \int_0^1 (\varpi'_2 \circ S_x^n) dx dr + \frac{3}{2} \int_0^t \int_0^1 \varpi_2(t) |S_x^n|^2 dx dr \\ &\leq \mathcal{E}_n(0). \end{aligned}$$

Now, since the sequences  $(w_0^n)_{n \in \mathbb{N}}$ ,  $(w_1^n)_{n \in \mathbb{N}}$ ,  $(\xi_0^n)_{n \in \mathbb{N}}$ ,  $(\xi_1^n)_{n \in \mathbb{N}}$ ,  $(S_0^n)_{n \in \mathbb{N}}$ ,  $(S_1^n)_{n \in \mathbb{N}}$  converge and using (A2), in both cases, we can find a positive constant  $c$  independent of  $n$  such that

$$(3.6) \quad \mathcal{E}_n(t) \leq c.$$

Therefore, using the fact that  $\beta_i(t) \geq \beta_i(0)$ , the estimate (3.6) together with (3.5) give us, for all  $n \in \mathbb{N}$ ,  $t_n = T$ ,

$$(3.7) \quad \begin{aligned} (w^n)_{n \in \mathbb{N}} &\text{ is bounded in } L^\infty(0, T; V), \\ (\xi^n)_{n \in \mathbb{N}} &\text{ is bounded in } L^\infty(0, T; V), \\ (S^n)_{n \in \mathbb{N}} &\text{ is bounded in } L^\infty(0, T; V), \\ (w_t^n)_{n \in \mathbb{N}} &\text{ is bounded in } L^\infty(0, T; V), \\ (\xi_t^n)_{n \in \mathbb{N}} &\text{ is bounded in } L^\infty(0, T; V), \\ (S_t^n)_{n \in \mathbb{N}} &\text{ is bounded in } L^\infty(0, T; V). \end{aligned}$$

Consequently, we conclude that

$$(3.8) \quad \begin{aligned} w^n &\rightharpoonup^* u \quad \text{in } L^\infty(0, T; V), \\ \xi^n &\rightharpoonup^* u \quad \text{in } L^\infty(0, T; V), \\ S^n &\rightharpoonup^* v \quad \text{in } L^\infty(0, T; V), \\ w_t^n &\rightharpoonup^* u_t \quad \text{in } L^\infty(0, T; V), \\ \xi_t^n &\rightharpoonup^* v_t \quad \text{in } L^\infty(0, T; V), \\ S_t^n &\rightharpoonup^* u_t \quad \text{in } L^\infty(0, T; V). \end{aligned}$$

From (3.7), we have  $(w^n)_{n \in \mathbb{N}}$ ,  $(\xi^n)_{n \in \mathbb{N}}$ ,  $(S^n)_{n \in \mathbb{N}}$  are bounded in  $L^\infty(0, T)$ . Then  $(w^n)_{n \in \mathbb{N}}$ ,  $(\xi^n)_{n \in \mathbb{N}}$ ,  $(S^n)_{n \in \mathbb{N}}$  are bounded in  $L^2(0, T; V)$ . Consequently,  $(w^n)_{n \in \mathbb{N}}$ ,  $(w^n)_{n \in \mathbb{N}}$ ,  $(S^n)_{n \in \mathbb{N}}$  are bounded in  $H^1(0, T; V)$ . Since the embedding

$$H^1(0, T; H^1(0, 1)) \hookrightarrow L^2(0, T; L^2(0, 1)),$$

is compact, using Aubin-Lion's theorem [7], we can extract subsequences  $(w^k)_{k \in \mathbb{N}}$  of  $(w^n)_{n \in \mathbb{N}}$ ,  $(\xi^k)_{k \in \mathbb{N}}$  of  $(\xi^n)_{n \in \mathbb{N}}$  and  $(S^k)_{k \in \mathbb{N}}$  of  $(S^n)_{n \in \mathbb{N}}$  such that

$$\begin{aligned} w^k &\rightarrow w \quad \text{strongly in } L^2(0, T; L^2(0, 1)), \\ \xi^k &\rightarrow \xi \quad \text{strongly in } L^2(0, T; L^2(0, 1)), \end{aligned}$$

and

$$S^k \rightarrow S \quad \text{strongly in } L^2(0, T; L^2(0, 1)).$$

Therefore,

$$\begin{aligned} w^k &\rightarrow w \quad \text{strongly and a.e } (0, T) \times (0, 1), \\ \xi^k &\rightarrow \xi \quad \text{strongly and a.e } (0, T) \times (0, 1), \end{aligned}$$

and

$$S^k \rightarrow S \quad \text{strongly and a.e } (0, T) \times (0, 1),$$

The proof now can be completed arguing as in Theorem 3.1 of [7].

