Research Article

An Alternative Regularization Method for Equilibrium Problems and Fixed Point of Nonexpansive Mappings

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We introduce a new regularization iterative algorithm for equilibrium and fixed point problems of nonexpansive mapping. Then, we prove a strong convergence theorem for nonexpansive mappings to solve a unique solution of the variational inequality and the unique sunny nonexpansive retraction. Our results extend beyond the results of S. Takahashi and W. Takahashi (2007), and many others.

1. Introduction

Let $H$ be a real Hilbert space with inner product $\langle \cdot , \cdot \rangle$ and norm $\| \cdot \|$, respectively. let $C$ be a nonempty closed convex subset of $H$. Let $\phi$ be a bifunction of $C \times C \rightarrow \mathbb{R}$, where $\mathbb{R}$ is the set of real numbers. The equilibrium problem for $\phi : C \times C \rightarrow \mathbb{R}$ is to find $x \in C$ such that

$$\phi(x, y) \geq 0, \quad \forall y \in C. \quad (1.1)$$

The set of solutions of (1.1) is denoted by $\text{EP}(\phi)$. Given a mapping $T : C \rightarrow H$, let $\phi(x, y) = \langle Tx, y - x \rangle$ for all $x, y \in C$. Then, $z \in \text{EP}(\phi)$ if and only if $\langle Tz, y - z \rangle \geq 0$ for all $y \in C$, that is, $z$ is a solution of the variational inequality. Numerous problems in physics, optimization, and economics reduce to find a solution of (1.1). Some methods have been proposed to solve the equilibrium problem; see, for instance, [1–6].

A mapping $S$ of $C$ into $H$ is said to be nonexpansive if

$$\|Sx - Sy\| \leq \|x - y\| \quad \forall x, y \in C. \quad (1.2)$$
We denote by $F(S)$ the set of fixed points of $S$. The fixed point equation $Tx = x$ is ill-posed (it may fail to have a solution, nor uniqueness of solution) in general. Regularization therefore is needed. Contractions can be used to regularize nonexpansive mappings. In fact, the following regularization has widely been implemented ([7–9]). Fixing a point $u \in C$ and for each $t \in (0, 1)$, one defines a contraction $T_t : C \rightarrow C$ by

$$T_t x = tu + (1 - t)Tx, \quad x \in C. \quad (1.3)$$

In this paper we provide an alternative regularization method. Our idea is to shrink $x$ first and then apply $T$ to the convex combination of the shrunk $x$ and the anchor $u$ (this idea appeared implicitly in [10] where iterative methods for finding zeros of maximal monotone operators were investigated). In other words, we fix an anchor $u \in C$ and $t \in (0, 1)$ and define a contraction $T_t : C \rightarrow C$ by

$$T_t x = T(tu + (1 - t)x), \quad x \in C. \quad (1.4)$$

Compared with (1.1), (1.4) looks slightly more compact in the sense that the mapping $T$ is more directly involved in the regularization and thus may be more convenient in manipulations since the nonexpansivity of $T$ is utilized first.


**Theorem 1.1 (Moudafi [11]).** Let $C$ be a nonempty closed convex subset of a Hilbert space $H$ and let $S$ be a nonexpansive mapping of $C$ into itself such that $F(S)$ is nonempty. Let $f$ be a contraction of $C$ into itself and let $\{x_n\}$ be a sequence defined as follows: $x_1 = x \in C$ and

$$x_{n+1} = \frac{1}{1 + \varepsilon_n} Sx_n + \frac{\varepsilon_n}{1 + \varepsilon_n} f(x_n) \quad (1.5)$$

for all $n \in \mathbb{N}$, where $\{\varepsilon_n\} \subset (0, 1)$ satisfies

$$\lim_{n \rightarrow \infty} \varepsilon_n = 0, \quad \sum_{n=1}^{\infty} \varepsilon_n = \infty, \quad \lim_{n \rightarrow \infty} \left| \frac{1}{\varepsilon_{n+1}} - \frac{1}{\varepsilon_n} \right| = 0. \quad (1.6)$$

Then, $\{x_n\}$ converges strongly to $z \in F(S)$, where $z = P_{F(S)} f(z)$ and $P_{F(S)}$ is the metric projection of $H$ onto $F(S)$.

Such a method for approximation of fixed points is called the viscosity approximation method.

In 2007, S. Takahashi and W. Takahashi [5] introduced and considered the following iterative algorithm by the viscosity approximation method in the Hilbert space:

$$x_1 \in H,$$

$$\phi(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \quad (1.7)$$

$$x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n) S u_n,$$

for all $n \in \mathbb{N}$, where $\{\alpha_n\} \subset [0, 1]$ and $\{r_n\} \subset (0, \infty)$ satisfy some appropriate conditions. Furthermore, they proved that $\{x_n\}$ and $\{u_n\}$ converge strongly to $z \in F(S) \cap \text{EP}(\phi)$, where $z = P_{F(S) \cap \text{EP}(\phi)} f(z)$. 


Throughout this paper, we consider a nonexpansive mapping. Starting with an arbitrary $x_1, u \in H$, define sequences $\{x_n\}$ and $\{u_n\}$ by

$$\phi(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C,$$

$$x_{n+1} = \beta_n f(x_n) + (1 - \beta_n) T(\alpha_n u + (1 - \alpha_n) u_n), \quad n \geq 1. \quad (1.8)$$

We will prove in Section 3 that if the sequences $\{\alpha_n\}$, $\{\beta_n\}$, and $\{\gamma_n\}$ of parameters satisfy appropriate conditions, then the sequence $\{x_n\}$ and $\{u_n\}$ generated by (1.8) converges strongly to the unique solution of the variational inequality

$$\langle (I - f)z, x - z \rangle \geq 0, \quad \forall x \in F(S) \cap EP(\phi), \quad (1.9)$$

which is the optimality condition for the minimization problem

$$\min_{x \in F(S) \cap EP(\phi)} \frac{1}{2} \langle x, x \rangle - h(x), \quad (1.10)$$

where $h$ is a potential function for $f$ and at the same time, the sequence $\{x_n\}$ and $\{u_n\}$ generated by (1.8) converges in norm to $Q(u)$, where $Q : C \to \text{Fix}(T)$ is the sunny nonexpansive retraction.

