Research Article

Traveling Wavefronts of Competing Pioneer and Climax Model with Nonlocal Diffusion

Xiaojing Yu, Peixuan Weng, and Yehui Huang

School of Mathematics, South China Normal University, Guangzhou 510631, China

Correspondence should be addressed to Peixuan Weng; wengpx@scnu.edu.cn

Received 17 November 2012; Revised 11 March 2013; Accepted 21 March 2013

Academic Editor: Dumitru Baleanu

Copyright © 2013 Xiaojing Yu et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

We study a competing pioneer-climax species model with nonlocal diffusion. By constructing a pair of upper-lower solutions and using the iterative technique, we establish the existence of traveling wavefronts connecting the pioneer-existence equilibrium and the coexistence equilibrium. We also discuss the asymptotic behavior of the wave tail for the traveling wavefronts as \( s = x + ct \to -\infty \).

1. Introduction

As we know, the interactions among species are important in determining the process of evolution for the ecosystem, and the modeling accompanied with the mathematical analysis of the models can help people to understand and control the propagation of species. In general, the per capital growth rate (i.e., fitness) for a species in the model is assumed to be a function of a weighted total density of all interacting species. A well-known example is the standard Lotka-Volterra model; its fitness of a species is a linear function. It is natural to consider other kinds of fitness functions other than the linear one, because of the various species and interaction rules. In this paper, we will analyze a reaction-diffusion model describing pioneer and climax species. This model describes interaction among species with peculiar fitness functions.

A species is called a pioneer species if it thrives best at lower density but its fitness decreases monotonically with total population density for overcrowded. Thus, the fitness function of a pioneer species is assumed to be a decreasing function. Pine and yellow poplar are the species of this type. A species is called a climax species if its fitness increases up to a maximum value and then decreases of its total density. Hence, a climax population is assumed to have a nonmonotone, “one-humped” smooth fitness function. Oak and maple are the climax species.

A typical reaction-diffusion model for a pioneer-climax species is given by the following system:

\[
\begin{align*}
\frac{\partial u}{\partial t} &= d_1 \frac{\partial^2 u}{\partial x^2} + uf(c_{11}u + c_{12}v), \\
\frac{\partial v}{\partial t} &= d_2 \frac{\partial^2 v}{\partial x^2} + vg(c_{21}u + c_{22}v),
\end{align*}
\]

where \( u \) and \( v \) represent densities of the pioneer and climax species, respectively. \( f \) and \( g \) denote the pioneer fitness function and climax fitness function, respectively, \( c_{ij} > 0 \) \((i, j = 1, 2)\). By making changes of variables \( \tilde{u} = c_{21}u \), \( \tilde{v} = c_{12}v \), system (1) changes into the form (the tildes of \( \tilde{u} \) and \( \tilde{v} \) are dropped out)

\[
\begin{align*}
\frac{\partial u}{\partial t} &= d_1 \frac{\partial^2 u}{\partial x^2} + uf(c_{11}u + v), \\
\frac{\partial v}{\partial t} &= d_2 \frac{\partial^2 v}{\partial x^2} + vg(u + c_{22}v),
\end{align*}
\]

where we still use \( c_{11} \) and \( c_{22} \) as the new coefficients without confusing.

From the previous introduction, we assume that the pioneer fitness function \( f \) satisfies

\[
f'(z) < 0, \quad f(z_0) = 0\]
Abstract and Applied Analysis

Figure 1: Typical fitness functions for pioneer species and climax species.

for some \( z_0 > 0 \), and the climax fitness function \( g \) satisfies

\[
\begin{align*}
g(w_1) &= g(w_2) = 0, \quad 0 < w_1 < w_2, \\
(w^* - w)g'(w) &> 0 \quad \text{for} \ w \neq w^* \in (w_1, w_2).
\end{align*}
\]

Ricker [1] used the fitness function \( f(u) = e^{-(1-u)} - a \), Hassell and Comins [2] used the fitness function \( f(u) = \frac{r}{1 + bu} - a \), and Cushing [3] used the fitness function \( g(u) = uw^r(1-u) - a \). It is obvious that these \( f \) and \( g \) have the curves in Figure 1.

There are some existing results about the stability and traveling wave solutions for (2) ([4–6]). About traveling wave solutions, Brown et al. [4] studied the traveling wave of (1) connecting two boundary equilibria by singular perturbation technique, and Yuan and Zou [6] obtained the existence of traveling wave solutions connecting a monoculture state and a coexistence state by upper-lower solution method combined with the Schauder fixed point theorem. Also see van Vuuren [7] for the existence of traveling plane waves in a general class of competition-diffusion systems and Murray [8] for more biological description of traveling wave solutions.

For system without spatial diffusion, the model will be

\[
\begin{align*}
\frac{du}{dt} &= uf(u) + v \frac{du}{dx}, \\
\frac{dv}{dt} &= vg(u + c_2v).
\end{align*}
\]

Selgrade and Roberts [9], Sumner [10] analyzed the Hopf bifurcation of (5), and Selgrade and Namkoong [11], Sumner [12] considered the stable periodic behavior of (5). Because of the existence of rich equilibria and the various ranges of parameters, the dynamics of ordinary differential system (5) are complex, and a detailed review of all equilibrium types can be found in Buchanan [13, 14].