□

## 4 Exponential stability

In this section we study the asymptotic behavior of the system (1.2). For the proof of Theorem 2.3 we need a several Lemmas.

**Lemma 4.1.** *Let  $(w, \xi, S)$  be the solution of (1.2), then we have the inequality*

$$(4.1) \quad \begin{aligned} \frac{d\mathcal{E}(t)}{dt} &\leq -3\mu \int_0^1 |S_t(x, t)|^2 dx - \frac{1}{2}\varpi_1(t) \int_{\Omega} |\xi_x(x, t)|^2 dx \\ &+ \frac{1}{2} \int_{\Omega} (\varpi'_1 \circ \xi_x)(x) dx - \frac{3}{2}\varpi_2(t) \int_{\Omega} |S_x(x, t)|^2 dx + \frac{3}{2} \int_{\Omega} (\varpi'_2 \circ S_x)(x) dx \\ &\leq 0. \end{aligned}$$

*Proof.* Multiplying the first, the second and the third equation of (1.2) by  $w_t$ ,  $\xi_t$  and  $3S_t$  respectively, then summing and integrating it over  $(0, t)$ , we obtain

$$(4.2) \quad \begin{aligned} &\frac{1}{2} \frac{d}{dt} \int_0^1 (\rho w_t^2(x, t) + I_{\rho} \xi_t^2(x, t) + dx + 3I_{\rho} S_t^2(x, t) \\ &+ G|3S - \xi - w_x|^2 + D\xi_x^2 + 3DS_x^2) dx \\ &= -3\mu \int_0^1 |S_t|^2 dx + \int_0^1 \int_0^t \varpi_1(r) \xi_x(r) \xi_x(t) dr dx \\ &+ 3 \int_0^1 \int_0^t \varpi_2(r) S_x(r) S_x(t) dr dx. \end{aligned}$$

Owing to Lemma 2.1, the last term in the RHS of (4.2) can be rewritten as

$$(4.3) \quad \begin{aligned} &\int_0^t \varpi_1(r) \int_0^1 \xi_x(r) \xi_x(t) dr dx + \frac{1}{2} \varpi_1(t) \int_0^1 |\xi_x|^2(x, t) dx \\ &= \frac{1}{2} \frac{d}{dt} \left( \int_0^t \varpi_1(r) dr \int_0^1 |\xi_x|^2(x, t) dx - \int_0^1 (\varpi_1 \circ \xi_x)(t) dx \right) \\ &+ \frac{1}{2} \int_0^1 (\varpi'_1 \circ \xi_x)(t) dx, \end{aligned}$$

and

$$(4.4) \quad \begin{aligned} &\int_0^t \varpi_2(r) \int_0^1 S_x(r) \xi_x(t) dr dx + \frac{1}{2} \varpi_2(t) \int_0^1 |S_x|^2(x, t) dx \\ &= \frac{1}{2} \frac{d}{dt} \left( \int_0^t \varpi_2(r) dr \int_0^1 |S_x|^2(x, t) dx - \int_0^1 (\varpi_2 \circ S_x)(t) dx \right) \\ &+ \frac{1}{2} \int_0^1 (\varpi'_2 \circ S_x)(t) dx. \end{aligned}$$

So, from (2.2),  $\frac{dE}{dt}$  becomes

$$(4.5) \quad \begin{aligned} \frac{d\mathcal{E}}{dt} &= -3\mu \int_0^1 |S_t|^2 dx - \frac{1}{2}\varpi_1(t) \int_0^1 |\xi_x|^2(x, t) dx \\ &+ \frac{1}{2} \int_0^1 (\varpi'_1 \circ \xi_x)(t) dx - \frac{3}{2}\varpi_2(t) \int_0^1 |S_x|^2(x, t) dx + \frac{3}{2} \int_0^1 (\varpi'_2 \circ S_x)(t) dx. \end{aligned}$$