2. Preliminaries

Throughout this paper, we consider $H$ as the Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$, respectively, $C$ is a nonempty closed convex subset of $H$. Consider a subset $D$ of $C$ and a mapping $Q : C \to D$. Then we say that

(i) $Q$ is a retraction provided $Qx = x$ for $x \in D$;
(ii) $Q$ is a nonexpansive retraction provided $Q$ is a retraction that is also nonexpansive;
(iii) $Q$ is a sunny nonexpansive retraction provided $Q$ is a nonexpansive retraction with the additional property: $Q(x + t(x - Qx)) = Qx$ whenever $x + t(x - Qx) \in C$, where $x \in C$ and $t \geq 0$.

Let now $T : C \to C$ be a nonexpansive mapping. For a fixed anchor $u \in C$ and each $t \in (0, 1)$ recall that $z_t \in C$ is the unique fixed point of the contraction $C \ni x \mapsto T(tu + (1 - t)x)$. Namely, $z_t \in C$ is the unique solution in $C$ to the fixed point equation

$$z_t = T(tu + (1 - t)z_t). \quad (2.1)$$

In the Hilbert space (either uniformly smooth or reflexive with a weakly continuous duality map), then $z_t$ is strongly convergent should it is bounded as $t \to 0^+$. 
We also know that for any sequence \( \{x_n\} \subset H \) with \( x_n \to x \), the inequality
\[
\liminf_{n \to \infty} \|x_n - x\| < \liminf_{n \to \infty} \|x_n - y\|
\] (2.2)
holds for every \( y \in H \) with \( x \neq y \), (we usually call it Opial’s condition); see [12, 13] for more details.

For solving the equilibrium problem for a bifunction \( \phi : C \times C \to \mathbb{R} \), let us assume that \( \phi \) satisfies the following conditions:

(A1) \( \phi(x, x) = 0 \), for all \( x \in C \);
(A2) \( \phi \) is monotone, that is, \( \phi(x, y) + \phi(y, x) \leq 0 \), for all \( x, y \in C \);
(A3) For each \( x, y, z \in C \), \( \lim_{t \to 0} \phi(tz + (1 - t)x, y) \leq \phi(x, y) \);
(A4) For each \( x \in C \), the function \( y \mapsto \phi(x, y) \) is convex and lower semicontinuous.

The following lemma appeared implicitly in [14].

**Lemma 2.1** (see [14]). Let \( C \) be a nonempty closed convex subset of \( H \) and let \( \phi : C \times C \to \mathbb{R} \) be a bifunction satisfying (A1)-(A4). Let \( r > 0 \) and \( x \in H \), then, there exists \( z \in C \) such that
\[
\phi(z, y) + \frac{1}{r} \langle y - z, z - x \rangle \geq 0, \quad \forall y \in C.
\] (2.3)

**Lemma 2.2** (see [6]). Assume that \( \phi : C \times C \to \mathbb{R} \) satisfies (A1)-(A4). For \( r > 0 \) and \( x \in H \), define a mapping \( T_r : H \to C \) as follows:
\[
T_r(x) = \left\{ z \in C : \phi(z, y) + \frac{1}{r} \langle y - z, z - x \rangle \geq 0, \forall y \in C \right\},
\] (2.4)
for all \( z \in H \). Then, the following hold:

1. \( T_r \) is single-valued;
2. \( T_r \) is firmly nonexpansive, that is, for any \( x, y \in H \),
   \[
   \|T_r x - T_r y\|^2 \leq \langle T_r x - T_r y, x - y \rangle;
   \] (2.5)

3. \( F(T_r) = \text{EP}(\phi) \);
4. \( \text{EP}(\phi) \) is closed and convex.

**Lemma 2.3** (see [15]). Let \( \{a_n\} \subset [0, \infty), \{b_n\} \subset [0, \infty) \) and \( \{c_n\} \subset [0, 1) \) be sequences of real numbers such that
\[
a_{n+1} \leq (1 - c_n)a_n + b_n, \quad \forall n \in \mathbb{N},
\]
\[
\sum_{n=1}^{\infty} c_n = \infty, \quad \sum_{n=1}^{\infty} b_n < \infty \quad \left( \text{or} \limsup_{n \to \infty} \frac{b_n}{c_n} \leq 0 \right),
\] (2.6)
then, \( \lim_{n \to \infty} a_n = 0 \).
Lemma 2.4 (see [9]). Suppose that $X$ is a smooth Banach space. Then a retraction $Q : C \to D$ is sunny nonexpansive if and only if

$$\langle x - Qx, J(y - Qx) \rangle \leq 0, \quad x \in C, \ y \in D. \quad (2.7)$$

Lemma 2.5. Let $X$ be a uniformly smooth Banach space, $C$ a nonempty closed convex subset of $X$, and $T : C \to C$ a nonexpansive mapping. Let $z_t$ be defined by (2.1). Then $(z_t)$ remains bounded as $t \to 0$ if and only if $\text{Fix}(T) \neq \emptyset$. Moreover, if $\text{Fix}(T) \neq \emptyset$, then $(z_t)$ converges in norm, as $t \to 0^+$, to a fixed point of $T$; and if one sets

$$Q(u) := \lim_{t \to 0} z_t, \quad (2.8)$$

then $Q$ defines the unique sunny nonexpansive retraction from $C$ onto $\text{Fix}(T)$.

Lemma 2.6. In the Hilbert space, the following inequalities always hold

(i) $\|x + y\|^2 \leq \|x\|^2 + 2\langle y, x + y \rangle$;

(ii) $\|tx + (1-t)y\|^2 \leq t\|x\|^2 + (1-t)\|y\|^2$.

