Research Article

Power Prior Elicitation in Bayesian Quantile Regression

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We address a quantile dependent prior for Bayesian quantile regression. We extend the idea of the power prior distribution in Bayesian quantile regression by employing the likelihood function that is based on a location-scale mixture representation of the asymmetric Laplace distribution. The propriety of the power prior is one of the critical issues in Bayesian analysis. Thus, we discuss the propriety of the power prior in Bayesian quantile regression. The methods are illustrated with both simulation and real data.

1. Introduction

Quantile regression models have been widely used for a variety of applications (Koenker [1]; Yu et al. [2]). Like standard or mean regression models, dealing with parameter and model uncertainty as well as updating information is of great importance for quantile regression and application. Since Yu and Moyeed [3] Bayesian inference quantile regression has attracted a lot of attention in the literature (Hanson and Johnson [4]; Tsionas [5]; Scaccia and Green [6]; Schennach [7]; Dunson and Taylor [8]; Geraci and Bottai [9]; Taddy and Kottas [10]; Yu and Stander [11]; Kottas and Krnjaic [12]; Lancaster and Jun [13]). These Bayesian inference models include Bayesian parametric, Bayesian semiparametric as well as Bayesian nonparametric models. However, almost all these models set priors independent of the values of quantiles, or the prior is the same for modelling different quantiles. This approach may result in inflexibility in quantile modelling. For example, a 95% quantile regression model should have different parameter values from the median quantile, and thus the priors used for modelling the quantiles should be different. It is therefore more reasonable to set different priors for different quantiles. In this paper, we address a quantile dependent prior for Bayesian quantile regression. Our idea is to set priors based on historical data. Although one can use improper prior in Bayesian quantile regression, the inference on current data could be more reliable and sensitive if there exist historical data gathered from
similar previous studies. There are several methods to incorporate the historical data in the analysis of a current study. One of these methods is the power prior proposed by Ibrahim and Chen [14] which is constructed by raising the likelihood function of the historical data to a power parameter between 0 and 1. The power parameter represents the proportion of the historical data needed in the current study. The a priori idea for the power prior distribution belongs to Diaconis and Ylvisaker [15] and Morris [16] who studied conjugate priors for the exponential families, where they considered the power parameter as fixed constant which can be determined in advance. Ibrahim and Chen [14] developed this idea and considered the uncertainty case of the power parameter. They applied it in generalized linear mixed models, semiparametric proportional hazards models, and cure rate models for survival data. Chen et al. [17] examined the theoretical properties of power prior distribution for generalized linear models, while Ibrahim et al. [18] studied the optimality properties of the power prior, and Chen and Ibrahim [19] studied the relation between the power prior and hierarchical models and provided a formal justification of the power prior by examining formal analytical relationships between the power prior and hierarchical modelling in linear models.

Following the standard setup and notation for the power prior by Ibrahim and Chen [14], suppose that there exist historical data gathered from previous studies similar to the current study denoted by \( D_0 = (n_0, y_0, x_0) \) along with a precision parameter \( a_0 \), \( 0 \leq a_0 \leq 1 \), where \( n_0 \) denotes the sample size of the historical data, \( y_0 \) is an \( n_0 \times 1 \) historical data response vector, and \( x'_0 = (1, x_{01}, x_{02}, \ldots, x_{0m}) \) represent the \( k+1 \) known covariates from the historical data. The power parameter \( a_0 \) represents how much data from the previous study is to be used in the current study. There are two special cases for \( a_0 \): the first case \( a_0 = 0 \) corresponds to no incorporation of the data from previous study relative to the current study. The second case \( a_0 = 1 \) corresponds to full incorporation of the data from previous study relative to the current study. Therefore, \( a_0 \) controls the influence of the data gathered from previous studies that is similar to the current study; such control is important when the sample size of the current data is quite different from the sample size of the historical data or where there is heterogeneity between two studies (Ibrahim and Chen [14]). In generalized linear models, Ibrahim and Chen [14] defined the power prior of unknown parameters \( \beta \) based on the historical data as

\[
\pi(\beta \mid D_0, a_0) \propto [L(\beta \mid D_0)]^{a_0} \pi_0(\beta \mid c_0),
\]

(1.1)

where \( c_0 \) is a specified hyperparameter for the initial prior. Formulation (1.1) was initially elicited for \( a_0 \) as known parameter which can be determined previously, for example, by using expert beliefs or via a meta-analytic approach. Ibrahim and Chen [14] extend this idea by treating \( a_0 \) as random that is why the formulation becomes quite complicated. However, a random \( a_0 \) gives the researcher more freedom and flexibility in weighting the data gathered from previous studies. Thus Ibrahim and Chen [14] proposed a joint power prior distribution for \((\beta, a_0)\) in generalized linear model of the form

\[
\pi(\beta, a_0 \mid D_0) \propto [L(\beta \mid D_0)]^{a_0} \pi_0(\beta \mid c_0) \pi(a_0 \mid y_0),
\]