This completes the proof.  $\square$

Now, we define a functional  $F_1$  as follows

$$(4.6) \quad F_1(t) = - \int_0^1 (\rho w w_t + I_\rho \xi \xi_t + 3I_\rho S S_t + \frac{3}{2} \mu S^2) dx.$$

Then, we have the following estimate

**Lemma 4.2.**

$$(4.7) \quad \begin{aligned} F'_1(t) &\leq - \int_0^1 (\rho w_t^2 + I_\rho \xi_t^2 + 3I_\rho S_t^2) dx + G \int_0^1 |3S - \xi - w_x|^2 dx \\ &\quad + c \int_0^1 \xi_x^2 dx + c \int_0^1 S_x^2 dx + c \int_0^1 (\varpi_1 \circ \xi_x) dx + c \int_0^1 (\varpi_2 \circ S_x) dx. \end{aligned}$$

*Proof.* Taking the derivative of  $F_1(t)$  with respect to  $t$  and using (1.2), we find that

$$(4.8) \quad \begin{aligned} F'_1(t) &= - \int_0^1 (\rho w_t^2 + I_\rho \xi_t^2 + 3I_\rho S_t^2) dx + G \int_0^1 w(3S - \xi - w_x)_x dx \\ &\quad - \int_0^1 \xi \left( G(3S - \xi - w_x) + D\xi_{xx} - \int_0^t \varpi_1(r) \xi_{xx}(t-r) dr \right) dx \\ &\quad - \int_0^1 3S \left( DS_{xx} - G(3S - \xi - w_x) - \mu S_t - \int_0^t \varpi_2(r) S_{xx}(t-r) dr \right) dx \\ &\quad - 3\mu \int_0^1 S_t S dx \\ &= - \int_0^1 (\rho w_t^2 + I_\rho \xi_t^2 + 3I_\rho S_t^2) dx + G \int_0^1 |3S - \xi - w_x|^2 dx \\ &\quad + D \int_0^1 \xi_x^2 dx + 3D \int_0^1 S_x^2 dx \\ &\quad - \int_0^1 \xi_x(x, t) \left( \int_0^t \varpi_1(r) \xi_x(t-r) dr \right) dx \\ &\quad - 3 \int_0^1 S_x(x, t) \left( \int_0^t \varpi_2(r) S_x(t-r) dr \right) dx. \end{aligned}$$

Using the fact that

$$(4.9) \quad \begin{aligned} &\int_0^1 \int_0^t \varpi_1(r) |\xi_x(s) - \xi_x(t)| |\xi_x(x, t)| dr dx \\ &\leq \delta \int_0^1 |\xi_x|^2(x, t) dx + \frac{1}{4\delta} \int_0^1 \left( \int_0^t \varpi_1(r) |\xi_x(s) - \xi_x(t)| dr \right)^2 dx \\ &\leq \delta \int_0^1 |\xi_x|^2(x, t) dx + \frac{D - \beta_1(t)}{4\delta} \int_0^1 (\varpi_1 \circ \xi_x)(t) d. \end{aligned}$$

and

$$(4.10) \quad \begin{aligned} &\int_0^1 \int_0^t \varpi_2(r) |S_x(s) - S_x(t)| |S_x(x, t)| dr dx \\ &\leq \delta \int_0^1 |S_x|^2(x, t) dx + \frac{D - \beta_2(t)}{4\delta} \int_0^1 (\varpi_2 \circ S_x)(t) dx. \end{aligned}$$

Inserting the estimate (4.9), (4.10) into (4.8) and using Young's, Poincaré's inequalities lead to the desired estimate.