3. Main Results

Theorem 3.1. Let $C$ be a nonempty closed convex subset of $H$, $\phi : C \times C \to \infty$ be a bifunction satisfying $(A_1)$–$(A_4)$ and $T : C \to C$ be a nonexpansive mapping of $C$ into $H$ such that $F(T) \cap \text{EP}(\phi) \neq \emptyset$. Let $f$ be a contraction of $H$ into itself with $\alpha \in (0, 1)$, initially give an arbitrary element $x_1 \in H$ and let $\{x_n\}$ and $\{u_n\}$ be sequences generated by (1.8), where $\{\alpha_n\} \subset [0, 1)$ and $\{r_n\} \subset (0, \infty)$ satisfy the following conditions:

(I) $\lim_{n \to \infty} \alpha_n = 0, \sum_{n=1}^{\infty} \alpha_n = \infty$ and $\sum_{n=1}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty$;

(II) $\liminf_{n} r_n > 0$ and $\sum_{n=1}^{\infty} |r_{n+1} - r_n| < \infty$;

(III) $\lim_{n \to \infty} \beta_n = 0, \sum_{n=1}^{\infty} \beta_n = \infty$ and $\sum_{n=1}^{\infty} |\beta_{n+1} - \beta_n| < \infty$;

(IV) $\lim_{n \to \infty} (\alpha_n / \beta_n) = 0$.

Then, the sequences $\{x_n\}$ and $\{u_n\}$ converge strongly to $z \in F(T) \cap \text{EP}(\phi)$, where $z = P_{F(T) \cap \text{EP}(\phi)} f(z)$ and converge in norm to $Q(u)$, where $Q : C \to \text{Fix}(T)$ is the sunny nonexpansive retraction.

Proof. Let $Q = P_{F(T) \cap \text{EP}(\phi)}$. Then $Qf$ is a contraction of $H$ into itself. In fact, there exists $a \in [0, 1)$ such that $\|f(x) - f(y)\| \leq a\|x - y\|$ for all $x, y \in H$. So, we have that

$$\|Qf(x) - Qf(y)\| \leq \|f(x) - f(y)\| \leq a\|x - y\| \quad (3.1)$$

for all $x, y \in H$. So, $Qf$ is a contraction of $H$ into itself. Since $H$ is complete, there exists a unique element $z \in H$ such that $z = Qf(z)$, such a $z \in H$ is an element of $C$. We divide the proof into several steps.

Step 1. $\{x_n\}$ and $\{u_n\}$ are all bounded. Let $p \in F(T) \cap \text{EP}(\phi)$, Then from $u_n = T_{r_n} x_n$, we have

$$\|u_n - p\| = \|T_{r_n} x_n - T_{r_n} p\| \leq \|x_n - p\| \quad (3.2)$$
for all \( n \in \mathbb{N} \). Put \( y_n = \alpha_n u + (1 - \alpha_n) u_n \), so \( \{ x_{n+1} \} \) can be rewritten as

\[
x_{n+1} = \beta_n f(x_n) + (1 - \beta_n) Ty_n,
\]

\[
\| y_n - p \| = \| \alpha_n u + (1 - \alpha_n) u_n - p \|
\]

\[
= \| \alpha_n (u - p) + (1 - \alpha_n) (u_n - p) \|
\]

\[
\leq \alpha_n \| u - p \| + (1 - \alpha_n) \| u_n - p \|.
\] 

Therefore, from (3.2) we get

\[
\| y_n - p \| \leq \alpha_n \| u - p \| + (1 - \alpha_n) \| x_n - p \| \leq \max\{ \| u - p \|, \| x_n - p \| \}.
\] 

If \( \| x_n - p \| \leq \| u - p \| \), then \( \{ x_n \} \) is bounded. So, we assume that \( \| x_n - p \| \geq \| u - p \| \). Then \( \| y_n - p \| \leq \| x_n - p \| \),

\[
\| x_{n+1} - p \| = \| \beta_n f(x_n) + (1 - \beta_n) Ty_n - p \|
\]

\[
= \| \beta_n (f(x_n) - p) + (1 - \beta_n) (Ty_n - p) \|
\]

\[
\leq \beta_n \| f(x_n) - p \| + (1 - \beta_n) \| Ty_n - p \|
\]

\[
\leq \beta_n \alpha \| x_n - p \| + (1 - \beta_n) \| x_n - p \| + \beta_n \| f(p) - p \|
\]

\[
= (1 - (1 - \alpha) \beta_n) \| x_n - p \| + \beta_n (1 - \alpha) \frac{\| f(p) - p \|}{1 - \alpha}
\]

\[
\leq \max\{ \| x_n - p \| , \left\{ \frac{\| f(p) - p \|}{1 - \alpha} \right\} \}.
\] 

So, by induction, we have

\[
\| x_n - p \| \leq \max\{ \| x_1 - p \| , \left\{ \frac{\| f(p) - p \|}{1 - \alpha} \right\} \},
\] 

hence \( \{ x_n \} \) is bounded. We also obtain that \( \{ u_n \}, \{ Tu_n \}, \{ Tx_n \}, \{ f(x_n) \} \) and \( \{ y_n \} \) are bounded.

Step 2. \( \| x_{n+1} - x_n \| \to 0 \) as \( n \to \infty \),

\[
\| x_{n+1} - x_n \| = \| \beta_n f(x_n) + (1 - \beta_n) Ty_n - \beta_n f(x_{n-1}) - (1 - \beta_{n-1}) Ty_{n-1} \|
\]

\[
= \| \beta_n (f(x_n) - f(x_{n-1})) + (\beta_n - \beta_{n-1}) f(x_{n-1}) + Ty_n - Ty_{n-1} - \beta_n (Ty_n - Ty_{n-1}) - (\beta_n - \beta_{n-1}) Ty_{n-1} \|
\]

\[
\leq \beta_n \alpha \| x_n - x_{n-1} \| + (\beta_n - \beta_{n-1}) \| f(x_{n-1}) - Ty_{n-1} \|
\]

\[
\] 

\[
\| y_n - y_{n-1} \| = \| \alpha_n u + (1 - \alpha_n) u_n - \alpha_{n-1} u + (1 - \alpha_{n-1}) u_{n-1} \|
\]

\[
= \| (\alpha_n - \alpha_{n-1}) u + u_n - u_{n-1} - \alpha_n (u_n - u_{n-1}) - (\alpha_n - \alpha_{n-1}) u_{n-1} \|
\]

\[
\leq \| \alpha_n - \alpha_{n-1} \| \| u - u_{n-1} \| + (1 - \alpha_n) \| u_n - u_{n-1} \|.
\]
On the other hand, from \(\text{un} = Tr_n x_n\) and \(u_{n+1} = T_{r_{n+1}} x_{n+1}\), we have

\[
\phi(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C, \tag{3.9}
\]

\[
\phi(u_{n+1}, y) + \frac{1}{r_{n+1}} \langle y - u_{n+1}, u_{n+1} - x_{n+1} \rangle \geq 0, \quad \forall y \in C. \tag{3.10}
\]

