A PARABOLIC ANALOGUE OF FINN’S MAXIMUM PRINCIPLE

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Abstract. We obtain a parabolic analogue of the well-known maximum principle established by R. Finn for solutions of the minimal surface equation.

1. Introduction and main results

The aim of this article is to discuss certain properties of the solutions of the equation

\[ u_t = \sum_{i=1}^{n} \frac{\partial}{\partial x_i} \left( \frac{u_{x_i}}{\sqrt{1 + |\nabla x u|^2}} \right), \tag{1} \]

which are parabolic analogues of the well-known maximum principle established by Finn [2] for solutions of the minimal surface equation

\[ \sum_{i=1}^{n} \frac{\partial}{\partial x_i} \left( \frac{u_{x_i}}{\sqrt{1 + |\nabla x u|^2}} \right) = 0. \tag{2} \]

It is known that while in some respects solutions of the minimal surface equation behave in complete accordance with the general theory of elliptic equations, in other respects these solutions reveal completely unexpected properties. Examples of the latter case are the well-known theorem of Bernstein [1] on the non-existence of non-trivial solutions of equation (2) in the whole space, for \( n = 2 \), and Finn’s maximum principle [2].

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Let $R_{a,b}$ be the ring \{$(x_1,...,x_n) \in \mathbb{R}^n, a < r < b \}$, $r = \sqrt{x_1^2 + ... + x_n^2}$, $n \geq 2, 0 < a < b < \infty$, and $D$ an arbitrary domain in $\mathbb{R}^n$. Also let $K(r,a) = \cosh^{-1} \frac{r}{a}, K(r,a) \leq 0$.

The function $K(r,a)$ determines a supersolution (in the case $n = 2$ a solution) of the minimal surface equation (2) in the exterior of the sphere \{\$r = a\$\} that vanishes on this sphere. It is easy to see that this supersolution cannot be extended inside the sphere \{\$r = a\$\}.

Let us state Finn’s maximum principle in one of its simplest versions (see [6]).

Let $c$ be an arbitrary fixed constant.

**Theorem (Finn).** Let $D \subseteq R_{a,b}$, and let $u(x)$ be a solution of the minimal surface equation (2) in $D$, continuous in $\bar{D}$ and such that $u - K(r,a) \leq c$ on $\partial D \setminus \{r = a\}$. Then $u - K(r,a) \leq c$ in $D$.

We note that the essential difference between the behaviour of solutions of the minimal surface equation and solutions of linear uniformly-elliptic equations is particularly well seen in the case when part of the boundary of the domain $D$ lies on the sphere \{\$r = a\$\}, for example, when $D = R_{a,b}$.

In view of the fact that each solution of the minimal surface equation is a solution of (1), it is clear that the second solutions inherit one or other properties of the first solutions, and hence it is reasonable to assume that the situation described above for solutions of the minimal surface equation will also be seen in the case of equation (1), namely: while in some respects the solutions of equation (1) behave in complete accordance with the general theory of parabolic equations, in other respects these solutions reveal completely unexpected properties (see, for example, [4-5]). However, sometimes these completely unexpected properties are fully expected, and, moreover, solutions of equation (1) in fact inherit one or other properties of solutions of the minimal surface equation. The main aim of this article is to give another confirmation of this intuitive hypothesis.

Suppose, as above, that $D$ is an arbitrary domain in $\mathbb{R}^n$, which in general may coincide with the whole space, $D_T = (0,T) \times D$, and $\partial D_T = D \cup \{(0,T) \times \partial D\}$ is the parabolic part of the boundary of $D_T$. If $D = \mathbb{R}^n$ we take $\partial D$ to be empty.

**Definition.** By a subsolution (supersolution) of equation (1) in $D_T$ we mean a function $u(t,x)$ which belongs to the space $C(0,T; Lip_{loc}(D))$, whose derivative $u_t$ belongs to the space $L_1(0,T; L_1,loc(D))$, and which satisfies the following integral inequality:

\[
\int_{D_T} \left[ u_t \varphi + \sum_{i=1}^{n} \varphi_{x_i} \frac{u_{x_i}}{\sqrt{1 + |\nabla u|^2}} \right] dt dx \leq 0 \quad (\geq 0)
\]

for an arbitrary nonnegative function $\varphi \in C(0,T; \overline{\mathbb{R}(D)})$.