This completes the proof.  $\square$

**Lemma 4.3.** *Let  $(w, \xi, S)$  be the solution of (1.2). Assume that*

$$(4.11) \quad \frac{\rho}{G} = \frac{I_\rho}{D}.$$

*Then the functional  $F_2$  defined by*

$$(4.12) \quad \begin{aligned} F_2(t) &= -I_\rho \int_0^1 (w_t \xi_x + 3w_t S_x) dx + I_\rho \int_0^1 \xi_t (3S - \xi - w_x) dx \\ &+ 3I_\rho \int_0^1 S_t (3S - \xi - w_x) dx + \frac{\rho}{G} \int_0^1 w_t \int_0^t \varpi_1(t-r) \xi_x(r) dr dx \\ &+ \frac{3\rho}{G} \int_0^1 w_t \int_0^t \varpi_2(t-r) S_x(r) dr dx, \end{aligned}$$

*satisfies the following estimate*

$$(4.13) \quad \begin{aligned} F'_2(t) &\leq - \left[ (D\xi_x - \int_0^t \varpi_1(t-r) \xi_x(r) dr) w_x \right]_{x=0}^{x=1} \\ &- 3 \left[ (DS_x - \int_0^t \varpi_2(t-r) S_x(r) dr) w_x \right]_{x=0}^{x=1} \\ &+ c \int_0^1 w_t^2 dx - I_\rho \int_0^1 \xi_t^2 dx + c \int_0^1 S_t^2 dx dx + c \int_0^1 \xi_x^2 dx + c \int_0^1 S_x^2 dx \\ &- (2G - \frac{3}{2}\mu) \int_0^1 |3S - \xi - w_x|^2 dx + c \int_0^1 (\varpi'_1 \circ \xi_x) dx + c \int_0^1 (\varpi'_2 \circ S_x) dx. \end{aligned}$$

*Proof.* Taking the derivative of  $F_2(t)$  with respect to  $t$ , using (1.2) and some integrations by parts, we obtain

$$(4.14) \quad \begin{aligned} F'_2(t) &= - \left[ (D\xi_x - \int_0^t \varpi_1(t-r) \xi_x(r) dr) w_x \right]_{x=0}^{x=1} \\ &- 3 \left[ (DS_x - \int_0^t \varpi_2(t-r) S_x(r) dr) w_x \right]_{x=0}^{x=1} \\ &- 2G \int_0^1 |3S - \xi - w_x|^2 dx - I_\rho \int_0^1 \xi_t^2 dx + 9I_\rho \int_0^1 S_t^2 dx \\ &- 3\mu \int_0^1 (3S - \xi - w_x) S_t dx + \frac{\rho}{G} \varpi_1(t) \int_0^1 w_t \xi_x dx \\ &+ \frac{\rho}{G} \int_0^1 w_t \left( \int_0^t \varpi'_1(t-r) \xi_x(t-r) dr \right) dx + \frac{3\rho}{G} \varpi_1(t) \int_0^1 w_t S_x dx \\ &+ \frac{3\rho}{G} \int_0^1 w_t \left( \int_0^t \varpi'_2(t-r) S_x(t-r) dr \right) dx. \end{aligned}$$

By (4.9), (4.10) and using Young, Poincaré's inequalities lead to the desired estimate. This completes the proof.  $\square$

**Lemma 4.4.** *Let  $m \in C^1([0, 1])$  be a function satisfying  $m(0) = -m(1) = 2$ . Then there exists  $c > 0$  such that, for any  $0 < \varepsilon < 1$ , the functional  $F_3$  defined by*

$$(4.15) \quad \begin{aligned} F_3(t) = & \frac{1}{4\varepsilon} \int_0^1 I_\rho m(x) \xi_x \left( D\xi_x - \int_0^t \varpi_1(t-r) \xi_x(r) dr \right) dx + \frac{4\varepsilon}{G} \int_0^1 \rho m(x) w_t w_x dx \\ & + \frac{3}{4\varepsilon} \int_0^1 I_\rho m(x) S_t \left( DS_x - \int_0^t \varpi_2(t-r) S_x(r) dr \right) dx, \end{aligned}$$