Putting \(y = u_{n+1}\) in (3.9) and \(y = u_n\) in (3.10), we have

\[
\phi(u_n, u_{n+1}) + \frac{1}{r_n} \langle u_{n+1} - u_n, u_n - x_n \rangle \geq 0, \tag{3.11}
\]

\[
\phi(u_{n+1}, u_n) + \frac{1}{r_{n+1}} \langle u_n - u_{n+1}, u_{n+1} - x_{n+1} \rangle \geq 0.
\]

So, from \((A_2)\) we have

\[
\left\langle u_{n+1} - u_n, \frac{u_n - x_n}{r_n} - \frac{u_{n+1} - x_{n+1}}{r_{n+1}} \right\rangle \geq 0, \tag{3.12}
\]

and hence

\[
\left\langle u_{n+1} - u_n, u_n - u_{n+1} + u_{n+1} - x_n - \frac{r_n}{r_{n+1}} (u_{n+1} - x_{n+1}) \right\rangle \geq 0. \tag{3.13}
\]

Without loss of generality, let us assume that there exists a real number \(b\) such that \(r_n > b > 0\) for all \(n \in N\). Then, we have

\[
\|u_{n+1} - u_n\|^2 \leq \left\langle u_{n+1} - u_n, x_{n+1} - x_n + \left(1 - \frac{r_n}{r_{n+1}}\right) (u_{n+1} - x_{n+1}) \right\rangle
\]

\[
\leq \|u_{n+1} + u_n\| \left\{ \|x_{n+1} - x_n\| + \left|1 - \frac{r_n}{r_{n+1}}\right| \|u_{n+1} - u_{n+1}\| \right\}, \tag{3.14}
\]

and hence

\[
\|u_{n+1} - u_n\| \leq \|x_{n+1} - x_n\| + \frac{1}{r_{n+1}} |r_{n+1} - r_n| \|u_{n+1} - x_{n+1}\|
\]

\[
\leq \|x_{n+1} - x_n\| + \frac{1}{b} |r_{n+1} - r_n| L, \tag{3.15}
\]

where \(L = \sup\{\|u_n - x_n\| : n \in N\}\). Then we obtain

\[
\|u_n - u_{n-1}\| \leq \|x_n - x_{n-1}\| + \frac{1}{b} |r_n - r_{n-1}| L. \tag{3.16}
\]
So, put (3.8) and (3.16) into (3.7) we have

\[
\|x_{n+1} - x_n\| \leq \beta_n \alpha \|x_n - x_{n-1}\| + \left(1 - \beta_n\right) \left(\|x_{n-1} - x_{n-2}\| + (1 - \alpha_n) \left(\|x_{n-1} - x_n\| + \frac{1}{\beta} |r_n - r_{n-1}|L\right)\right) \\
\leq (1 - (1 - \alpha) \beta_n) \|x_n - x_{n-1}\| + \frac{1}{\beta} |r_n - r_{n-1}|L \\
+ |\alpha_n - \alpha_{n-1}| K_1 + |\beta_n - \beta_{n-1}| K_2,
\]

(3.17)

where \(K_1 := \sup\{\|u - u_n\|, \forall n \geq 1\}\) is a constant; \(K_2 := \sup\{\|f(x_{n-1})\| + \|Ty_{n-1}\|, \forall n \geq 1\}\) is a constant.

Using Lemma 2.3 and conditions (I), (II), (III) we have

\[
\lim_{n \to \infty} \|x_{n+1} - x_n\| = 0.
\]

(3.18)

From (3.15) and \(|r_{n+1} - r_n| \to 0\), we have

\[
\lim_{n \to \infty} \|u_{n+1} - u_n\| = 0.
\]

(3.19)

Since \(y_n = \alpha_n u + (1 - \alpha_n) u_n, x_n = \beta_n f(x_{n-1}) + (1 - \beta_n) Ty_{n-1}\), we have

\[
\|y_n - u_n\| = \alpha_n \|u - u_n\| \to 0, \quad \text{as} \ n \to \infty, \\
\|x_n - Tu_n\| \leq \|x_n - Ty_{n-1}\| + \|Ty_{n-1} - Tu_{n-1}\| + \|Tu_{n-1} - Tu_n\| \\
\leq \beta_{n-1} \|f(x_{n-1}) + Ty_{n-1}\| + \|y_{n-1} - u_{n-1}\| + \|u_n - u_{n-1}\| \to 0, \quad \text{as} \ n \to \infty.
\]

(3.20)

(3.21)

For \(p \in F(T) \cap EP(\phi)\), we have

\[
\|u_n - p\|^2 = \|Tr_n x_n - Tr_p\|^2 \leq \langle Tr_n x_n - Tr_p, x_n - p \rangle \\
= \langle u_n - p, x_n - p \rangle \\
= \frac{1}{2} \left(\|u_n - p\|^2 + \|x_n - p\|^2 - \|u_n - x_n\|^2\right),
\]