Although the Laplacian operator \( \Delta := \frac{\partial^2}{\partial x^2} \) is always used to model the diffusion of the species, it suggests that the population at the location \( x \) can only be influenced by the variation of the population near \( x \). As we know that the individuals can move freely, then the movement of individuals is bounded to affect the other individuals. So, the Laplacian operator may have some shortage to describe the diffusion. One way to deal with this problem is to replace the Laplacian operator with a convolution diffusion term \( \int_{-\infty}^{\infty} j(x-y)u(t,y) - u(t,x)dy \). This implies that the probability distribution function for the population at location \( y \) moving to the location \( x \) is \( f(x-y) \). At time \( t \), the total individuals that move from the whole space into the location \( x \) will be \( \int_{-\infty}^{\infty} f(x-y)|u(t,y) - u(t,x)|dy \). Therefore, one may call it as a nonlocal diffusion, and, correspondingly, call \( \partial^2 u(t,x)/\partial x^2 \) as a local diffusion. During the recent years, the models with the nonlocal diffusion have been attracted much more attentions (see [15–18]).

In this paper, instead of (2), we will concentrate on the following pioneer-climax species with nonlocal diffusion:

\[
\begin{align*}
\frac{\partial u(t,x)}{\partial t} &= d_1 \int_{-\infty}^{\infty} f(y-x) \left[ u(t,y) - u(t,x) \right] dy \\
&\quad + u(t,x) f(c_1u + v), \\
\frac{\partial v(t,x)}{\partial t} &= d_2 \int_{-\infty}^{\infty} f(y-x) \left[ v(t,y) - v(t,x) \right] dy \\
&\quad + v(t,x) g(u + c_2v),
\end{align*}
\]

where \( d_1, d_2 \) are positive constants accounting for the diffusivity, \( f(z) \) is a kernel function which is continuous on \( \mathbb{R} \) satisfying

\[
\begin{align*}
\int_{\mathbb{R}} f(x) \, dx &= 1, \\
J(x) &= f(-x) \quad \text{for} \ x \in \mathbb{R}, \quad \text{(A1)}
\end{align*}
\]

\[
\int_{\mathbb{R}} f(x) e^{vx} \, dx < \infty \quad \text{for any fixed} \ v \in [0, \infty).
\]

We are interested in traveling wavefronts accounting for a mild invasion of the two species (traveling wavefronts connecting a boundary equilibrium and the coexistence equilibrium). For system (2), the sufficient condition for (2) to have a mild invasion is \( d_2/d_1 \geq 1/2 \) (see [6]), but our condition in this paper for system (6) is \( d_2/d_1 \geq 1 \), which reveals a fact that the nonlocal diffusion of either the pioneer species or the climax species did affect the climax invasion and wave propagation. Please see Section 5 for the discussion.

The remaining of this paper is organized as follows. In Section 2, there are some preliminaries about the equilibria and the system is transformed into a cooperative one. In Section 3, we prove the existence of traveling wavefronts by using an iteration scheme combined with a pair of admissible upper and lower solutions, which can be constructed obviously, and thus a criterion of the existence for traveling wavefronts is obtained. We also give a discussion on asymptotic behavior for the traveling wavefront tail as \( s = x + ct \to -\infty \) in Section 4. At last, we give some concluding discussions in Section 5.
2. Preliminaries

It is evident that $(0, 0)$ is a trivial equilibrium of (6). The system (6) has at least four equilibria and at most six equilibria. The existence of nonnegative steady states depends on the locations of the three nullclines:

\[
 c_{11}u + v = z_0, \quad u + c_{22}v = w_1, \quad u + c_{22}v = w_2. \quad (7)
\]

The long-term behavior of solutions to (6) can be qualitatively different caused by the different number, distribution, and types of equilibria. The dynamics of the system (6) are of course very rich and complex. However, in this paper, we will only consider the following case:

\[
 z_0 > \frac{w_2}{c_{22}}, \quad w_1 < z_0 \frac{c_{11}}{c_{11}} < w_2. \quad (8)
\]

The condition $c_{11}c_{22} > 1$ follows as a sequence. Under the previous assumption, (6) has four nontrivial equilibria: $(z_0/c_{11}, 0)$, $(0, w_1/c_{22})$, $(0, w_2/c_{22})$, and $(u^*, v^*)$ except for $(0, 0)$, where

\[
 u^* = c_{22}z_0 - w_2, \quad v^* = c_{11}w_2 - z_0. \quad (9)
\]

It is obvious that $u^* < z_0 / c_{11}$. We further assume that

\[
 w^* \leq u^* \quad (10)
\]

for the technical reason. See Figure 2 for this situation.

As mentioned in the introduction, we are interested in the coexistence of the two species. That means that we will seek traveling wavefronts connecting equilibria $(z_0/c_{11}, 0)$ and equilibria $(u^*, v^*)$.