Let $E$ be the exterior of the sphere \{\$r = a\$\}, $E_T = (0,T) \times E, \partial_F D_T = D \cup \{(0,T) \times \{\partial D \setminus \{r = a\}\}\}$, and let $c_1 \geq 1$ and $c$ be arbitrary fixed constants.
Theorem 1. Suppose that \( u(t, x) \) is a subsolution of equation (1) in \( D_T, \)
\( D_T \subseteq E_T, \) continuous on the set \( D_T \cup \partial D_T \) and such that \( u - c_1 K(r, a) \leq c \)
on \( \partial F D_T. \) Then \( u - c_1 K(r, a) \leq c \) in \( D_T. \)

Similar results hold for supersolutions of equation (1).

Theorem 1’. Suppose that \( v(t, x) \) is a supersolution of equation (1) in \( D_T, \)
\( D_T \subseteq E_T, \) continuous on the set \( D_T \cup \partial F D_T \) and such that \( v + c_1 K(r, a) \geq c \)
on \( \partial F D_T. \) Then \( v + c_1 K(r, a) \geq c \) in \( D_T. \)

Apparently the most impressive example is when the domain \( D \) coincides
with the ring \( R_{a,b} \) or with the exterior of the sphere \( \{ r = a \}. \) In the first
case we have a direct parabolic analogue of the Finn’s maximum principle
[2].

Corollary 1. Suppose that \( u(t, x) \) is a subsolution of equation (1) in \( (0, T) \times R_{a,b}, \)
continuous on the set \( [0, T) \times \{ a < r \leq b \} \) and such that \( u - K(r, a) \leq c \)
on \( R_{a,b} \cup \{ [0, T) \times \{ r = b \} \}. \) Then \( u - K(r, a) \leq c \) in \( (0, T) \times R_{a,b}. \)

Corollary 2. Suppose that \( u(t, x) \) is a subsolution of equation (1) in \( E_T, \)
continuous on \( E \) and such that \( u - c_1 K(r, a) \leq c \) on \( E. \) Then \( u - c_1 K(r, a) \leq c \)
in \( E_T. \)

The above assertions form a working tool for studying the qualitative
properties of solutions of equation (1) in the same way as Finn’s maximum
principle for solutions of the minimal surface equation (2). We give the
simplest of them.

Corollary 3. Suppose that \( u(t, x) \) is a subsolution of equation (1) in \( (0, T) \times \)
\( \{ 0 < r \leq b \}, \) continuous on the set \( [0, T) \times \{ 0 < r \leq b \} \) and such that \( u - K(r, a) \leq c \)
on \( \{ 0 < r < b \} \cup \{ [0, T) \times \{ r = b \} \}. \) Then \( \lim_{(\tau, x) \to (t, 0)} u(t, x) \)
\( \leq c \) for all \( (\tau, x) \in (0, T) \times \{ 0 < r < b \} \) and all \( t \in (0, T). \)

Proof. For fixed \( r, \lim_{a \to 0} \cosh^{-1} \frac{r}{a} = 0. \)

Questions on the solubility of initial-value problems for equation (1)
acquire a special interest in connection with what has been said above. It is
easy to construct special cases of insolubility by using the stated assertions.

The basic idea of the proof of Theorem 1 (Theorem 1’) consists in comparing
the unknown subsolution (supersolution) of equation (1) with a definite
fixed supersolution (subsolution) of the same equation whose properties have
been thoroughly studied. An application of this fundamental approach is
possible based on the following assertion.

Theorem 2 (Comparison Principle). Let \( u(t, x) \) and \( v(t, x) \) be respectively a subsolution and a supersolution of equation (1) in \( D_T, \)
continuous on the set \( D_T \cup \partial D_T \) and such that \( u \leq v \) on \( \partial D_T. \) Then \( u \leq v \) in \( D_T. \)

We note that the comparison principle stated here has no direct analogues
in the framework of the linear theory of parabolic equations. A confirmation
of this is well-known fact that a non-trivial classical solution exists of the
Cauchy problem for the heat conduction equation with zero initial data [7].
2. Proofs of the main results

Proof of Theorem 2. Let \( u(t,x) \) and \( v(t,x) \) be respectively a subsolution and a supersolution of equation (1) in \( D_T \) such that \( u \leq v \) on \( \partial D_T \).

It follows then from (3) that for an arbitrary nonnegative function \( \varphi \in C(0,T; \text{Lip}(D)) \) the relations

\[
\int_{D_T} \left[ u_t \varphi + \sum_{i=1}^{n} \varphi_{x_i} \frac{u_{x_i}}{\sqrt{1 + |\nabla x u|^2}} \right] dtdx \leq 0
\]

and

\[
\int_{D_T} \left[ v_t \varphi + \sum_{i=1}^{n} \varphi_{x_i} \frac{v_{x_i}}{\sqrt{1 + |\nabla x v|^2}} \right] dtdx \geq 0
\]

hold.