(3.22)

\[
\|u_n - p\|^2 \leq \|x_n - p\|^2 - \|u_n - x_n\|^2.
\]
Therefore, we have
\[
\|x_{n+1} - p\|^2 = \|(1 - \beta_n) (T y_n - p) + \beta_n (f(x_n) - p)\|^2 \\
\leq (1 - \beta_n)^2 \|T y_n - p\|^2 + 2 \beta_n \langle f(x_n) - p, x_{n+1} - p \rangle \\
\leq (1 - \beta_n)^2 (\|y_n - u_n\| + \|u_n - p\|)^2 + 2 \beta_n \|x_n - p\| \|x_{n+1} - p\| + 2 \beta_n \|f(p) - p\| \|x_{n+1} - p\| \\
= (1 - \beta_n)^2 \|u_n - p\|^2 + \|y_n - u_n\| (1 - \beta_n)^2 (\|y_n - u_n\| + 2 \|u_n - p\|) \\
+ 2 \beta_n \|x_n - p\| \|x_{n+1} - p\| + 2 \beta_n \|f(p) - p\| \|x_{n+1} - p\| \\
= \left(1 - 2 \beta_n + \beta_n^2 \right) \|x_n - p\|^2 - (1 - \beta_n)^2 \|u_n - x_n\|^2 \\
+ \|y_n - u_n\| (1 - \beta_n)^2 (\|y_n - u_n\| + 2 \|u_n - p\|) \\
+ 2 \beta_n \|x_n - p\| \|x_{n+1} - p\| + 2 \beta_n \|f(p) - p\| \|x_{n+1} - p\| \\
\leq \|x_n - x_{n+1}\| (\|x_n - p\| + \|x_{n+1} - p\|) \\
+ \beta_n \left( \beta_n \|x_n - p\|^2 - 2 \|x_n - p\|^2 \right) - (1 - \beta_n)^2 \|u_n - x_n\|^2 \\
+ \|y_n - u_n\| (1 - \beta_n)^2 (\|y_n - u_n\| + 2 \|u_n - p\|) \\
+ 2 \beta_n \|x_n - p\| \|x_{n+1} - p\| + 2 \beta_n \|f(p) - p\| \|x_{n+1} - p\| \\
\leq \|x_n - x_{n+1}\| (\|x_n - p\| + \|x_{n+1} - p\|) \\
+ \beta_n \left( \beta_n \|x_n - p\|^2 - 2 \|x_n - p\|^2 \right) - (1 - \beta_n)^2 \|u_n - x_n\|^2 \\
+ \|y_n - u_n\| (1 - \beta_n)^2 (\|y_n - u_n\| + 2 \|u_n - p\|) \\
+ 2 \beta_n \|x_n - p\| \|x_{n+1} - p\| + 2 \beta_n \|f(p) - p\| \|x_{n+1} - p\|. \\
\tag{3.23}
\]

By the above of what we have and the condition of \(\lim_{n \to \infty} \beta_n = 0\), we get \(\lim_{n \to \infty} \|x_n - u_n\| = 0\). Since \(\|T u_n - u_n\| \leq \|T u_n - x_n\| + \|x_n - u_n\|\), it follows that \(\|T u_n - u_n\| \to 0\).

**Step 3.** we show that
\[
\limsup_{n \to \infty} \langle f(z) - z, x_n - z \rangle \leq 0, \tag{3.24}
\]
where \( z = P_{F(S) \cap EP(\phi)} f(z) \). To show this inequality, we choose a subsequence \( \{u_{n_i}\} \) of \( \{u_n\} \) such that

\[
\limsup_{i \to \infty} \langle f(z) - z, x_{n_i} - z \rangle = \limsup_{n \to \infty} \langle f(z) - z, x_n - z \rangle.
\] (3.25)

Since \( \{u_{n_i}\} \) is bounded, there exists a subsequence \( \{u_{n_i}\} \) of \( \{u_n\} \) which converges weakly to \( w \). Without loss of generality, we can assume that \( u_{n_i} \rightharpoonup w \). From \( \|Tu_{n_i} - u_n\| \to 0 \), we obtain \( Tu_{n_i} \rightharpoonup w \). Let us show \( w \in EP(\phi) \). By \( u_n = Tu_{n_i} \), we have

\[
\phi(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C.
\] (3.26)

From \((A_2)\), we also have

\[
\frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq \phi(y, u_n),
\] (3.27)

and hence

\[
\langle y - u_n, \frac{u_n - x_n}{r_n} \rangle \geq \phi(y, u_n).
\] (3.28)

Since \( u_{n_i} - x_{n_i}/r_{n_i} \to 0 \) and \( u_{n_i} \rightharpoonup w \), from \((A_1)\) we have \( 0 \geq \phi(y, w) \) for all \( y \in C \). For \( t \) with \( 0 < t < 1 \) and \( y \in C \), let \( y_t = ty + (1 - t)w \). Since \( y_t \in C \) and \( w \in C \), we have \( y_t \in C \) and hence \( \phi(y_t, w) \leq 0 \). So, from \((A_1)\) and \( A_4 \) we have

\[
0 = \phi(y_t, y_t) \leq t\phi(y_t, y) + (1 - t)\phi(y_t, w)
\] (3.29)

and hence \( 0 \leq \phi(y_t, y) \). From \((A_3)\), we have \( 0 \leq \phi(w, y) \) for all \( y \in C \), and hence \( w \in EP(\phi) \).

We will show that \( w \in F(T) \). Assume that \( w \notin F(T) \). Since \( u_{n_i} \rightharpoonup w \) and \( w \notin Tw \), from Opial’s theorem we have

\[
\liminf_{i \to \infty} \|u_{n_i} - w\| < \liminf_{i \to \infty} \|u_{n_i} - Tw\|
\leq \liminf_{i \to \infty} \|u_{n_i} - Tu_{n_i}\| + \|Tu_{n_i} - Tw\|
\leq \liminf_{i \to \infty} \|u_{n_i} - w\|.
\] (3.30)