By making changes of variables $\bar{u} = z_0 / c_{11} - u$, $\bar{v} = v$ and dropping the tildes, system (6) becomes

\[
 \frac{\partial u(t, x)}{\partial t} = d_1 \int_{-\infty}^{+\infty} J(y - x) u(t, y) dy - d_1 u(t, x)
 + \left( u(t, x) - \frac{z_0}{c_{11}} \right) f (z_0 - c_{11}u + v),
\]

\[
 \frac{\partial v(t, x)}{\partial t} = d_2 \int_{-\infty}^{+\infty} J(y - x) v(t, y) dy - d_2 v(t, x)
 + v(t, x) g \left( \frac{z_0}{c_{11}} - u + c_{22}v \right),
\]

and the equilibria $(z_0/c_{11}, 0)$, $(u^*, v^*)$ are changed into $(0, 0)$, $(u^*, v^*)$, respectively, where $u^* = z_0 / c_{11} - u^*$, $v^* = v^*$.

3. Existence of Traveling Wavefronts

A traveling wavefront of (6) connecting equilibria $(z_0/c_{11}, 0)$ and $(u^*, v^*)$ can be changed into a traveling wavefront of (11) connecting $(0, 0)$ and $(u^*, v^*)$. Therefore, we consider the system (11) hereby.

A traveling wave solution of (11) is a solution with the form $u(t, x) = \phi(x + ct) = \phi(s)$ and $v(t, x) = \varphi(x + ct) = \varphi(s)$, where $s = x + ct$ and $c > 0$ is a wave speed. A traveling wavefront is a traveling wave solution $(\phi(s), \varphi(s))$ which has finite limits $(\phi(\pm \infty), \varphi(\pm \infty))$. Denoting the traveling wave coordinate $x + ct$ still by $t$, we derive the wave profile system from (11):

\[
 c\varphi'(t) = d_1 \int_{-\infty}^{+\infty} J(y - t) \phi(y) dy - d_1 \phi(t)
 + \left( \phi(t) - \frac{z_0}{c_{11}} \right) f \left( z_0 - c_{11}\phi(t) + \varphi(t) \right),
\]

\[
 c\varphi'(t) = d_2 \int_{-\infty}^{+\infty} J(y - t) \varphi(y) dy - d_2 \varphi(t)
 + \varphi(t) g \left( \frac{z_0}{c_{11}} - \phi(t) + c_{22}\varphi(t) \right).
\]

Associated with (12), we consider its solutions subject to the following boundary value conditions:

\[
 \lim_{t \to -\infty} (\phi(t), \varphi(t)) = (0, 0),
\]

\[
 \lim_{t \to +\infty} (\phi(t), \varphi(t)) = (u^*, v^*). \quad (13)
\]

For $a = (a_1, a_2)$, $b = (b_1, b_2) \in \mathbb{R}^2$, $a \leq b$ implies $a_i \leq b_i$ ($i = 1, 2$); $a < b$ implies $a \leq b$ but $a \neq b$; $a \ll b$ implies $a_i < b_i$ ($i = 1, 2$). Furthermore, the norm $\| \cdot \|$ in $\mathbb{R}^2$ is the Euclidean norm. Define

\[
 \mathbb{D} = \left\{ (\phi, \varphi) \in (C(\mathbb{R}, \mathbb{R}^2)) \mid 0 \leq \phi(t) \right. \leq u^*, 0 \leq \varphi(t) \leq v^*, t \in \mathbb{R} \right\}. \quad (14)
\]

For some constants $\beta_1, \beta_2$, letting $b_1 = \beta_1 - d_1, b_2 = \beta_2 - d_2$, we define an operator $H = (H_1, H_2) : \mathbb{D} \to C(\mathbb{R}, \mathbb{R}^2)$ by

\[
 H_1(\phi, \varphi)(t) = d_1 \int_{-\infty}^{+\infty} J(y - t) \phi(y) dy
 + \left( \phi(t) - \frac{z_0}{c_{11}} \right) f \left( z_0 - c_{11}\phi(t) + \varphi(t) \right) + \beta_1 \phi(t),
\]

\[
 H_2(\phi, \varphi)(t) = d_2 \int_{-\infty}^{+\infty} J(y - t) \varphi(y) dy
 + \varphi(t) g \left( \frac{z_0}{c_{11}} - \phi(t) + c_{22}\varphi(t) \right) + \beta_2 \varphi(t).
\]
$$H_2 (\phi, \varphi) (t)$$

$$= d_2 \int_{-\infty}^{+\infty} f (y - t) \varphi (y) \, dy$$

$$+ \varphi (t) g \left( \frac{z_0}{c_{11}} - \phi (t) + c_{22} \varphi (t) \right) + b_2 \varphi (t).$$

(15)

Then, (12) can be written as an equivalent form:

\begin{align}
&c \phi' (t) = -\beta_1 \phi (t) + H_1 (\phi, \varphi) (t), \\
&c \varphi' (t) = -\beta_2 \varphi (t) + H_2 (\phi, \varphi) (t).
\end{align}

(16)

Denote $Q = (Q_1, Q_2)$ by

$$Q_1 (\phi, \varphi) (t) = \frac{1}{c} e^{-\left( \beta_1 / c \right) t} \int_{-\infty}^{t} e^{\left( \beta_1 / c \right) s} H_1 (\phi, \varphi) (s) \, ds,$$

$$Q_2 (\phi, \varphi) (t) = \frac{1}{c} e^{-\left( \beta_2 / c \right) t} \int_{-\infty}^{t} e^{\left( \beta_2 / c \right) s} H_2 (\phi, \varphi) (s) \, ds.$$

(17)

It is obvious that a traveling wave solution of the problem (12) and (13) is a fixed point of $Q$ and vice versa.