(1.2)

where \( c_0 \) and \( y_0 \) are specified hyperparameter vectors. Power priors (1.1) and (1.2) will not have a closed form in general; however Ibrahim and Chen [14] suggested using a uniform prior for \( \pi_0(\beta \mid c_0) \) and a beta prior for \( \pi(a_0 \mid y_0) \), or other choices, such as truncated normal or gamma priors. The advantage of employing these three priors for \( \pi(a_0 \mid y_0) \) is due to
their similar theoretical and computational properties. Furthermore, the authors extend the original power prior to a situation where the set of covariates measured in the previous study is a subset from a set of covariates in the current data or when the historical data are not available. In addition they generalized power prior (1.2) to multiple data from previous studies, and power prior (1.2) becomes

\[
\pi(\beta, a_0 \mid D_0) \propto \left\{ \prod_{j=1}^{M} [L(\beta \mid D_{0j})]^a_0 \pi(a_0 \mid y_0) \right\} \pi_0(\beta \mid c_0),
\]

where \( M \) represent the size of previous studies, \( a_0 = (a_{01}, \ldots, a_{0M}) \), \( D_{0j} \) is the historical data for \( j \)th study, \( j = 1, 2, \ldots, M \), and \( D_0 = (D_{01}, \ldots, D_{0M}) \).

Section 2 of the paper gives a brief overview of likelihood function based on asymmetric type of Laplace distribution, and we define the power prior for Bayesian quantile regression. In Section 3, we discuss the propriety of the power prior. In Section 4 we describe in detail the location-scale mixture of normal representation, and we propose power priors by using this representation for Bayesian quantile regression. Section 5 contains two simulation studies with one real data, and we end with a short discussion in Section 6.

2. The Power Prior

Consider the quantile linear regression model

\[
y_i = x'_i \beta_p + \varepsilon_i,
\]

where \( \{(x_i, y_i), i = 1, 2, \ldots, n\} \) are independent observations, \( y_i \) is the response variable, \( x'_i = (1, x_{i1}, x_{i2}, \ldots, x_{ik}) \) represent the \( (k + 1) \) known covariates, \( \beta'_p = (\beta_{0(p)}, \beta_{1(p)}, \ldots, \beta_{k(p)}) \) is the \( (k + 1) \) unknown parameters, and \( \varepsilon_i, i = 1, \ldots, n \), represent error terms which are independent and identically distributed errors. The distribution of the error is assumed unknown and is restricted to have the \( p \)th quantile equal to zero and \( 0 < p < 1 \). Let \( q_p(y \mid x) \) represent the conditional quantile of \( y_i \) given \( x_i \). Then the relation between \( q_p(y \mid x) \) and \( x \) can be modelled as \( q_p(y \mid x) = x'_i \beta_p \).

Following Yu and Moyeed [3], we suppose that \( \varepsilon_i \) has an asymmetric Laplace distribution with the density

\[
f(\varepsilon \mid p) = p(1-p) \exp\{-p\rho_p(\varepsilon)\},
\]

where

\[
\rho_p(u) = \begin{cases} 
  p|u| & \text{if } u \geq 0, \\
  (1-p)|u| & \text{if } u < 0.
\end{cases}
\]
We refer to Kotz et al. [20] for a nice comprehensive review about the asymmetric Laplace distribution. The mean and variance of the asymmetric Laplace distribution are, respectively, given by

\[ E(\varepsilon_i) = \frac{1 - 2p}{p(1 - p)}, \quad \text{Var}(\varepsilon_i) = \frac{1 - 2p + 2p^2}{p^2(1 - p)^2}. \]  

(2.4)

It is known that the probability density function of the asymmetric Laplace distribution of \( y_i \) given a location parameter \( \mu_i = x_i'\beta_p \) is given by

\[ f(y_i \mid \beta_p) = p(1 - p) \exp\left\{ -(y_i - x_i'\beta_p) \left\{ p - I_{y_i \leq x_i'\beta_p} \right\} \right\}. \]  

(2.5)

Let \( D = (n, y_i, x_i) \) denote the data from the current study. Then, the likelihood function for the current study is given by

\[ f(\beta_p \mid D) = p^n(1 - p)^n \prod_{i=1}^n \exp\left\{ -(y_i - x_i'\beta_p) \left\{ p - I_{y_i \leq x_i'\beta_p} \right\} \right\} \]

\[ = p^n(1 - p)^n \exp\left\{ -\sum_{i=1}^n (y_i - x_i'\beta_p) \left\{ p - I_{y_i \leq x_i'\beta_p} \right\} \right\}. \]  

(2.6)