This is a contradiction. So, we get \( w \in F(T) \). Therefore, \( w \in F(T) \cap EP(\phi) \). Since \( z = P_{F(T) \cap EP(\phi)} f(z) \), we have

\[
\limsup_{n \to \infty} \langle f(z) - z, x_n - z \rangle = \lim_{i \to \infty} \langle f(z) - z, x_{n_i} - z \rangle
= \langle f(z) - z, w - z \rangle \leq 0.
\] (3.31)
From \( x_{n+1} - z = (1 - \beta_n)Ty_n - z + \beta_n(f(x_n) - z) \), we have

\[
\|x_{n+1} - z\|^2 \leq (1 - \beta_n)^2\|y_n - z\|^2 + 2\beta_n\|f(x_n) - z, x_{n+1} - z\|
\]

\[
\leq (1 - \beta_n)^2\|\alpha_n(u - z) + (1 - \alpha_n)(x_n - z)\|^2
\]

\[
+ 2\beta_n\|x_n - z\|\|x_{n+1} - z\| + 2\beta_n\langle f(z) - z, x_{n+1} - z\rangle
\]

\[
\leq (1 - \beta_n)^2\left(\alpha_n\|u - z\|^2 + (1 - \alpha_n)\|x_n - z\|^2\right)
\]

\[
+ \beta_n\alpha_\beta_n\|x_{n+1} - z\|^2 + 2\beta_n\langle f(z) - z, x_{n+1} - z\rangle
\]

\[
\leq \left[ (1 - \beta_n)^2(1 - \alpha_n) + \beta_n\alpha_\beta_n \right]\|x_n - z\|^2
\]

\[
+ \beta_n\alpha_\beta_n\|x_{n+1} - z\|^2 + (1 - \beta_n)^2\alpha_n\|u - z\|^2 + 2\beta_n\langle f(z) - z, x_{n+1} - z\rangle,
\]

\[
\|x_{n+1} - z\|^2 \leq \frac{(1 - \beta_n)^2 + \beta_n\alpha}{1 - \alpha\beta_n}\|x_n - z\|^2
\]

\[
+ \frac{(1 - \beta_n)^2\alpha_n}{1 - \alpha\beta_n}\|u - z\|^2 + \frac{2\beta_n}{1 - \alpha\beta_n}\langle f(z) - z, x_{n+1} - z\rangle
\]

\[
\leq \left[ 1 - \frac{2(1 - \alpha)\beta_n}{1 - \alpha\beta_n} \right]\|x_n - z\|^2 + \frac{\beta_n^2}{1 - \alpha\beta_n}\|x_n - z\|^2
\]

\[
+ \frac{(1 - \beta_n)^2\alpha_n}{1 - \alpha\beta_n}\|u - z\|^2 + \frac{2\beta_n}{1 - \alpha\beta_n}\langle f(z) - z, x_{n+1} - z\rangle
\]

\[
\leq \left[ 1 - \frac{2(1 - \alpha)\beta_n}{1 - \alpha\beta_n} \right]\|x_n - z\|^2 + \frac{2(1 - \alpha)\beta_n}{1 - \alpha\beta_n}
\]

\[
\times \left\{ \frac{\beta_n^2}{2(1 - \alpha)} M + \frac{(1 - \beta_n)^2\alpha_n}{2(1 - \alpha)\beta_n}\|u - z\|^2 + \frac{1}{1 - \alpha}\langle f(z) - z, x_{n+1} - z\rangle \right\}
\]

\[
= (1 - \delta_n)\|x_n - z\|^2 + \delta_n\zeta_n,
\]

(3.32)

where \( M = \sup\{\|x_n - z\|^2 : n \in \mathbb{N}\} \), \( \delta_n = 2(1 - \alpha)\beta_n/1 - \alpha\beta_n \) and \( \zeta_n := \beta_n/2(1 - \alpha)M + (1 - \beta_n)^2\alpha_n/2(1 - \alpha)\beta_n\|u - z\|^2 + 1/\alpha\langle f(z) - z, x_{n+1} - z\rangle \). It is easy to see that \( \delta_n \to 0 \), \( \Sigma_{n=1}^\infty\delta_n = \infty \) and \( \limsup_{n \to \infty} \zeta_n/\delta_n \leq 0 \) by (3.31) and the conditions. Hence, by Lemma 2.3, the sequence \( \{x_n\} \) converges strongly to \( z \).

If \( z_t \) is defined as (2.1), then, from Lemma 2.5, we have \( \|z_t - q\| \to 0 \) as \( t \to 0 \), and if we set \( Q(u) := \lim_{t \to 0} z_t \), then \( Q \) defines the unique sunny nonexpansive retraction from \( C \) onto \( \text{Fix}(T) \). So, if we replace \( t \) with \( \alpha_n \), the corollary still holds. And it is that \( z_n = T(\alpha_n u + (1 - \alpha_n)z_n) \) is a fixed point sequence and \( \|z_n - q\| \to 0 \) as \( n \to \infty \), and if we set \( Q(u) := \lim_{n \to \infty} z_n \), then \( Q \) defines the unique sunny nonexpansive retraction from \( C \) onto \( \text{Fix}(T) \). In the iterative algorithm of Theorem 3.1, we can take \( z_n \) to replace \( Ty_n \) in particular. Then, we have \( x_{n+1} = \beta_n f(x_n) + (1 - \beta_n)z_n \), so \( \|x_{n+1} - z_n\| = \beta_n\|f(x_n) - z_n\| \to 0 \) as \( n \to \infty \). By the uniqueness
of limit, we have \( z = q \), that is, \( z = Q(u) \), where \( Q \) defines the unique sunny nonexpansive retraction from \( C \) onto \( \text{Fix}(T) \).

\[ \square \]

**Remark.** We notice that \( u_n = T_n x_n \) has not influence on \( x_n \), \( u_n \to z = P_{F(T) \cap \text{EP}(\phi)} f(z) \).

As direct consequences of Theorem 3.1, we obtain corollary.