The following lemma states the monotone property of $H$.

**Lemma 1.** Assume that (A1) holds, for sufficiently large $\beta_1, \beta_2 > 0$ and $(\phi, \varphi) \in \mathbb{D}$, $i = 1, 2$ with $\phi_1 (s) \leq \phi_2 (s)$ and $\varphi_1 (s) \leq \varphi_2 (s)$, $s \in \mathbb{R}$; one has

(i) $H_1 (\phi_2, \varphi_1) (t) \geq H_1 (\phi_1, \varphi_1) (t)$,

$H_2 (\phi_2, \varphi_2) (t) \geq H_2 (\phi_1, \varphi_1) (t)$,

(ii) $H_1 (\phi_1, \varphi_2) (t) \geq H_1 (\phi_1, \varphi_1) (t)$,

$H_2 (\phi_2, \varphi_1) (t) \geq H_2 (\phi_1, \varphi_1) (t)$

for all $t \in \mathbb{R}$.

**Proof.** In order to prove (i), let $f_1 (x, y) = (x - z_0 / c_{11}) f (z_0 - c_{11} x + y) + b_1 x, g_1 (x, y) = yg (z_0 / c_{11} - x + c_{22} y) + b_2 y.$ Then

$$\frac{\partial f_1}{\partial x} = f_1 \left( \frac{z_0}{c_{11}} - c_{11} x + y \right)$$

$$+ (z_0 - c_{11} x) f'_1 \left( \frac{z_0}{c_{11}} - c_{11} x + y \right) + \beta_1 - d_1,$$

$$\frac{\partial g_1}{\partial y} = g_1 \left( \frac{z_0}{c_{11}} - x + c_{22} y \right)$$

$$+ c_{22} y g'_1 \left( \frac{z_0}{c_{11}} - x + c_{22} y \right) + \beta_2 - d_2.$$  

(18)

For $0 \leq x < u^*, 0 \leq y < v^*$ and sufficiently large $\beta_1, \beta_2 > 0$, it follows that $\partial f_1 / \partial x \geq 0, \partial g_1 / \partial y \geq 0.$ Thus, if $\phi_1 (s) \leq \phi_2 (s)$ and $\varphi_1 (s) \leq \varphi_2 (s)$ for $s \in \mathbb{R}$, we have

$$H_1 (\phi_2, \varphi_1) (t) - H_1 (\phi_1, \varphi_1) (t)$$

$$= d_1 \int_{-\infty}^{t} f (y - t) \left[ \phi_2 (y) - \phi_1 (y) \right] \, dy$$

$$+ f_1 (\phi_2, \varphi_1) - f_1 (\phi_1, \varphi_1) \geq 0,$$

$$H_2 (\phi_1, \varphi_2) (t) - H_2 (\phi_1, \varphi_1) (t)$$

$$= d_2 \int_{-\infty}^{t} f (y - t) \left[ \varphi_2 (y) - \varphi_1 (y) \right] \, dy$$

$$+ g_1 (\phi_1, \varphi_2) - g_1 (\phi_1, \varphi_1) \geq 0.$$  

(19)

For (ii), we know that $0 \leq \phi_1 (t) \leq u^* = z_0 / c_{11} - u^* \leq z_0 / c_{11}$ and $f' (y) < 0$ for $y \in \mathbb{R}$. It follows that

$$H_1 (\phi_1, \varphi_2) (t) - H_1 (\phi_1, \varphi_1) (t)$$

$$= \left( \phi_1 (t) - \frac{z_0}{c_{11}} \right) \left[ f (z_0 - c_{11} \phi_1 (t) + \varphi_2 (t)) \right.$$

$$- f (z_0 - c_{11} \phi_1 (t) + \varphi_1 (t)) \bigg] \geq 0.$$  

(20)

From $0 \leq \varphi_1 (t) \leq v^* = v^*$, $0 \leq \phi_1 (t) \leq \phi_2 (t) \leq u^* = z_0 / c_{11} - u^*$, we have

$$w^* \leq u^* = \frac{z_0}{c_{11}} - \left( \frac{z_0}{c_{11}} - u^* \right) \leq \frac{z_0}{c_{11}} - \phi_2 (t) + c_{22} \varphi_1 (t)$$

$$\leq \frac{z_0}{c_{11}} - \phi_1 (t) + c_{22} \varphi_1 (t).$$  

(21)

Note that $g'(w) < 0$ for $w > w^*$. This leads to

$$H_2 (\phi_2, \varphi_1) (t) - H_2 (\phi_1, \varphi_1) (t)$$

$$= \varphi_1 (t) \left[ g \left( \frac{z_0}{c_{11}} - \phi_2 (t) + c_{22} \varphi_1 (t) \right) \right.$$

$$- g \left( \frac{z_0}{c_{11}} - \phi_1 (t) + c_{22} \varphi_1 (t) \right) \bigg] \geq 0.$$  

(22)

The proof is complete.