Suppose that there exists historical data from a previous study denoted by \( D_0 = (n_0, y_0, x_0) \) measuring the same response variable and covariates as the current study, where \( n_0 \) denotes the sample size of the previous study, \( y_0 \) is an \( n_0 \times 1 \) response vector of the previous study, and \( x_0' = (1, x_{01}, x_{02}, \ldots, x_{0k}) \) represent the \( k + 1 \) known covariates from the previous study. Then the likelihood function based on the data from the previous study is defined by

\[ L(\beta_p \mid D_0) = p^{n_0}(1 - p)^{n_0} \exp\left\{ -\sum_{i=1}^{n_0} (y_i - x_{0i}'\beta_p) \left\{ p - I_{y_i \leq x_{0i}'\beta_p} \right\} \right\}. \]  

(2.7)

From Ibrahim and Chen [14] we define the joint prior distribution of \( \beta_p \) and \( a_0 \) for Bayesian quantile regression as

\[ \pi(\beta_p, a_0 \mid D_0) \propto [L(\beta_p \mid D_0)]^{a_0} \pi_0(\beta_p \mid c_0) \pi(a_0 \mid \gamma_0), \]  

(2.8)

where \( L(\beta_p \mid D_0) \) is the likelihood function for the historical data for quantile regression which is given by (2.7). We assume that the initial prior for \( \beta_p \) is uniform. However, other choices, including multivariate normal or a double exponential can be used. Yu and Stander [11] prove that all posterior moments for \( \beta_p \) exist under these priors.

3. The Propriety of Power Prior Distribution in Quantile Regression

The power prior proposed by Ibrahim and Chen [14] has been constructed to be a useful class of informative prior in Bayesian analysis. This prior depends on the availability of
the historical data, and in the context of Bayesian analysis when such data are available the prior distribution should be proper because it is well known that any informative Bayesian analysis requires a proper prior distribution; thus the propriety of the power prior is of critical importance. In this section we discuss the propriety of the power prior distribution in Bayesian quantile regression.

**Theorem 3.1.** Suppose that the initial prior distribution for $\beta_p$ is a uniform prior and $a_0$ has a beta prior with hyperparameters ($\delta_0 > 0$, $\lambda_0 > 0$). Then, the joint prior distribution (2.8) in quantile regression for $(\beta_p, a_0)$ is proper. In other words

$$0 < \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \int_{0}^{1} [L(\beta_p \mid D_0)] \, a_0^{\delta_0-1} (1 - a_0)^{\lambda_0-1} \, da_0 \, d\beta_p < \infty. \quad (3.1)$$

**Proof.** See the appendix.

**Corollary 3.2.** Suppose that the initial prior distribution for $\beta_p$ is a uniform prior and the random variable $a_0$ has a uniform prior. Then, the joint power prior distribution (2.8) in quantile regression for $(\beta_p, a_0)$ is proper. In other words

$$0 < \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \int_{0}^{1} [L(\beta_p \mid D_0)] \, da_0 \, d\beta_p < \infty. \quad (3.2)$$

This corollary is derived directly from Theorem 3.1 because the uniform distribution is the special case of the beta distribution when ($\delta_0 = 1$, $\lambda_0 = 1$) and the proof is omitted.

**Corollary 3.3.** Suppose that the initial prior distribution for $\beta_p$ is uniform prior and $a_0$ is constant. Then, power prior (1.1) in quantile regression for $\beta_p$ is proper. In other words

$$0 < \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} [L(\beta_p \mid D_0)] \, d\beta_p < \infty. \quad (3.3)$$

This corollary is derived directly from Corollary 3.2, and the proof is omitted. It is straightforward to verify that the joint prior $\pi(\beta_p, a_0 \mid D_0)$ when $\beta_p$ has a uniform prior is always proper in quantile regression, which also ensures the proper propriety of the joint posterior of $(\beta_p, a_0)$.

**Theorem 3.4.** Suppose that the initial prior distribution for $\beta_p$ is assumed to be independent, and each $\pi_0(\beta_i(\cdot) \mid c_0) \propto \exp\{-1/\lambda_i \, |\beta_i(\cdot) - \mu_i|\}$, a double-exponential with fixed $\mu_i$, $\lambda_i > 0$, and $a_0$ has a beta prior with hyperparameters ($\delta_0, \lambda_0$). Then, the joint prior distribution (2.8) in quantile regression for $(\beta_p, a_0)$ is proper.

### 4. Mixture Representation

Consider the linear model for quantile regression (2.1), where the error term $\varepsilon$ has an asymmetric Laplace distribution with the $p$th quantile equal to zero. The probability density function of the asymmetric Laplace distribution with location parameter $\mu$ and skewness parameter $p$, $p \in (0, 1)$ is given by (2.2).
It is well known that the asymmetric Laplace distribution (2.2) can be viewed as a mixture of an exponential and a scaled normal distribution (Reed and Yu [21] and Kotz et al. [20]). This can be recognized in the following lemma.