**Corollary 3.2.** Let \( C \) be a nonempty closed convex subset of \( H \), \( S : C \to C \) be a nonexpansive mapping of \( C \) into \( H \) such that \( F(S) \neq \emptyset \). Let \( f \) be a contraction of \( H \) into itself and let \( \{x_n\} \) and \( \{u_n\} \) be sequences generated initially by an arbitrary elements \( x_1 \in H \) and then by

\[
x_{n+1} = \beta_n f(x_n) + (1 - \beta_n) S(\alpha_n u + (1 - \alpha_n) PC x_n)
\] (3.33)

for all \( n \in N \), where \( \{\alpha_n\} \subset (0, \infty) \) satisfies the following conditions:

1. \( \lim_{n \to \infty} \alpha_n = 0 \), \( \sum_{n=1}^{\infty} \alpha_n = \infty \) and \( \sum_{n=1}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty \);
2. \( \lim_{n \to \infty} \beta_n = 0 \), \( \sum_{n=1}^{\infty} \beta_n = \infty \) and \( \sum_{n=1}^{\infty} |\beta_{n+1} - \beta_n| < \infty \);
3. \( \lim_{n \to \infty} \frac{\alpha_n}{\beta_n} = 0 \).

Then, the sequences \( \{x_n\} \) converge strongly to \( z \in F(S) \), where \( z = P_{F(S)} f(z) \).

**Proof.** Put \( \phi(x, y) = 0 \), for all \( x, y \in C \) and \( r_n = 1 \), for all \( n \in N \) in Theorem 3.1.

Then we have \( u_n = PC x_n \). So, from Theorem 3.1, the sequence \( x_n \) generated by \( x_1 \in H \) and

\[
x_{n+1} = \beta_n f(x_n) + (1 - \beta_n) S(\alpha_n u + (1 - \alpha_n) PC x_n)
\] (3.34)

for all \( n \in \mathbb{N} \) converges strongly to \( z \in F(S) \), where \( z = P_{F(S)} f(z) \). \( \square \)

### 4. Application for Zeros of Maximal Monotone Operators

We adapt in this section the iterative algorithm (3.1) to find zeros of maximal monotone operators and find EP(\( \phi \)). Let us recall that an operator \( A \) with domain \( D(A) \) and range \( R(A) \) in a real Hilbert space \( H \) with inner product \( \langle \cdot, \cdot \rangle \) and norm \( \| \cdot \| \) is said to be monotone if the graph of \( A \),

\[ G(T) := \{(x, y) \in H \times H : x \in D(T), \ y \in Tx\} \] (4.1)

is a monotone set. Namely,

\[ \langle x - x', y - y' \rangle \geq 0, \quad (x, y), (x', y') \in G(A). \] (4.2)

A monotone operator \( A \) is said to be maximal monotone of the graph \( G(T) \) is not properly contained in the graph of any other monotone defined in \( H \). See Brezis [16] for more details on maximal monotone operators.
In this section, we always assume that $A$ is maximal monotone and the set of zeros of $A$, $N(A) = \{x \in D(A) : 0 \in Ax\}$, is nonempty so that the metric projection $P_{N(A)}$ from $H$ onto $N(A)$ is well-defined.

One of the major problems in the theory of maximal operators is to find a point in the zero set $N(A)$ because various problems arising from economics, convex programming, and other applied areas can be formulated as finding a zero of maximal monotone operators. The proximal point algorithm (PPA) of Rockafellar [17] is commonly recognized as the most powerful algorithm in finding a zero of maximal monotone operators. This (PPA) generates, starting with any initial guess $x_0 \in H$, a sequence $\{x_n\}$ according to the inclusion:

$$x_n + e_n \in x_{n+1} + c_n A(x_{n+1}),$$

where $\{e_n\}$ is a sequence of errors and $\{c_n\}$ is a sequence of positive regularization parameters. Equivalently, we can write

$$x_{n+1} = f^c_A(x_n + e_n),$$

where for $c > 0$, $f^c_A$ denotes the resolvent of $A$, $f^c_A = (I + cA)^{-1}$, with $I$ being the identity operator on the space $H$.

Rockafellar [17] proved the weak convergence of his algorithm (4.4) provided the regularization sequence $\{c_n\}$ remains bounded away from zero and the error sequence $\{e_n\}$ satisfies the condition

$$\sum_{n=0}^{\infty} \|e_n\| < \infty.$$  (4.6)

The aim of this section is to combine algorithm (3.1) with algorithm (4.4). Our algorithm generates a sequence $\{x_n\}$ and $\{u_n\}$ be sequences generated initially by an arbitrary elements $x_1 \in H$ and then by

$$\phi(u_n, y) + \frac{1}{r_n}(y - u_n, y - x_n) \geq 0, \quad \forall y \in C,$$

$$x_{n+1} = \beta_n f(x_n) + (1 - \beta_n) f^A_{c_n}(\alpha_n u + (1 - \alpha_n) u_n + e_n),$$

where $\alpha_n$ and $c_n$ are sequences of positive real numbers. Furthermore, we prove that $\{x_n\}$ and $\{u_n\}$ converge strongly to $z \in N(A) \cap \text{EP}(\phi)$, where $z = P_{N(A) \cap \text{EP}(\phi)} f(z)$.

Before stating the convergence theorem of the algorithm (4.7), we list some properties of maximal monotone operators.

**Proposition 4.1.** Let $A$ be a maximal monotone operator in $H$ and let $f^c_A = (I + cA)^{-1}$ denote the resolvent, where $c > 0$,

(a) $f^c_A$ is nonexpansive for all $c > 0$;
(b) $N(A) = F(f_c)$ for all $c > 0$;
(c) For $c > c' > 0$, $\|J^A_c - x\| \leq 2\|J^A_c - x\|$ for $x \in H$;

(d) (The Resolvent Identity) For $\lambda, \mu > 0$, there holds the identity:

$$J^I_\lambda x = J^I_\mu (\frac{\mu}{\lambda} x + (1 - \frac{\mu}{\lambda})J^I_\lambda x), \quad x \in H. \quad (4.8)$$