The conclusion of the following lemma is direct.

**Lemma 2.** Assume that $\beta_1 > 0, \beta_2 > 0$ are sufficiently large. For $(\phi, \varphi) \in \mathbb{D}$ with $\varphi(t), \varphi(t)$ nondecreasing on $t \in \mathbb{R}$, $H_1 (\phi, \varphi) (t), H_2 (\phi, \varphi) (t)$ are also nondecreasing on $t \in \mathbb{R}$.

We can easily see that $Q = (Q_1, Q_2)$ also enjoys the same properties as those for $H = (H_1, H_2)$ settled in Lemmas 1 and 2.

Let $\mu \in (0, \min \{ \beta_1 / c, \beta_2 / c \})$

$$B_\mu (\mathbb{R}, \mathbb{R}^2) = \left\{ \phi \in C (\mathbb{R}, \mathbb{R}^2) \left| \sup_{t \in \mathbb{R}} |\phi (t)| e^{-\mu |t|} < \infty \right. \right\}.$$  

(23)

It is clear that $(B_\mu (\mathbb{R}, \mathbb{R}^2), \cdot \cdot_\mu)$ is a Banach space equipped with the norm $\cdot \cdot_\mu$ defined by $|\phi|_\mu = \sup_{t \in \mathbb{R}} |\phi (t)| e^{-\mu |t|}$.

**Definition 3.** A pair of continuous functions $(\bar{\phi}(t), \bar{\varphi}(t))$, $\Phi(t) = (\phi(t), \varphi(t))$ is called an upper solution and...
a lower solution of (12), respectively, if there exists a set \( \Gamma \subset [T_i, T_{i+1}) \) such that \( \Phi \) and \( \Phi' \) are differentiable in \( \mathbb{R} \setminus \Gamma \) and the essential bounded functions \( \Phi', \Phi'' \) satisfy

\[
\begin{align*}
&d_1 \int_{-\infty}^{+\infty} J(y-t) \Phi'(y) dy - d_1 \Phi'(t) \\
&\quad + \left( \Phi(t) - \frac{z_0}{c_{11}} \right) f \left( z_0 - c_{11} \Phi(t) + \Phi(t) \right) \leq 0, \\
&d_2 \int_{-\infty}^{+\infty} J(y-t) \Phi(y) dy - d_2 \Phi(t) - c \Phi'(t) \\
&\quad + \Phi(t) g \left( \frac{z_0}{c_{11}} - \Phi(t) + c_2 \Phi(t) \right) \leq 0,
\end{align*}
\]

(24)

for \( t \in \mathbb{R} \setminus \Gamma \).

In what follows, we assume that (12) has an upper solution \((\Phi(t), \Phi'(t))\) and a lower solution \((\phi(t), \phi'(t))\), such that

\[
\begin{align*}
(\text{P1}) \quad & (0,0) \prec (\phi(t), \phi(t)) \leq (\Phi(t), \Phi(t)) \leq (u', v') \quad \text{for } t \in \mathbb{R} \setminus \Gamma, \\
(\text{P2}) \quad & \lim_{t \to -\infty} (\Phi(t), \Phi(t)) = (0,0), \quad \lim_{t \to +\infty} (\Phi(t), \Phi(t)) = (u', v'); \\
(\text{P3}) \quad & \Phi(t) \text{ and } \Phi(t) \text{ are nondecreasing.}
\end{align*}
\]

Define the following profile set \( \Lambda = \Lambda(\Phi, \Phi') \) by

\[
\Lambda(\Phi, \Phi') = \{ (\phi, \phi) \in D \mid (i) \phi(t) \leq \phi(t) \leq \Phi(t), \\
\quad \phi(t) \leq \phi(t) \leq \Phi(t), \\
\quad (\phi(t), \phi(t)) \text{ are nondecreasing for } t \in \mathbb{R} \}.
\]

(25)

It is obvious that \( \Lambda(\Phi, \Phi') \) is nonempty.