satisfies the following estimate

$$(4.16) \quad \begin{aligned} F'_3(t) \leq & -\frac{1}{4\varepsilon} \left[ \left( D\xi_x(1, t) - \int_0^t \varpi_1(t-r) \xi_x(1, t-r) dr \right)^2 \right. \\ & + \left. \left( D\xi_x(0, t) - \int_0^t \varpi_1(t-r) \xi_x(0, t-r) dr \right)^2 \right] \\ & -\frac{3}{4\varepsilon} \left[ \left( DS_x(1, t) - \int_0^t \varpi_2(t-r) S_x(1, t-r) dr \right)^2 \right. \\ & + \left. \left( DS_x(0, t) - \int_0^t \varpi_2(t-r) S_x(0, t-r) dr \right)^2 \right] \\ & -4\varepsilon(w_x^2(1, t) + w_x^2(0, t)) \\ & + \frac{2\rho\varepsilon c}{G} \int_0^1 w_t^2 dx + c \int_0^1 \xi_t^2 dx + c \int_0^1 S_t^2 dx dx \\ & + c \int_0^1 \xi_x^2 dx + c \int_0^1 S_x^2 dx + Gc \int_0^1 |3S - \xi - w_x|^2 dx \\ & + c \int_0^1 (\varpi_1 \circ \xi_x) dx + c \int_0^1 (\varpi_2 \circ S_x) dx \\ & + c \int_0^1 (\varpi'_1 \circ \xi_x) dx + c \int_0^1 (\varpi'_2 \circ S_x) dx. \end{aligned}$$

*Proof.* Taking the derivative of  $F_3(t)$  with respect to  $t$ , using (1.2) and some integra-

tions by parts, we obtain

$$\begin{aligned}
F'_3(t) = & \frac{1}{4\varepsilon} \left[ \frac{1}{2}m(x) \left( D\xi_x(x, t) - \int_0^t \varpi_1(t-r)\xi_x(x, t-r) dr \right)^2 \right]_{x=0}^{x=1} \\
& - \frac{1}{4\varepsilon} \int_0^1 \frac{1}{2}m'(x) \left( D\xi_x - \int_0^t \varpi_1(t-r)\xi_x(r) dr \right)^2 dx \\
& + \frac{G}{4\varepsilon} \int_0^1 m(x)(3S - \xi - w_x) \left( D\xi_x - \int_0^t \varpi_1(t-r)\xi_x(r) dr \right) dx \\
& - \frac{I_\rho D}{4\varepsilon} \int_0^1 \frac{1}{2}m'(x)\xi_t^2 dx \\
& - \frac{I_\rho}{4\varepsilon} \varpi_1(t) \int_0^1 \xi_t \xi_x dx - \frac{I_\rho}{4\varepsilon} \int_0^1 m(x)\xi_t \left( \int_0^t \varpi_1'(t-r)\xi_x(t-r) dr \right) dx \\
& + \frac{3}{4\varepsilon} \left[ \frac{1}{2}m(x) \left( DS_x(x, t) - \int_0^t \varpi_2(t-r)S_x(x, t-r) dr \right)^2 \right]_{x=0}^{x=1} \\
(4.17) \quad & - \frac{3}{4\varepsilon} \int_0^1 \frac{1}{2}m'(x) \left( DS_x - \int_0^t \varpi_2(t-r)S_x(r) dr \right)^2 dx \\
& - \frac{3G}{4\varepsilon} \int_0^1 m(x)(3S - \xi - w_x) \left( DS_x - \int_0^t \varpi_2(t-r)S_x(r) dr \right) dx \\
& - \frac{3\mu}{4\varepsilon} \int_0^1 m(x)S_t \left( DS_x - \int_0^t \varpi_2(t-r)S_x(r) dr \right) dx \\
& - \frac{3I_\rho D}{4\varepsilon} \int_0^1 \frac{1}{2}m'(x)S_t^2 dx - \frac{3I_\rho}{4\varepsilon} \varpi_2(t) \int_0^1 S_t S_x dx \\
& - \frac{3I_\rho}{4\varepsilon} \int_0^1 m(x)S_t \left( \int_0^t \varpi_2'(t-r)S_x(t-r) dr \right) dx \\
& - \frac{2\varepsilon\rho D}{G} \int_0^1 \frac{1}{2}m'(x)w_t^2 dx - 12\varepsilon \int_0^1 \frac{1}{2}m(x)w_x S_x dx \\
& + 4\varepsilon \int_0^1 \frac{1}{2}m(x)w_x \xi_x dx - 4\varepsilon \int_0^1 \frac{1}{2}m'(x)w_x^2 dx + 4\varepsilon \left[ -(w_x^2(1, x) + w_x^2(0, x)) \right].
\end{aligned}$$

