

Notes on the Z-transform, part 2¹

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1 The unit pulse

Another entry to the table of standard Z-transforms is supplied by the unit pulse

$$(\delta_k)_{k=0}^{\infty} = (1, 0, 0, 0, \dots) \quad (1)$$

so only the first term of this sequence is non-zero: $x_0 = 1$ and $x_k = 0$ for all $k > 0$. The Z-transform of this sequence can be worked out directly, remember the definition of the Z-transform

$$\mathcal{Z}[(x_k)_{k=0}^{\infty}] = \sum_{z=0}^{\infty} \frac{x_k}{z^k}. \quad (2)$$

In this case there is only one term in the sequence and hence only one term in the sum:

$$\mathcal{Z}[(\delta_k)_{k=0}^{\infty}] = \frac{1}{z^0} = 1 \quad (3)$$

2 Linearity of the Z-transform

It is possible to add sequences and to multiply them by constants. Say $(x_k)_{k=0}^{\infty}$ and $(y_k)_{k=0}^{\infty}$ are two sequences and a and b are two constants then we have a sequence

$$(ax_k + by_k)_{k=0}^{\infty} = a(x_k)_{k=0}^{\infty} + b(y_k)_{k=0}^{\infty} \quad (4)$$

For example

$$(2^k + 3)_{k=0}^{\infty} = (4, 5, 7, 11, \dots) \quad (5)$$

is the sum of the sequence $(2^k) = (1, 2, 4, 8, \dots)$ and the sequence $(3, 3, 3, \dots)$. Another example is the sequence (ar^k) which is a times the sequence (r^k) .

The Z-transform is linear. This means that

$$\mathcal{Z}[(ax_k + by_k)_{k=0}^{\infty}] = a\mathcal{Z}[(x_k)_{k=0}^{\infty}] + b\mathcal{Z}[(y_k)_{k=0}^{\infty}] \quad (6)$$

Hence, for example,

$$\begin{aligned} \mathcal{Z}[(4, 5, 7, 11, \dots)] &= \mathcal{Z}[(2^k + 3)_{k=0}^{\infty}] = \mathcal{Z}[(2^k)_{k=0}^{\infty}] + 3\mathcal{Z}[(1, 1, 1, \dots)] \\ &= \frac{z}{z-2} + \frac{3z}{z-1} = \frac{z(z-1) + 3z(z-2)}{(z-2)(z-1)} \end{aligned}$$

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$$= \frac{4z^2 - 7z}{z^2 - 3z + 2} \quad (7)$$

Another general example is

$$\mathcal{Z}[(ar^k)_{k=0}^\infty] = a\mathcal{Z}[(r^k)_{k=0}^\infty] = \frac{az}{z-r} \quad (8)$$

3 The delay theorem or first shift theorem

A delayed sequence is one that starts later than some other known sequence. It has the form $(x_{k-k_0})_{k=0}^\infty$ so for $k < k_0$ the subscript is negative and, since $x_j = 0$ for $j < 0$, all the entries up to $k = k_0$ are zero. Here is an example, say

$$(x_k)_{k=0}^\infty = (4, 5, 7, 11, \dots) \quad (9)$$

then

$$(x_{k-2})_{k=0}^\infty = (0, 0, 4, 5, 7, 11, \dots) \quad (10)$$

so, the sequence is delayed by $k_0 = 2$ steps. Here is another example,

$$(\delta_{k-4})_{k=0}^\infty = (0, 0, 0, 0, 1, 0, 0, 0, \dots) \quad (11)$$

In this example the unit pulse has been delayed by four steps.

The delay theorem tells us how to related the Z-tranform of a delayed sequence to the Z-tranform of the corresponding undelayed sequence. It states that

$$\mathcal{Z}[(x_{k-k_0})] = \frac{1}{z^{k_0}} \mathcal{Z}[(x_k)] \quad (12)$$

This theorem is also called the first shift theorem for Z-transforms. It is easy enough to prove. By definition

$$\mathcal{Z}[(x_{k-k_0})] = \sum_{k=0}^{\infty} \frac{x_{k-k_0}}{z^k} \quad (13)$$

Now do a change of index: let $k' = k - k_0$. Hence, $k = k' + k_0$; when $k = 0$, $k' = -k_0$ and when $k = \infty$, $k' = \infty$. Thus

$$\mathcal{Z}[(x_{k-k_0})] = \sum_{k'=-k_0}^{\infty} \frac{x_{k'}}{z^{k'+k_0}} \quad (14)$$

However, because $x_{k'} = 0$ for $k' < 0$ the sum starts at $k' = 0$. Thus

$$\mathcal{Z}[(x_{k-k_0})] = \sum_{k'=0}^{\infty} \frac{x_{k'}}{z^{k'+k_0}} = \frac{1}{z^{k_0}} \sum_{k'=0}^{\infty} \frac{x_{k'}}{z^{k'}} = \frac{1}{z^{k_0}} \mathcal{Z}[(x_k)] \quad (15)$$

as required.