**Lemma 4.1.** Suppose that $X$ is a random variable that follows the asymmetric Laplace distribution with density (2.2), $\xi$ is a standard normal random variable, and $z$ is a standard exponential random variable. Then, one can represent $X$ as a location-scale mixture of normals given by

$$X \overset{d}{=} \frac{1 - 2p}{p(1-p)}z + \sqrt{\frac{2z}{p(1-p)}}\xi. \quad (4.1)$$

From this result we can equivalently represent the error term $\varepsilon_i$ as a mixture of normal distributions, given by

$$\varepsilon_i = \theta z_i + \phi \sqrt{z_i} \xi_i, \quad (4.2)$$

where

$$\theta = \frac{1 - 2p}{p(1-p)}, \quad \phi^2 = \frac{2}{p(1-p)}. \quad (4.3)$$

Following Reed and Yu [21], we assume that the conditional distribution of each $y_i$ given $z_i$ is normal with mean $x_i'\beta_p + \theta z_i$ and variance $\phi^2 z_i$ and the $z_i$ given $\beta_p$ are independent standard exponential variables. Letting $y' = (y_1, \ldots, y_n)$ and $z' = (z_1, \ldots, z_n)$, then, the joint density of $(y, z)$ is given by

$$f(y, z \mid \beta_p) = \prod_{i=1}^{n} f(y_i \mid \beta_p, z_i) \pi(z_i \mid \beta_p), \quad (4.4)$$

$$f(y, z \mid \beta_p) \propto \prod_{i=1}^{n} (z_i^{-1/2}) \exp \left\{ - \frac{(y_i - x_i'\beta_p - \theta z_i)^2}{2\phi^2 z_i} \right\} \exp \{-zi\}$$

$$= \left( \prod_{i=1}^{n} z_i^{-1/2} \right) \exp \left\{ - \sum_{i=1}^{n} \frac{(y_i - x_i'\beta_p - \theta z_i)^2}{2\phi^2 z_i} \right\} \exp \left\{ - \sum_{i=1}^{n} z_i \right\}. \quad (4.5)$$

We then integrate out the exponential variable $z$, which leads to the likelihood $f(y \mid \beta_p)$, where

$$f(y \mid \beta_p) = \int f(y, z \mid \beta_p) dz. \quad (4.6)$$

**4.1. The Power Prior for Mixture Representation**

Suppose that we are interested in making inference about $\beta_p$ on the normal distribution with unknown variance, by incorporating both the previous and current studies.
Following the standard setup and notation for the power prior distribution for mixture representation, we assume that only one historical data set exists, and it is given by $D_0 = (n_0, y_0, x_0)$, where $n_0$ is the sample size of the historical data, $y_0$ is the $n_0 \times 1$ response vector, and $x_0$ is the $n_0 \times (k + 1)$ matrix of covariates.

Let $z_0' = (z_{01}, \ldots, z_{0n_0})$, where $z_{01}, \ldots, z_{0n_0}$ are standard exponential random variables. As a mixture representation, the joint density for the historical data of $y_0$ given $z_0$ is normal with mean $x_0' \beta_p + \theta z_0$ and variance $\phi^2 z_0$, and each $z_0$ given $\beta_p$ is independently and identically standard exponential distribution, which can be viewed as the prior distribution on $z_0$. For $\pi_0(\beta_p \mid c_0)$ we choose a normal density as initial prior with mean 0 and variance $B = c_0 I$, that is, $\pi_0(\beta_p \mid c_0) \propto \exp(-(1/2c_0)\beta_p'\beta_p)$. The purpose of this choice is due to the fact that all posterior moments of $\beta_p$ exist under the above prior as provided in the studies of Yu and stander [11]. It is also convenient if all covariates are measured on the same scale parameter. As a special case one may choose a uniform improper prior which is special case of beta distribution when $(\delta_0 = 1, \lambda_0 = 1)$ for $\pi_0(\beta_p \mid c_0)$, that is, $\pi_0(\beta_p \mid c_0) \propto 1$; this corresponds to $c_0 \rightarrow \infty$, and this choice is very convenient with the partially Gibbs sampler as provided by Reed and Yu [21]. We propose a prior distribution of $\beta_p$ taking the form

$$
\pi(\beta_p \mid D_0, a_0) \propto \left\{ \prod_{i=1}^{n_0} \int_{z_0} \left[ f(y_{0i} \mid \beta_p, z_{0i})\right]^{a_0} \pi(z_{0i} \mid \beta_p)dz_{0i} \right\} \pi_0(\beta_p \mid c_0), \quad (4.7)
$$