By subtracting the latter from the former we obtain the inequality

\[
\int_{D_T} \left[ (u - v)_t \varphi + \sum_{i=1}^{n} \varphi_{x_i} \left( \frac{u_{x_i}}{\sqrt{1 + |\nabla x u|^2}} - \frac{v_{x_i}}{\sqrt{1 + |\nabla x v|^2}} \right) \right] dtdx \\
\leq 0
\]

Let \( 0 < r < R, s > 1 \) and \( p > 1 \) be arbitrary real numbers. Set \( \varphi = \exp(-t) \psi^s(x) w^p \) in (4), where \( w(t,x) = \exp(-t)(u - v)^+(t,x), \psi \in \dot{C}^\infty (\{x: |x| < R\}) \), \( 0 \leq \psi(x) \leq 1 \), \( \psi(x) = 1 \) at \( \{x : |x| \leq r\} \). Then

\[
\int_{D_T} (u - v)_t \psi^s w^p \exp(-t) dtdx \\
+ p \int_{D_T} \sum_{i=1}^{n} \psi_{x_i} \left( \frac{u_{x_i}}{\sqrt{1 + |\nabla x u|^2}} - \frac{v_{x_i}}{\sqrt{1 + |\nabla x v|^2}} \right) \\
\cdot \exp(-t) \psi^s w^{p-1} dtdx \\
+ s \int_{D_T} \sum_{i=1}^{n} \psi_{x_i} \left( \frac{u_{x_i}}{\sqrt{1 + |\nabla x u|^2}} - \frac{v_{x_i}}{\sqrt{1 + |\nabla x v|^2}} \right) \\
\cdot \exp(-t) \psi^{s-1} w^p dtdx \\
\equiv I_1 + I_2 + I_3 \leq 0.
\]

Estimate further the integrals \( I_1, I_2, I_3 \). Since

\[
(u - v)^+_t = \begin{cases} (u - v)_t, & \text{if } u - v > 0, \\ 0, & \text{if } u - v \leq 0,
\end{cases}
\]
the following continued equality

\[ I_1 = \int_{D_T} (w \exp (t))_t \psi^s w^p \exp (-t) \, dt \, dx \]

(6)

\[ = \int_{D_T} w_t \psi^s w^p \, dt \, dx + \int_{D_T} \psi^s w^{1+p} \, dt \, dx \]

\[ = \frac{1}{1+p} \int_{D_T} (w^{1+p})_t \psi^s \, dt \, dx + \int_{D_T} \psi^s w^{1+p} \, dt \, dx \]

takes place.

It follows from the inequality \( u \leq v \) on \( D \) that

\[ \int_D \psi^s (x) w^{1+p} (\tau, x) \, dx \to 0 \quad \text{at} \quad \tau \to 0. \]

Since the integrand \( \psi^s w^{1+p} \) is not negative in \( D_T \), we have

(7) \[ I_1 \geq \int_{D_T} \psi^s w^{1+p} \, dt \, dx. \]

Next it can be easily understood that \( I_2 \geq 0 \) as

\[ \sum_{i=1}^{n} (u - v) x_i \left( \frac{u_{x_i}}{\sqrt{1 + |\nabla u|^2}} - \frac{v_{x_i}}{\sqrt{1 + |\nabla v|^2}} \right) \geq 0. \]

Then from (5)–(7) we obtain

(8) \[ \int_{D_T} \psi^s w^{1+p} \, dt \, dx \leq |I_3|. \]

We further estimate \(|I_3|\) in (8). As far as

\[ |I_3| \leq s \int_{D_T} \exp (-t) \psi^{s-1} w^p |\nabla \psi| \cdot \left( \sum_{i=1}^{n} \left( \frac{u_{x_i}}{\sqrt{1 + |\nabla u|^2}} - \frac{v_{x_i}}{\sqrt{1 + |\nabla v|^2}} \right) \right)^2 \frac{1}{2} \, dt \, dx \]

and

\[ \sum_{i=1}^{n} \left( \frac{u_{x_i}}{\sqrt{1 + |\nabla u|^2}} - \frac{v_{x_i}}{\sqrt{1 + |\nabla v|^2}} \right)^2 \leq 4, \]

then

(9) \[ |I_3| \leq 2s \int_{D_T} \exp(-t) \psi^{s-1} w^p |\nabla \psi| \, dt \, dx. \]
Now from inequalities (8) – (9) we conclude that

\[ \int_{D_T} \psi^s w^{1+p} dt \, dx \leq \int_{D_T} 2s \exp(-t) \psi^{s-1} w^p |\nabla \psi| dt \, dx. \]  