Here is an example: the sequence $(0, 0, 1, 3, 9, 27, \dots) = (x_{k-2})_{k=0}^{\infty}$ where $(x_k)_{k=0}^{\infty} = (3^k)_{k=0}^{\infty} = (1, 3, 9, 27, \dots)$ so the Z-transform is

$$\mathcal{Z}[(0, 0, 1, 3, 9, 27, \dots)] = \frac{1}{z^2} \mathcal{Z}[(1, 3, 9, 27, \dots)] = \frac{1}{z^2} \frac{z}{z-3} \quad (16)$$

Here is another example, consider

$$\mathcal{Z}[(\delta_{k-4})_{k=0}^{\infty}] = \frac{1}{z^4} \mathcal{Z}[(\delta_k)] = \frac{1}{z^4} \quad (17)$$

since $\mathcal{Z}[(\delta_k)] = 1$. The sequence $(0, 1, 1, 1, 1, \dots)$ is the one step delay of $(1, 1, 1, 1, \dots)$ so we have

$$\mathcal{Z}[(0, 1, 1, 1, 1, \dots)] = \frac{1}{z} \mathcal{Z}[(1, 1, 1, 1, \dots)] = \frac{1}{z} \frac{z}{z-1} = \frac{1}{z-1} \quad (18)$$

There is another way of doing the same question: by using linearity. We can write

$$(0, 1, 1, 1, 1, \dots) = (1, 1, 1, 1, \dots) - (1, 0, 0, 0, \dots) \quad (19)$$

so

$$\begin{aligned} \mathcal{Z}[(0, 1, 1, 1, 1, \dots)] &= \mathcal{Z}[(1, 1, 1, 1, \dots)] - \mathcal{Z}[(1, 0, 0, 0, \dots)] \\ &= \frac{z}{z-1} - 1 = \frac{z - (z-1)}{z-1} = \frac{1}{z-1} \end{aligned} \quad (20)$$

4 Exercises

Work out the Z-transform of the following sequences

1. $(2, 4, 10, 28, \dots)$
2. $(2, -2, 10, -26, \dots)$
3. $(3, 0, 0, 0, \dots)$
4. $(0, 0, 1, 1, 1, \dots)$
5. $(0, 2, 4, 10, 28, \dots)$
6. $(0, 0, 1, 2, 4, 8, \dots)$
7. $(1, 1, 0, 1, 1, 1, \dots)$

1. So this sequence is

$$(2, 4, 10, 28, \dots) = (1, 1, 1, 1, \dots) + (1, 3, 9, 27, \dots) \quad (21)$$

so we use linearity

$$\begin{aligned} \mathcal{Z}[(2, 4, 10, 28, \dots)] &= \mathcal{Z}[(1, 1, 1, 1, \dots)] + \mathcal{Z}[(1, 3, 9, 27, \dots)] \\ &= \frac{z}{z-1} + \frac{z}{z-3} = \frac{2z^2 - 4z}{z^2 - 4z + 3} \end{aligned} \quad (22)$$

2. So this sequence is

$$(2, -2, 10, -26, \dots) = (1, 1, 1, 1, \dots) + (1, -3, 9, -27, \dots) \quad (23)$$

so we use linearity

$$\begin{aligned} \mathcal{Z}[(2, -2, 10, -27, \dots)] &= \mathcal{Z}[(1, 1, 1, 1, \dots)] + \mathcal{Z}[(1, -3, 9, -27, \dots)] \\ &= \frac{z}{z-1} + \frac{z}{z+3} = \frac{2z^2 + 2z}{z^2 + 2z - 3} \end{aligned} \quad (24)$$

3. $(3, 0, 0, 0, \dots) = 3(\delta_k)$ so $\mathcal{Z}[(3, 0, 0, 0, \dots)] = 3$.

4. $(0, 0, 1, 1, 1, \dots)$ is the $k_0 = 2$ delay of $(1, 1, 1, 1, \dots)$ which means that

$$\mathcal{Z}[(0, 0, 1, 1, 1, \dots)] = \frac{1}{z^2} \frac{z}{z-1} \quad (25)$$

5. $(0, 2, 4, 10, 28, \dots)$ is (x_{k-1}) where $(x_k) = (2, 4, 10, 28, \dots)$ as in first exercise, hence,

$$\mathcal{Z}[(0, 2, 4, 10, 28, \dots)] = \frac{1}{z} \frac{2z^2 - 4z}{z^2 - 4z + 3} = \frac{2z - 4}{z^2 - 4z + 3} \quad (26)$$

6. $(0, 0, 1, 2, 4, 8, \dots) = (2^{k-2})$ and $\mathcal{Z}[(2^k)] = z/(z-2)$, so,

$$\mathcal{Z}[(0, 0, 1, 2, 4, 8, \dots)] = \frac{1}{z^2} \frac{z}{z-2} = \frac{1}{z(z-2)} \quad (27)$$

7. This one is a bit trickier. Notice that

$$(1, 1, 0, 1, 1, 1, \dots) = (1, 1, 1, 1, 1, \dots) - (0, 0, 1, 0, 0, \dots) \quad (28)$$

and $(0, 0, 1, 0, 0, \dots) = (\delta_{k-2})$. Hence, using linearity and the delay theorem we get

$$\begin{aligned} \mathcal{Z}[(1, 1, 0, 1, 1, 1, \dots)] &= \mathcal{Z}[(1, 1, 1, 1, 1, \dots)] - \mathcal{Z}[(0, 0, 1, 0, 0, \dots)] \\ &= \frac{z}{z-1} - \frac{1}{z^2} = \frac{z^3 - z + 1}{z^2(z-1)} \end{aligned} \quad (29)$$