where $f(y_{0i} \mid \beta_p, z_{0i})$ and $f(z_{0i} \mid \beta_p)$ are the same $f(y_i \mid \beta_p, z_i)$ and $f(z_i \mid \beta_p)$ in (4.4) with $(y_{0i}, z_{0i})$ in place of $(y_i, z_i)$ to represent the historical data. Since we view $a_0$ as a random quantity, the prior specification is completed by specifying a prior distribution for $a_0$. We take a beta prior for $a_0$ with parameter $(\delta_0, \lambda_0)$, or one may choose a uniform prior. Thus we propose a joint prior distribution for $\beta_p$ and $a_0$ of the form

$$
\pi(\beta_p, a_0 \mid D_0) \propto \left\{ \prod_{i=1}^{n_0} \int_{z_0} \left[ f(y_{0i} \mid \beta_p, z_{0i})\right]^{a_0} \pi_0(z_{0i} \mid \beta_p)dz_{0i} \right\} \pi_0(\beta_p \mid c_0)\pi(a_0 \mid y_0), \quad (4.8)
$$

$$
\propto \prod_{i=1}^{n_0} \int_{z_0} \left( z_{0i}^{-1/2} \exp \left\{ -a_0 \frac{(y_{0i} - x_0' \beta_p - \theta z_{0i})^2}{2\phi^2 z_{0i}} \right\} \exp\{-z_{0i}\}dz_{0i} \right) \times \exp\left\{ -\frac{1}{2c_0} \beta_p' \beta_p \right\} \times a_0^{\delta_0-1} (1 - a_0)^{\lambda_0-1}. \quad (4.9)
$$

We see that (4.8) will not have a closed form in general because it depends on the initial priors that we choose. Thus the joint posterior distribution of $\beta_p$ and $a_0$ is given by

$$
p(\beta_p, a_0 \mid D, D_0) \propto \left[ \prod_{i=1}^{n} f(y_i \mid \beta_p, z_i) \right] \pi(\beta_p, a_0 \mid D_0). \quad (4.10)
$$

Power prior (4.8) is constructed for one historical data, and this power prior can be easily generalized to multiple historical data. To generalized power prior (4.8) to multiple historical data, we assume that there are $M$ historical studies denoted by $D_0 = (D_{01}, \ldots, D_{0M})$, where $D_{0j} = (n_{0j}, y_{0j}, x_{0j})$ represent the historical data based on the $j$ study, $j = 1, \ldots, M.$ Let $z_{0j}' = (z_{01j}, \ldots, z_{0n_{0j}})$, where $z_{01j}, \ldots, z_{0n_{0j}}$ are standard exponential random variables. We define $a_{0j}$
to be the power parameter for the $j$th study with beta prior distribution. Hence, the prior can be generalized as

$$
\pi(\beta_p, a_0 \mid D_0) \propto \prod_{j=1}^{M} \left\{ \prod_{i=1}^{n_{0j}} \int_{z_{0ij}} f(y_{0ij} \mid \beta_p, z_{0ij}) \right\}^{a_0} \pi_0(z_{0ij} \mid \beta_p) d z_{0ij} \right\} \times \pi_0(\beta_p \mid c_0) \pi(a_0 \mid y_0), \tag{4.11}
$$

where $a_0 = (a_{01}, \ldots, a_{0M})$, and each $a_{0j}$ has a beta prior with the same hyperparameters $(\delta_0, \lambda_0)$.

### 4.2. Inference with Scale Parameter

In the previous section, we have considered the power prior distribution in quantile regression model without taking into account a scale parameter. One may be interested to introduce a scale parameter into the model for the proposed Bayesian inference. Suppose that $\tau > 0$ is the scale parameter. From now on, it is more convenient to work with $\tau = \tau z_i$ for the current data and with $\tau_0 = \tau z_0$ for the historical data. We assume that only one historical data set exists, and it is given by $D_0 = (n_0, y_0, x_0)$. Let $v_0' = (v_{01}, \ldots, v_{0n_0})$. Then, the conditional distribution for each $y_{0i}$ given $v_{0i}, \beta_p, \tau$ is normal with mean $x_{0i}' \beta_p + \theta v_{0i}$ and variance $\tau \phi^2 v_{0i}$, that is, $y_{0i} \mid v_{0i}, \beta_p, \tau \sim N(x_{0i}' \beta_p + \theta v_{0i}, \tau \phi^2 v_{0i})$, and the $v_{0i}$ given $\beta_p$ and $\tau$ are independent and identically distributed exponentially variables with rate parameter $\tau$. The conditional distribution of $v_{0i}$ given $\beta_p$ and $\tau$ can be viewed as prior distribution on $v_{0i}$. It will be more convenient to work with the following priors:

$$
\tau \sim \Gamma(l_0, s_0),
$$

$$
\beta_p \mid \tau \sim N_k(0, B_0), \quad B_0 = c_0 I, \quad c_0 \rightarrow \infty, \tag{4.12}
$$