**Theorem 4.2.** Let $C$ be a nonempty closed convex subset of $H$, $\phi : C \times C \to \mathbb{R}$ be a bifunction satisfying $(A_1)$–$(A_4)$ and $A$ be a maximal monotone operator such that $N(A) \cap \text{EP}(\phi) \neq \emptyset$. Let $f$ be a contraction of $H$ into itself and let $\{x_n\}$ and $\{u_n\}$ be sequences generated initially by an arbitrary elements $x_0 \in H$ and then by

$$\begin{align*}
\phi(u_n, y) + \frac{1}{r_n}(y - u_n, u_n - x_n) &\geq 0, \quad \forall y \in C, \\
x_{n+1} &= \beta_n f(x_n) + (1 - \beta_n)J^A_c(\alpha_n u + (1 - \alpha_n)u_n + e_n),
\end{align*} \quad (4.9)$$

for all $n \in \mathbb{N}$, where $\{\alpha_n\} \subset [0, 1]$ and $\{r_n\} \subset (0, \infty)$ satisfy the following conditions:

(I) $\lim_{n \to \infty} \alpha_n = 0$, $\sum_{n=1}^\infty \alpha_n = \infty$ and $\sum_{n=1}^\infty |\alpha_{n+1} - \alpha_n| < \infty$;

(II) $\liminf_n r_n > 0$ and $\sum_{n=1}^\infty |r_{n+1} - r_n| < \infty$;

(III) $\lim_{n \to \infty} (c_{n+1}/c_n) = 1$;

(IV) $\lim_{n \to \infty} \beta_n = 0$, $\sum_{n=1}^\infty \beta_n = \infty$, $\sum_{n=1}^\infty |\beta_{n+1} - \beta_n| < \infty$, and $\lim_{n \to \infty} (\alpha_n/\beta_n) = 0$.

Then, the sequences $\{x_n\}$ and $\{u_n\}$ converge strongly to $z \in N(A) \cap \text{EP}(\phi)$, where $z = P_{N(A) \cap \text{EP}(\phi)} f(z)$.

**Proof.** Below we write $J_c = J^A_c$ for simplicity. Setting

$$w_n = \alpha_n u + (1 - \alpha_n)u_n + e_n, \quad y_n = J_c w_n, \quad (4.10)$$

we rewrite $x_{n+1}$ of (4.7) as

$$x_{n+1} = \beta_n f(x_n) + (1 - \beta_n)J_c w_n = \beta_n f(x_n) + (1 - \beta_n) y_n. \quad (4.11)$$

Because the proof is similar to Theorem 3.1, here we just give the main steps as follows:

(1) $\{x_n\}$ is bounded;

(2) $\|x_{n+1} - x_n\| \to 0$, as $n \to 0$;

(3) $\|u_n - J_c u_n\| \to 0$, as $n \to 0$;

(4) $\|x_n - u_n\| \to 0$, as $n \to 0$;

(5) $\limsup_{n \to \infty} (f(z) - z, x_n - z) \leq 0$;

(6) $x_n, u_n \to z$, as $n \to z$. \qed
5. Application for Optimization Problem

In this section, we study a kind of optimization problem by using the result of this paper. That is, we will give an iterative algorithm of solution for the following optimization problem with nonempty set of solutions

\[
\min h(x), \\
x \in C,
\]

where \( h(x) \) is a convex and lower semicontinuous functional defined on a closed convex subset \( C \) of a Hilbert space \( H \). We denoted by \( B \) the set of solutions of (5.1). Let \( \phi \) be a bifunction from \( C \times C \) to \( R \) defined by \( \phi(x, y) = h(y) - h(x) \). We consider the following equilibrium problem, that is, to find \( x \in C \) such that

\[
\phi(x, y) \geq 0, \quad \forall y \in C. \tag{5.2}
\]

It is obvious that \( EP(\phi) = B \), where \( EP(\phi) \) denotes the set of solutions of equilibrium problem (5.2). In addition, it is easy to see that \( \phi(x, y) \) satisfies the conditions \( (A_1) - (A_4) \) in the Section 2. Therefore, from Theorem 3.1, we know that the following iterative algorithm:

\[
h(y) - h(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \geq 0, \quad \forall y \in C,
\]

\[
x_{n+1} = \beta_n f(x_n) + (1 - \beta_n) T(\alpha_n u + (1 - \alpha_n) u_n), \tag{5.3}
\]

for any initial guess \( x_1 \), converges strongly to a solution \( z = P_B f(z) \) of optimization problem (5.1), where \( \{\alpha_n\} \subset [0, 1] \), \( \{\beta_n\} \subset [0, 1] \), and \( \{r_n\} \subset [0, \infty) \) satisfy

\[
\lim_{n \to \infty} \alpha_n = 0, \quad \sum_{n=1}^{\infty} \alpha_n = \infty, \quad \sum_{n=1}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty,
\]

\[
\lim_{n \to \infty} \beta_n = 0, \quad \sum_{n=1}^{\infty} \beta_n = \infty, \quad \sum_{n=1}^{\infty} |\beta_{n+1} - \beta_n| < \infty, \quad \lim_{n \to \infty} \frac{\alpha_n}{\beta_n} = 0, \tag{5.4}
\]

\[
\liminf_{n \to \infty} r_n > 0, \quad \sum_{n=1}^{\infty} |r_{n+1} - r_n| < \infty.
\]

For a special case, we pick \( f(x) = \eta \), for all \( \eta \in H \), and \( r_n = 1, \beta_n = 1/2 \) and \( \alpha_n = 0 \) for all \( n \geq 1 \), then \( x_{n+1} = (1/2)Tu_n + (1/2)\eta \), from (5.3), we get the special iterative algorithm as follows:

\[
h(y) - h(u_n) + \left\langle y - u_n, u_n - \left(\frac{1}{2} \eta + \frac{1}{2} T u_n\right)\right\rangle \geq 0, \quad \forall y \in C, \ n \geq 2,
\]

\[
h(y) - h(u_1) + \left\langle y - u_1, u_1 - \left(\frac{1}{2} \eta + \frac{1}{2} T u_1\right)\right\rangle \geq 0, \quad \forall y \in C. \tag{5.5}
\]

Then \( \{u_n\} \) converges strongly to a solution \( z = P_B \eta \) of optimization problem (5.1).

In fact, \( z \) is the minimum norm point from \( \eta \) onto the \( B \), furthermore, if \( \eta = 0 \), then \( z \) is the minimum norm point on the \( B \).
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References