Taking \( s = 1 + p \), such that, \( (s - 1) \frac{1+p}{p} = s \), and estimating the right-hand side in (10) by using of Young's inequality

\[ AB \leq \frac{1}{2} A^\beta + 2^{\beta-1} B^\beta, \]

where \( A = (\psi w)^{s-1} \), \( B = 2s \exp(-t) |\nabla \psi| \) and \( \beta = s \), we get the following inequality

\[ \int_{D_T(R)} \psi^s w^s dt \, dx \leq \frac{1}{2} \int_{D_T(R)} \psi^s w^s dt \, dx + 2^{2s-1} s \int_{D_T(R)} |\nabla \psi|^s \exp(-st) dt \, dx. \]

Henceforth \( D_T(R) = (0, T) \times \{ D \cap \{ x : |x| < R \} \} \).

It follows directly from the previous inequality that

\[ \int_{D_T(R)} \psi^s w^s dt \, dx \leq (4s)^s \int_{D_T(R)} |\nabla \psi|^s \exp(-st) dt \, dx. \]

In order to complete the proof of the theorem we need to consider the two following cases.

If the domain \( D \) is bounded we choose \( r \) to be sufficiently large, so that, \( D_T(r) = D_T \). It follows then from the fact that \( |\nabla \psi| = 0 \) a.e. in \( D_T \) and the previous inequality that \( w = 0 \) a.e. in \( D_T \), and consequently \( u \leq v \) a.e. in \( D_T \).

If the domain \( D \) is unbounded, we take \( s \) to be sufficiently large, so that \( s > n \), and minimize the right-hand side of the obtained inequality over all admissible functions \( \psi(x) \) of the type indicated above (that is equivalent to the calculation of the \( s \)-capacity for a certain condenser (see, for example, [3])). As a result we obtain inequality

\[ \int_{D_T(R)} w^s dt \, dx \leq \frac{\sigma_n}{s} (4s)^s \left( \frac{s - n}{s - 1} \right)^{s-1} \left( 1 - \left( \frac{R}{r} \right)^{\frac{n-s}{s-1}} \right) \left( \frac{R - s}{s - 1} \right)^{1-s} R^{n-s}. \]

Here \( \sigma_n \) is the \((n - 1)\)-dimensional volume of the surface of the unit ball in \( \mathbb{R}^n \).

Now, taking \( R = 2r \) and passing to the limit as \( R \to \infty \) in (11), we get the statement of Theorem 2 immediately. ■
Proof of Theorem 1. Set
\[ \epsilon = \sup_{a' \leq r} |c_1 K(r, a) - c_1 K(r, a')| \]
for any fixed \( a' > a \). Since by the hypotheses of the theorem, it follows that
\[ (12) \quad \lim (u(t, x) - c_1 K(r, a')) \leq c + \epsilon \]
for all sequences of points \((t, x) \in D_T\), tending to the parabolic part of the boundary of the domain \( D_T \), lying on the set \([0, T) \times \{a' \leq r\}\). Now we want to establish that
\[ (13) \quad u(t, x) \leq c_1 K(r, a') + c + \epsilon \]
throughout the domain \( D'_T = [0, T) \times \{D \cap \{a' < r\}\} \). The desired result immediately follows from (13), if we turn \( a' \) to \( a \).

To prove (13) it is sufficient by the comparison principle (Theorem 2) to show that (12) holds on the parabolic part of the boundary of the domain \( D'_T \). Since it is true for all points of the parabolic part of the boundary of the domain \( D_T \), lying on the set \([0, T) \times \{a' \leq r\}\), it is sufficient to show that (13) holds for all interior points of \( D_T \), lying on the set \((0, T) \times \{r = a'\}\).

Suppose that this is not the case. Then the function \( u - c_1 K(r, a) \) takes its maximum value \( M > c + \epsilon \) at some point \((t', x') = (t', x'_1, ..., x'_n)\), lying on the set \((0, T) \times \{r = a'\}\) and which is interior to the domain \( D_T \). By the comparison principle (Theorem 2) \( u(t, x) - c_1 K(r, a') \leq M \) throughout the domain \( D'_T \).

On the other hand \( \sup |
\nabla u| \) is bounded at this point, whereas \( \frac{\partial K}{\partial r} \big|_{r = a'} = -\infty \). Since \( u(t, x) - c_1 K(r, a') = M \) at the point \((t', x')\), there must then be points of \( D'_T \) near \((t', x')\) at which \( u(t, x) - c_1 K(r, a') > M \).

Hence, our assumption that (13) does not hold leads us to the contradiction, which completes the proof of the theorem.

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