where $l_0, s_0$, and $B_0$ are known parameters. For $a_0$ we take a beta prior with parameter $(\delta_0, \lambda_0)$. Now, the specification of the prior distribution is completed, and thus we propose a joint prior distribution for $\beta_p$, $\tau$, and $a_0$ of the form

$$
\pi(\beta_p, \tau, a_0 \mid D_0) \propto \left\{ \prod_{i=1}^{n_0} \int_{v_{0i}} [f(y_{0i} \mid \beta_p, \tau, v_{0i})]^{a_0} \pi_0(v_{0i} \mid \beta_p, \tau) d v_{0i} \right\} \times \pi_0(\beta_p \mid c_0) \pi(\tau \mid \pi(a_0 \mid y_0), \tag{4.13}
$$

$$
\propto \left\{ \prod_{i=1}^{n_0} \int_{v_{0i}} (\tau v_{0i})^{-1/2} \exp\left\{-a_0 \frac{(y_{0i} - x_{0i}' \beta_p - \theta v_{0i})^2}{2 \phi^2 \tau v_{0i}}\right\} \tau \exp\{-\tau v_{0i}\} d v_{0i} \right\} \times \exp\left\{-\frac{1}{2c_0} \beta_p^' \beta_p \right\} \times (\tau)^{l_0 - 1} \exp\{-s_0 \tau\} a_0^{\delta_0 - 1} (1 - a_0)^{\lambda_0 - 1}. \tag{4.14}
$$
Then, the joint posterior distribution of $\beta_p$, $\tau$, and $a_0$ is given by

$$p(\beta_p, \tau, a_0 | D, D_0) \propto \left[ \prod_{i=1}^{n} f(y_i | \beta_p, \tau, v_i) \right] \pi(\beta_p, \tau, a_0 | D_0).$$ (4.15)

Power prior (4.13) can be easily generalized to $M$ historical data, and the generalized distribution can be given as

$$\pi(\beta_p, \tau, a_0 | D_0) \propto \prod_{j=1}^{M} \left\{ \prod_{i=1}^{m_j} \int_{v_{0ij}} f(y_{0ij} | \beta_p, \tau, v_{0ij}) \right\}^{a_{0ij}} \pi_0(\nu_{0ij} | \beta_p, \tau) dv_{0ij}$$

$$\times \pi_0(\beta_p | c_0) \pi(\tau) \pi(a_{0ij} | \nu_0).$$ (4.16)

5. Numerical Examples

In this section, our aim is to compare the posterior means of parameters of interest after incorporating the current and historical data with the mean of true values for both studies. In addition, we will demonstrate the behaviour of the prior under several choices of prior parameters.

Example 5.1. We simulate two data sets, the first one for the current study and the second for the previous study. For the current study we generate 100 observations from the model $y_i = \mu + \epsilon_i$ assuming that $\mu = 5.0$ and $\epsilon_i \sim N(0, 1)$.

For the historical data we use the same model with 50 observations and $\mu = 6.0$. In this example we have used only one parameter $\mu$. Table 1 compares the posterior means with the means of true values for $q_\mu(y_i) = \beta_p$ at 5 different quantiles, namely, 90%, 75%, 50%, 25%, and 10%. We conduct sensitive analysis with respect to five different choices for $(\delta_0, \lambda_0)$ for five different quantiles. For computation we construct a Markov chain via the Metropolis-Hastings (MH) algorithm. We ran the algorithm for 15000 iterations and discarded the first 5000 as burn in. Figures 1, 2, and 3 compare the posterior densities of $\beta_p$ for $p = 0.90, 0.50,$ and 0.10, respectively, for improper prior with the posterior densities of $\beta_p$ for the power prior with parameters $(\mu_{a_0}, \sigma_{a_0}) = (0.50, 0.078)$ and $(\mu_{a_0}, \sigma_{a_0}) = (0.99, 0.010)$. Clearly, the power prior is more informative than improper prior, due to the small range of posterior densities.

Note that as shown in Chen et al. [17] it is easier to specify the prior mean and standard deviation of $a_0$ from the following equations:

$$\mu_{a_0} = \frac{\delta_0}{(\delta_0 + \lambda_0)},$$

$$\sigma_{a_0} = (\mu_{a_0}(1 - \mu_{a_0}))^{1/2}(\delta_0 + \lambda_0 + 1)^{-1/2}.$$ (5.1)

Furthermore they have shown that the investigator must choose $\mu_{a_0}$ small if he/she wishes low weight to the historical data and must choose $\mu_{a_0} \geq 0.5$ if he/she wishes more weight to the historical data.

In this example we use power prior (2.8), taking uniform prior for $\beta_p$ and beta prior for $a_0$. Under specific quantile level, we see that as the weight for the historical data increases the
for the different weights for power parameter.