Then by Young's, Poincaré's inequalities and using (4.9), (4.10) and the fact that

$$w_x^2 \leq 2(3S - \xi - w_x)^2 + 36cS_x + c\xi_x,$$

leads to the desired estimate.  $\square$

**Lemma 4.5.** *Assume that (A1) hold. Then, the functional  $F(t)$  defined by*

$$F(t) = F_1(t) + F_2(t) + F_3(t),$$

satisfies, along the solution, the estimate

$$\begin{aligned}
 F'(t) &\leq -(\rho - 2c) \int_0^1 w_t^2 dx - (2I_\rho - c) \int_0^1 \xi_t^2 dx \\
 &\quad + c - (3I_\rho - 2c) \int_0^1 S_t^2 dx \\
 (4.18) \quad &- \{G(1 - c) - \frac{3}{2}\mu\} \int_0^1 |3S - \xi - w_x|^2 dx + c \int_0^1 \xi_x^2 dx \\
 &\quad + c \int_0^1 S_x^2 dx + c \int_0^1 (\varpi_1 \circ \xi_x) dx + c \int_0^1 (\varpi_2 \circ S_x) dx \\
 &\quad + c \int_0^1 (\varpi'_1 \circ \xi_x) dx + c \int_0^1 (\varpi'_2 \circ S_x) dx.
 \end{aligned}$$

*Proof.* Using (4.7), (4.13), (4.16) and the fact that

$$\begin{aligned}
 &\left[ (D\xi_x - \int_0^t \varpi_1(t-r)\xi_x(r) dr)w_x \right]_{x=0}^{x=1} \\
 &- 3 \left[ (DS_x - \int_0^t \varpi_2(t-r)S_x(r) dr)w_x \right]_{x=0}^{x=1} \\
 (4.19) \quad &\leq \frac{1}{4\varepsilon} \left[ (D\xi_x(1,t) - \int_0^t \varpi_1(t-r)\xi_x(1,r) dr)^2 \right] \\
 &+ \frac{1}{4\varepsilon} \left[ (D\xi_x(0,t) - \int_0^t \varpi_1(t-r)\xi_x(0,r) dr)^2 \right] \\
 &+ \frac{3}{4\varepsilon} \left[ (DS_x(0,t) - \int_0^t \varpi_2(t-r)S_x(0,r) dr)^2 \right] \\
 &+ \frac{3}{4\varepsilon} \left[ (DS_x(1,t) - \int_0^t \varpi_2(t-r)S_x(1,r) dr)^2 \right] \\
 &+ 4\varepsilon \left[ w_x^2(1) + w_x^2(0) \right],
 \end{aligned}$$

for any  $0 < \varepsilon < 1$ , we obtain (4.18).

This completes the proof.  $\square$

Next, we introduce the following functional

$$(4.20) \quad D(t) = \int_0^1 (I_\rho \xi \zeta_t \psi + \rho w_t \sigma + I_\rho S S_t - \rho w_t \theta + \frac{\mu}{2} S^2) dx,$$

where  $\sigma, \theta$  are the solutions of

$$\begin{aligned}
 (4.21) \quad &-\sigma_{xx} = \xi_x, \quad \sigma(0) = \sigma(1) = 0, \\
 &-\theta_{xx} = S_x, \quad \theta(0) = \theta(1) = 0.
 \end{aligned}$$

Then we have the following estimate

**Lemma 4.6.**

$$\begin{aligned}
 D(t) &\leq c(\delta) \int_0^1 \xi_t^2 dx + \rho \delta \int_0^1 w_t^2 dx + c(\delta) \int_0^1 S_t^2 dx \\
 (4.22) \quad &- (D - \int_0^\infty \varpi_1(r) dr - \delta) \int_0^1 \xi_x^2 dx \\
 &- (D - \int_0^\infty \varpi_2(r) dr - \delta) \int_0^1 S_x^2 dx \\
 &+ c \int_0^1 (\varpi_1 \circ \xi_x) dx + c \int_0^1 (\varpi_2 \circ S_x) dx.
 \end{aligned}$$