For \( t \in \mathbb{R} \) and \( n \geq 2 \), define \((\varphi, \varphi')(t) = (\phi, \phi)(t)\) and

\[
\begin{align*}
\varphi_n(t) &= Q_1 \left( \left( \Phi_{n-1}, \Phi_{n-1} \right) \right)(t), \\
\varphi_n(t) &= Q_2 \left( \left( \Phi_{n-1}, \Phi_{n-1} \right) \right)(t), \\
\phi_n(t) &= Q_1 \left( \left( \phi_{n-1}, \phi_{n-1} \right) \right)(t), \\
\phi_n(t) &= Q_2 \left( \left( \phi_{n-1}, \phi_{n-1} \right) \right)(t).
\end{align*}
\]

(26)

Lemma 4. For \( n \geq 2 \), the functions \( \varphi_n(t), \varphi_n(t) \) and \( \phi_n(t), \phi_n(t) \) defined by (26) satisfy

\[
\begin{align*}
(i) \quad & (\varphi_n(t), \varphi_n(t)) \in \Lambda; \\
(ii) \quad & (\Phi_{n-1}(t), \Phi_{n-1}(t)) \leq (\varphi_n(t), \varphi_n(t)) \leq (\Phi_n(t), \Phi_n(t)) \leq (\Phi_{n+1}(t), \Phi_{n+1}(t)) \quad \text{for } t \in \mathbb{R}; \\
(iii) \quad & (\phi_n(t), \phi_n(t)) \text{ and } (\phi(t), \phi(t)) \text{ is a pair of upper and lower solutions of (12)}; \\
(iv) \quad & (\Phi_n(t), \Phi_n(t)) \text{ and } (\Phi(t), \Phi(t)) \text{ are continuously differentiable on } t \in \mathbb{R}.
\end{align*}
\]

Proof. We only give the argument for \( n = 2 \), and the situation for \( n \geq 3 \) can be obtained by mathematical induction. From Definition 3, we obtain

\[
H_1(\Phi_n, \Psi_n)(t) \leq c \Phi_n(t) + \beta \Phi_n(t) \quad \text{for } t \in \mathbb{R} \setminus \Gamma. \quad (27)
\]

Let \( T_0 = -\infty, T_{k+1} = +\infty \). For any \( t \in \mathbb{R} \), there exists some \( i \) such that \( t \in (T_{i-1}, T_i) \) for \( i = 1, 2, \ldots, k \) or \( t \in (T_k, \infty) \). We then derive

\[
\begin{align*}
\Phi_2(t) &= Q_1 \left( \Phi_1, \Phi_1 \right)(t) = \frac{1}{c} \int_{-\infty}^{t} e^{-\beta_1(t-s)} H_1(\Phi_1, \Phi_1)(s) ds \\
&\leq \frac{1}{c} \left[ \sum_{i=1}^{k} \left( \int_{T_{i-1}}^{T_i} + \int_{T_i}^{t} \right) e^{-\beta_1(t-s)} \right] \left( c \Phi_1(s) + \beta \Phi_1(s) \right) ds = \Phi_1(t),
\end{align*}
\]

(28)

where \( i = 1, 2, \ldots, k + 1 \). By similar arguments, we get

\[
\begin{align*}
\left( \Phi_1(t), \Phi_1(t) \right) \leq \left( \Phi_2(t), \Phi_2(t) \right) \leq \left( \Phi_3(t), \Phi_3(t) \right) \leq \left( \Phi_4(t), \Phi_4(t) \right) \\
\leq \left( \Phi(t), \Phi(t) \right) \quad \text{for } t \in \mathbb{R}.
\end{align*}
\]

(29)

The previous arguments implies that the conclusion (ii) holds.

From the monotone property of \( Q \), we can easily obtain that \( \varphi_n(t), \varphi_n(t) \) are nondecreasing for \( t \in \mathbb{R} \), and therefore the conclusion (i) holds.
In a similar way, we can prove that convergence is uniform with respect to the decay norm.

Lemma 5. \( \lim_{n \to \infty} (\overline{\phi}_n(t), \overline{\varphi}_n(t)) = (\phi^*(t), \varphi^*(t)) \in \Lambda, \) and the convergence is uniform with respect to the decay norm \(|\cdot|_\mu\).

Proof. We have from Lemma 4 that the following limit exists:

\[
\lim_{n \to \infty} (\overline{\phi}_n(t), \overline{\varphi}_n(t)) = (\phi^*(t), \varphi^*(t)).
\]

It is easy to know that \( \Lambda \) is a closed and convex set.

By the nondecreasing property of \((\overline{\phi}_n(t), \overline{\varphi}_n(t))\), we have \((\phi^*(t), \varphi^*(t)) \in \Lambda. \) In the following, we prove that the convergence is uniform with respect to the decay norm.

Since

\[
| (\overline{\phi}_n(t), \overline{\varphi}_n(t)) - (\phi^*(t), \varphi^*(t)) | \leq 2 (u^+ + v^+) \quad \text{for } n \geq 1,
\]

for any \( \epsilon > 0 \), there exists a \( T = T(\epsilon) > 0 \), such that for all \( n \geq 1 \),

\[
\sup_{t \in [T, \infty]} \left| (\overline{\phi}_n(t), \overline{\varphi}_n(t)) - (\phi^*(t), \varphi^*(t)) \right| e^{-\mu |t|} < \epsilon.
\]

Now, we consider the sequences \((\overline{\phi}_n, \overline{\varphi}_n)_{n=1}^{\infty}\) for \( t \in [-T, T] \).