More noticeably, when \((\delta_0 = 100, \lambda_0 = 1)\), that is, we give more weight to the historical data, we see that the posterior mean is very close to the mean of the true values. In addition, under specific quantile level, we found that as the weight for the historical data increases the standard deviation tends to decrease.

**Example 5.2.** For a mixture representation with scale parameter, we simulate two data sets, the first one for the current study and the second for the previous study. For the current study we generate a data set of \(n = 50\) observations from the model \(y_i = \beta_0(p) + \beta_1(p)x_i + 1/11(1 + x_i)e_i\), where \(x_i\) are random uniform numbers on the interval \((0, 10)\) and \(e_i \sim N(0, 1)\). We restricted

<table>
<thead>
<tr>
<th>(p)</th>
<th>((\delta_0, \lambda_0))</th>
<th>((\mu_n, \sigma_n))</th>
<th>Mean (\hat{\beta}(p))</th>
<th>SD (\hat{\beta}(p))</th>
<th>Mean of the true values of (\hat{\beta}(p))</th>
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</table>
\[
B_0 = 0.90, \quad 0.50, \quad 0.5, \quad 0.5, \quad 0.5
\]

Posterior density

Figure 1: Plots of posterior densities for \(B_{0.90}\), where the dotted curve is for improper uniform prior, the dashed and solid curves are for power priors with parameters \((\mu_{a_0}, \sigma_{a_0}) = (0.50, 0.078)\) and \((\mu_{a_0}, \sigma_{a_0}) = (0.99, 0.010)\), respectively.

\[
B_0 = 0.50, \quad 0.50, \quad 0.5, \quad 0.5, \quad 0.5
\]

Posterior density

Figure 2: Plots of posterior densities for \(B_{0.50}\), where the dotted curve is for improper uniform prior, the dashed and solid curves are for power priors with parameters \((\mu_{a_0}, \sigma_{a_0}) = (0.50, 0.078)\) and \((\mu_{a_0}, \sigma_{a_0}) = (0.99, 0.010)\), respectively.

\[
B_{0(0)} = 10 \text{ and } B_{1(0)} = -1. \text{ For the previous study we generate } n_0 = 150 \text{ observations from the above model with } B_{0(0)} = 9 \text{ and } B_{1(0)} = -1.2.
\]

We use initial prior \(N(0, 10^6)\) on all regression parameters and \(\Gamma(10^{-3}, 10^{-3})\) on all scale parameters. Then we ran MCMC algorithm for 11000 iterations and discarded the first 1000 as burn in. We then compute the posterior means of the parameters at 5 different quantiles, namely, 90%, 75%, 50%, 25%, and 10%. We conduct sensitive analysis with respect to five
different weights for the power parameter, namely, 10%, 25%, 50%, 75%, and 90%. The results are summarized in Table 2. Based on the results in Table 2 for each quantile, it is consistent in the sense that the posterior mean of $\beta_p$ either increases or decreases steadily as the weight of the historical data increases. Under specific quantile level, we also found that as the weight for the historical data increases the posterior standard deviations for all parameters tend to decrease.

**Example 5.3.** We consider data from the British Household Panel Survey. The data were originally collected by the ESRC Research Centre on Microsocial Change at the University of Essex and analyzed by Yu et al. [22]. The data represent the wage distribution among British workers between 1991 and 2001. We use the data for the year 2000 as current data and for 1994 as historical data. Four covariates and intercept are included in the analysis. The relation between response variable and covariates are given by the following model:

$$
\ln(Y_i) = \beta_0 + \beta_1 S_i + \beta_2 E_i + \beta_3 E_i^2 + \beta_4 D_i + \epsilon_i,
$$

where $S_i$ is the number of years of schooling, $E_i$ is the potential experience (approximated by the age minus years of schooling minus 6), and $D_i$ is equal to 1 for public sector workers and 0 otherwise. In this example we fixed the power parameter at five weights, namely, 0.10, 0.25, 0.50, 0.75, and 0.90. The results are summarized in Table 3. From Table 3, we see that as the weight for the historical data increases, the posterior mean for each regression coefficient either decreases or increases. We also found that as the weight for the historical data increases, the posterior standard deviations for all parameters tend to decrease.
Table 2: Posterior means, posterior standard deviations (SD), and mean of the true values of $\beta_{(p)}$.