*Proof.* Using Equation (1.2), we find that

$$\begin{aligned}
 D'(t) &= I_\rho \int_0^1 \xi_t^2 dx + \rho \int_0^1 w_t^2 \sigma_t dx - (D - \int_0^\infty \varpi_1(r) dr) \int_0^1 \xi_x^2 dx - G \int_0^1 \xi^2 dx \\
 &- G \int_0^1 \xi w_x dx + 3G \int_0^1 \xi S dx - 3G \int_0^1 \sigma S_x dx - G \int_0^1 \xi_x \sigma dx + G \int_0^1 \sigma w_{xx} dx \\
 &- G \int_0^1 \sigma_t w_t dx + \int_0^1 \left( \int_0^t \varpi_1(t-r)(\xi_x(s) - \xi_x(t)) ds \right) \xi_x dx + I_\rho \int_0^1 S_t^2 dx \\
 &- \rho \int_0^1 w_t^2 \theta_t dx - (D - \int_0^\infty \varpi_2(r) dr) \int_0^1 S_x^2 dx - 3G \int_0^1 S^2 dx + G \int_0^1 S \xi dx \\
 &+ G \int_0^1 S w_x dx + 3G \int_0^1 \theta S_x dx - G \int_0^1 \theta \xi_x dx - G \int_0^1 \theta w_{xx} dx \\
 (4.23) \quad &+ \int_0^1 \left( \int_0^t \varpi_2(t-r)(S_x(s) - S_x(t)) ds \right) S_x dx.
 \end{aligned}$$

Integrating by parts and (4.21), we obtain

$$\begin{aligned}
 D'(t) &= I_\rho \int_0^1 \xi_t^2 dx + \rho \int_0^1 w_t^2 \sigma_t dx - (D - \int_0^\infty \varpi_1(r) dr) \int_0^1 \xi_x^2 dx \\
 (4.24) \quad &+ \int_0^1 \left( \int_0^t \varpi_1(t-r)(\xi_x(s) - \xi_x(t)) ds \right) \xi_x dx + I_\rho \int_0^1 S_t^2 dx - \rho \int_0^1 w_t^2 \theta_t dx \\
 &- (D - \int_0^\infty \varpi_2(r) dr) \int_0^1 S_x^2 dx + \int_0^1 \left( \int_0^t \varpi_2(t-r)(S_x(s) - S_x(t)) ds \right) S_x dx.
 \end{aligned}$$

Observing that, for  $\delta > 0$

$$(4.25) \quad \int_0^1 \left( \int_0^t \varpi_1(t-r)(\xi_x(s) - \xi_x(t)) ds \right) \xi_x dx \leq c(\delta) \int_0^1 (\varpi_1 \circ \xi_x) dx + \delta \int_0^1 \xi_x^2 dx,$$

and

$$(4.26) \quad \int_0^1 \sigma_t^2 dx \leq \int_0^1 \sigma_{tx}^2 dx \leq \int_0^1 \xi_t^2 dx.$$

Young's inequality and (4.25), (4.26) yield then the desired result.  $\square$

*Proof.* (Of Theorem 2.3) We define the Lyapunov functional

$$(4.27) \quad \mathcal{L}(t) = N_1 \mathcal{E}(t) + N_2 F(t) + D(t),$$

where  $N_1$  and  $N_2$  are positive constants that will be fixed later.

Taking the derivative of (4.27) with respect to  $t$  and making use of (4.1), (4.18) and (4.23), we obtain

$$\begin{aligned} \frac{d}{dt} \mathcal{L}(t) &\leq -\{N_2(\rho - 2c) - \rho\delta\} \int_0^1 w_t^2 dx - \{N_2(2I_\rho - c) - c(\delta)\} \int_0^1 \xi_t^2 dx \\ &\quad - \{3N_1\mu + N_2(3I_\rho - 2c) - c(\delta)\} \int_0^1 S_t^2 dx \\ (4.28) \quad &\quad - \left\{ \frac{1}{2}\varpi_1(t)N_1 + (\beta_1^0 - \delta) - cN_2 \right\} \int_0^1 \xi_x^2 dx \\ &\quad - \left\{ \frac{3}{2}\varpi_2(t)N_1 + (\beta_2^0 - \delta) - cN_2 \right\} \int_0^1 S_x^2 dx \\ &\quad - N_2\{G(1 - c) - \frac{3}{2}\mu\} \int_0^1 |3s - \xi - w_x|^2 dx \\ &\quad + c \int_0^1 (\varpi_1 \circ \xi_x) dx + c \int_0^1 (\varpi_2 \circ S_x) dx + c \int_0^1 (\varpi'_1 \circ \xi_x) dx + c \int_0^1 (\varpi'_2 \circ S_x) dx. \end{aligned}$$