Note \( \overline{\phi}_n(t) \) is nondecreasing on \( t \), and thus

\[
0 \leq \overline{\phi}_n(t) = Q_1^f (\overline{\phi}_{n-1}, \overline{\varphi}_{n-1}) (t) \leq \frac{1}{c} H_1 (\overline{\phi}_{n-1}, \overline{\varphi}_{n-1}) (t) - \frac{\beta_1}{c} e^{-(\beta_1/c)t} \times \int_{-\infty}^t e^{(\beta_1/c)s} H_1 (\overline{\phi}_{n-1}, \overline{\varphi}_{n-1}) (s) \, ds
\]

\[
\leq \frac{1}{c} H_1 (\overline{\phi}_{n-1}, \overline{\varphi}_{n-1}) (t) \leq \frac{1}{c} H_1 (\overline{\phi}_1, \overline{\varphi}_1) (t).
\]

By \((\overline{\phi}_1(t), \overline{\varphi}_1(t)) \in D, \) there exists a positive constant \( M_1 \), such that \( |\overline{\phi}_n(t)| \leq M_1 \) for \( t \in [-T, T] \). Similarly, we can prove that there exists a positive number \( M_2 \), such that \( |\overline{\varphi}_n(t)| \leq M_2 \) for \( t \in [-T, T] \).

From the previous estimates, we know that \( (\overline{\phi}_n(t), \overline{\varphi}_n(t))_{n=1}^{\infty} \) is equicontinuous on \([-T, T]\) with respect to the supremum norm. On the other hand, we have from Lemma 4 (ii) that \( (\overline{\phi}_n(t), \overline{\varphi}_n(t))_{n=1}^{\infty} \) is uniformly bounded. By Arzela-Ascoli theorem, there exist subsequences of \((\overline{\phi}_n(t), \overline{\varphi}_n(t))_{n=1}^{\infty}\) which are uniformly convergent in \( t \in [-T, T] \). Without loss of generality, we still express this subsequence as \((\overline{\phi}_n(t), \overline{\varphi}_n(t))_{n=1}^{\infty}\). Thus, there exists a positive integer \( N^* > 2 \), such that

\[
\sup_{t \in [-T, T]} \left| (\overline{\phi}_n(t), \overline{\varphi}_n(t)) - (\phi^*(t), \varphi^*(t)) \right| < \epsilon \quad \text{for } n > N^*.
\]

Furthermore, we have

\[
\sup_{t \in [-T, T]} \left| (\overline{\varphi}_n(t) - \phi^*(t)) \right| e^{-\mu |t|} < \epsilon \quad \text{for } n > N^*.
\]

Summarizing the previous arguments, for \( n > N^* \) we have

\[
\sup_{t \in \mathbb{R}} \left| (\overline{\phi}_n(t), \overline{\varphi}_n(t)) - (\phi^*(t), \varphi^*(t)) \right| e^{-\mu |t|} < \epsilon.
\]

The proof is complete.

Theorem 6. Assume that (A1) holds; if (12) has a pair of upper and lower solutions that satisfy (P1)–(P3), then the system (11) has a traveling wavefront satisfying (13).

Proof. By the Lebesgue’s dominated convergence theorem and the iteration scheme (26), we have

\[
(\phi^*(t), \varphi^*(t)) = (Q_1 (\phi^*(t), \varphi^*(t)), Q_2 (\phi^*(t), \varphi^*(t))).
\]

Therefore, \((\phi^*(t), \varphi^*(t))\) is a fixed point of \( Q \), which also satisfies (12). Furthermore, (P2) indicates that \((\phi^*(t), \varphi^*(t))\) satisfy \( \lim_{n \to -\infty} (\phi^*(t), \varphi^*(t)) = (0, 0) \). On the other hand, we have from the monotonicity of \((\phi^*(t), \varphi^*(t))\) that \( \lim_{n \to -\infty} (\phi^*(t), \varphi^*(t)) = (\overline{u}, \overline{v}) \) exists. Furthermore, since \((0, 0) \ll (\phi^*(t), \varphi^*(t)) \leq (\phi^*(t), \varphi^*(t)) \), we know that \((\overline{u}, \overline{v}) \gg (0, 0) \). By using L’Hospital’s rule, we obtain

\[
\overline{u} = \lim_{t \to -\infty} \varphi^*(t) = \lim_{t \to -\infty} Q_1 (\phi^*(t), \varphi^*(t)) = \lim_{t \to -\infty} \frac{(1/c) \int_{\overline{\phi}} e^{(\beta_1/c)s} H_1 (\phi^*(s), \varphi^*(s)) \, ds}{e^{(\beta_1/c)s}} \frac{1}{\beta_1} H_1 (\overline{u}, \overline{v}).
\]
Similarly, one can obtain $\bar{v} = (1/\beta_2)H_2(\bar{u}, \bar{v})$. That is, $(\bar{u}, \bar{v})$ is an equilibrium of (12). Note that the assumption (10) implies that there is only one positive equilibrium $(u^*, v^*)$ of (12) satisfying $(0, 0) < (u, v) \leq (u^*, v^*)$. Therefore, $(\bar{u}, \bar{v}) = (u^*, v^*)$ and $(\phi^*(t), \phi^*(t))$ is a traveling wavefront satisfying (13). The proof is complete.