<table>
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<tr>
<th>$p$</th>
<th>$a_0$</th>
<th>Mean $\beta_{(p)}$</th>
<th>SD $\beta_{(p)}$</th>
<th>Mean of the true values of $\beta_{(p)}$</th>
<th>Mean $\beta_{1(p)}$</th>
<th>SD $\beta_{1(p)}$</th>
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<tr>
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6. Discussion

In this paper, we have demonstrated the use of power prior in Bayesian quantile regression that incorporates both historical and current data. The advantage of the method is that the prior distribution is changing automatically when we change the quantile. Thus, we have prior distribution for each quantile, and the prior is proper. In addition, we proposed joint prior distributions using a mixture of normal representation of the asymmetric Laplace distribution. The behavior of the power prior is clearly quite robust with different weights for power parameter. We use random power parameter in the first example that can be determined via the hyperparameters of beta distribution, and we compare the posterior
mean of the intercept with the mean of true values. In the second example we show the behavior of the power prior distribution when the power parameter is a fixed parameter and can be determined using expert beliefs or via a meta-analytic approach, and we compare the posterior mean of parameter of interest with the mean of true values for both studies. In the third example, we also use fixed power parameter, and we compare the posterior mean for different weights for the historical data. The power prior is a very useful class of informative prior distribution for Bayesian quantile regression. It also seems to be useful in many applications such as model selection and carcinogenicity studies.

Table 3: Posterior means of $\beta_p$ for the real data. In the parentheses are standard deviations of $\beta_p$.

<table>
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<th>$p$</th>
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<th>Mean $\beta_{2(p)}$</th>
<th>Mean $\beta_{3(p)}$</th>
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<td></td>
<td>0.25</td>
<td>5.9255 (0.311)</td>
<td>0.0142 (0.018)</td>
<td>0.0301 (0.013)</td>
<td>−0.0007 (0.016)</td>
</tr>
<tr>
<td></td>
<td>0.50</td>
<td>5.9308 (0.299)</td>
<td>0.0114 (0.023)</td>
<td>0.0329 (0.011)</td>
<td>−0.0007 (0.015)</td>
</tr>
<tr>
<td></td>
<td>0.75</td>
<td>5.9550 (0.271)</td>
<td>0.0110 (0.014)</td>
<td>0.0302 (0.015)</td>
<td>−0.0006 (0.012)</td>
</tr>
<tr>
<td></td>
<td>0.90</td>
<td>5.9592 (0.248)</td>
<td>0.0095 (0.013)</td>
<td>0.0366 (0.012)</td>
<td>−0.0008 (0.012)</td>
</tr>
</tbody>
</table>
Appendix

Proof of Theorem 3.1

To prove the joint prior distribution is proper prior, that is,

\[ 0 < \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \int_0^1 \left[ L(\beta_p \mid D_0) \right] \frac{a_0^{\delta_0-1}}{\lambda_0^{\delta_0-1}} (1 - a_0)^{\lambda_0-1} \, da_0 \, d\beta_p < \infty, \tag{A.1} \]

note that

\[ \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \int_0^1 \ln \left[ L(\beta_p \mid D_0) \right] \frac{a_0^{\delta_0-1}}{\lambda_0^{\delta_0-1}} (1 - a_0)^{\lambda_0-1} \, da_0 \, d\beta_p \]

\[ = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} - \sum_{i=1}^{n_0} (y_{0i} - x_{0i}^t \beta_p) \left[ p - I(y_{0i} \leq x_{0i}^t \beta_p) \right] \int_0^1 a_0 \, da_0 
\]

\[ + \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \int_0^1 \ln \left[ a_0^{\delta_0-1} (1 - a_0)^{\lambda_0-1} \right] da_0 \, d\beta_p \]

\[ = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \ln \left\{ \exp \left\{ - \sum_{i=1}^{n_0} (y_{0i} - x_{0i}^t \beta_p) \left[ p - I(y_{0i} \leq x_{0i}^t \beta_p) \right] \right\} \right\} \left( \frac{1}{2} \right) \, d\beta_p + K, \tag{A.2} \]

where

\[ K = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \int_0^1 \ln \left[ a_0^{\delta_0-1} (1 - a_0)^{\lambda_0-1} \right] da_0 \, d\beta_p. \tag{A.3} \]

Then

\[ \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \int_0^1 \left[ L(\beta_p \mid D_0) \right] \frac{a_0^{\delta_0-1}}{\lambda_0^{\delta_0-1}} (1 - a_0)^{\lambda_0-1} \, da_0 \, d\beta_p \]

\[ = K \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \left\{ \exp \left\{ - \frac{1}{2} \sum_{i=1}^{n_0} (y_{0i} - x_{0i}^t \beta_p) \left[ p - I(y_{0i} \leq x_{0i}^t \beta_p) \right] \right\} \right\} d\beta_p. \tag{A.4} \]

Following Yu and Moyeed [3], this integral is finite:

\[ 0 < \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \int_0^1 \left[ L(\beta_p \mid D_0) \right] \frac{a_0^{\delta_0-1}}{\lambda_0^{\delta_0-1}} (1 - a_0)^{\lambda_0-1} \, da_0 \, d\beta_p < \infty. \tag{A.5} \]

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References