At this point, we choose our constants in (4.28), carefully, such that all the coefficients in (4.28) will be negative. We first choose  $N_2$  satisfying

$$N_2(\rho - 2c) - \rho\delta > 0,$$

and

$$N_2(2I_\rho - c) - c(\delta) > 0.$$

Then, we pick the constant  $N_1$  sufficiently large such that

$$3N_1\mu + N_2(3I_\rho - 2c) - c(\delta) > 0,$$

and

$$\frac{1}{2}\varpi_1(t)N_1 + (\beta_1^0 - \delta) - cN_2 > 0,$$

and

$$\frac{3}{2}\varpi_2(t)N_1 + (\beta_2^0 - \delta) - cN_2 > 0.$$

Consequently, from the above, we deduce that there exist positive constants  $\eta_1$ ,  $\eta_2$  and  $\eta_3$  such that (4.28) becomes

$$(4.29) \quad \frac{d\mathcal{L}(t)}{dt} \leq -\eta_1 \mathcal{E}(t) + \eta_2 \int_{\Omega} (\varpi_1 \circ \xi_x) dx + \eta_3 \int_{\Omega} (\varpi_2 \circ \nabla v) dx.$$

Therefore, if  $\chi(t) = \min\{\chi_1(t), \chi_2(t)\}$ ,  $\forall t \geq 0$ , then using (A2) and (4.1), we get

$$\begin{aligned}
 \xi(t)\mathcal{L}'(t) &\leq -\eta_1\chi(t)\mathcal{E}(t) + \eta_2\chi(t)\int_{\Omega}(\varpi_1 \circ \xi_x)dx + \eta_3\xi(t)\int_{\Omega}(\varpi_2 \circ S_x)dx \\
 &\leq -\eta_1\chi(t)\mathcal{E}(t) + \eta_2\chi_1(t)\int_{\Omega}(\varpi_1 \circ \xi_x)dx + \eta_3\chi_2(t)\int_{\Omega}(\varpi_2 \circ S_x)dx \\
 &\leq -\eta_1\chi(t)\mathcal{E}(t) + \eta_2\int_{\Omega}\int_0^t\chi_1(t-r)\varpi_1(t-r)|\xi_x(t) - \xi_x(r)|^2drdx \\
 (4.30) \quad &+ \eta_3\int_{\Omega}\int_0^t\chi_2(t-r)\varpi_2(t-r)|S_x(t) - S_x(r)|^2drdx \\
 &\leq -\eta_1\chi(t)\mathcal{E}(t) - \eta_2\int_{\Omega}\int_0^t\varpi_1'(t-r)|\xi_x(t) - \xi_x(r)|^2drdx \\
 &- \eta_3\int_{\Omega}\int_0^t\varpi_2'(t-r)|S_x(t) - S_x(s)|^2drdx \\
 &\leq -\eta_1\xi(t)\mathcal{E}(t) - c\mathcal{E}'(t), \quad \forall t \geq 0.
 \end{aligned}$$

Which gives

$$(\chi(t)\mathcal{L}(t) + c\mathcal{E}(t))' - \chi'(t)\mathcal{L}(t) \leq -\eta_1\chi(t)\mathcal{E}(t).$$

Using the fact that  $\chi'(t) \leq 0$ ,  $\forall t \geq 0$  and letting

$$(4.31) \quad J(t) = \chi(t)\mathcal{L}(t) + c\mathcal{E}(t) \sim \mathcal{E}(t),$$

we obtain

$$(4.32) \quad J'(t) \leq -\eta_1\chi(t)\mathcal{E}(t) \leq -\eta_3\chi(t)J(t).$$

A simple integration of (4.32) over  $(0, t)$  leads to

$$(4.33) \quad J(t) \leq J(0)e^{-\eta_3\int_0^t\chi(r)dr} \quad \forall t \geq 0.$$

A combination of (4.31) and (4.33) leads to (2.3).

This completes the proof.  $\square$

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