In order to construct a pair of admissible upper-lower solutions for (12), we linearize (12) at $(0, 0)$ and obtain

$$d_1 \int_{-\infty}^{+\infty} f'(y) \phi(y) dy - d_1 \phi'(t) - c \phi'(t) = 0,$$

$$d_2 \int_{-\infty}^{+\infty} f'(y) \phi(y) dy - d_2 \phi'(t) - c \phi'(t) + \phi(t) g\left(\frac{z_0}{\epsilon_{11}}\right) = 0. \quad (41)$$

Thus, we consider the following characteristic equation:

$$F(\lambda, c) := d_2 \int_{-\infty}^{+\infty} f'(y) \phi(y) dy - d_2 c + g\left(\frac{z_0}{\epsilon_{11}}\right) = 0.$$ \quad (42)

Note that

$$F(\lambda, 0) > 0 \quad \text{for any } \lambda > 0,$$

(by (A1) and $e^x + e^{-y} \geq 2$),

$$F(\lambda, +\infty) = -\infty \quad \text{for any } \lambda > 0,$$

$$F(0, c) = g\left(\frac{z_0}{\epsilon_{11}}\right) > 0,$$

$$\frac{\partial F(\lambda, c)}{\partial \lambda} = d_2 \int_{-\infty}^{+\infty} y f'(y) \phi(y) dy - c > 0,$$

$$\frac{\partial^2 F(\lambda, c)}{\partial \lambda^2} = d_2 \int_{-\infty}^{+\infty} y^2 f'(y) \phi(y) dy > 0 \quad \text{for any } \lambda \in \mathbb{R},$$

$$\frac{\partial F(\lambda, c)}{\partial c} = -\lambda < 0 \quad \text{for any } \lambda > 0. \quad (43)$$

The convex property of $F$ leads to $F(+\infty, c) = +\infty$ for any $c > 0$. In view of the previous observation, we have the following lemma directly.

**Lemma 7.** The following conclusions are true.

(i) There exists a $(\lambda^*, c^*)$, $\lambda^* > 0$, $c^* > 0$ such that $F(\lambda^*, c^*) = 0$, $\frac{\partial F(\lambda, c)}{\partial \lambda}\bigg|_{(\lambda^*, c^*)} = 0$. \quad (44)

(ii) For $0 < c < c^*$, $F(\lambda, c) > 0$ for $\lambda \in \mathbb{R}$.

(iii) For $c > c^*$, the equation $F(\lambda, c) = 0$ has two zeros $0 < \lambda_1 < \lambda_2$ such that $F(\lambda, c) < 0$ for $\lambda_1 < \lambda < \lambda_2$. \quad (45)

Now we are ready to construct the upper solution of (12).

**Lemma 8.** Define

$$\bar{v}(t) = \min \{e^{\lambda_1 t}, u^+\}, \quad \bar{v}(t) = \min \{c_{11} e^{\lambda_1 t}, v^+\}. \quad (46)$$

Then for $d_2 \geq d_1$, $(\bar{v}(t), \bar{v}(t))$ is an upper solution of (12).

Proof. Let $t_1, t_2$ be such that $e^{\lambda_1 t_1} = u^+$, $c_{11} e^{\lambda_1 t_2} = v^+$.

Notice that $v^+ = c_{11} u^+$, we have $t_0 := t_1 = t_2 = (1/\lambda_1) \ln (v^*/c_{11})$.

If $t < t_0$, $\bar{v}(t) = e^{\lambda_1 t}$, $\bar{v}(t) = c_{11} e^{\lambda_1 t}$, we have from the fact $\bar{v}(t) \leq e^{\lambda_1 t}$ for $t \in \mathbb{R}$ and $u_0 < w^* \leq u^* < z_0/c_{11} < w_2$ that

$$d_1 \int_{-\infty}^{+\infty} f'(y) \phi(y) dy - d_1 \phi'(t) - c \phi'(t) + \phi(t) g\left(\frac{z_0}{\epsilon_{11}}\right) = 0,$$

$$d_1 \int_{-\infty}^{+\infty} f'(y) \phi(y) dy - d_1 \phi'(t) - c \phi'(t) + \phi(t) g\left(\frac{z_0}{\epsilon_{11}}\right) = 0.$$
Let \( m := \min_{u \in [c_1/c_3, c_2/c_3, c_2/v_1]} g'(u) < 0 \). By the fact that
\[
\lambda_t c_1 c_2 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) \geq 0 \quad \text{for } t < t_3, \tag{58}
\]
we have
\[
\begin{align*}
g\left( \frac{z_0}{c_1} + c_1 c_2 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) \right) \\
= \left[ g \left( \frac{z_0}{c_1} + c_1 c_2 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) \right) - g \left( \frac{z_0}{c_1} \right) \right] + g \left( \frac{z_0}{c_1} \right) \\
\geq m c_1 c_2 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) + g \left( \frac{z_0}{c_1} \right) . \tag{59}
\end{align*}
\]
Note that (58) leads to \( e^{\lambda_t u} - q e^{\eta \lambda_t i} > 0 \) for \( t < t_3 \); it follows that
\[
(e^{\lambda_t u} - q e^{\eta \lambda_t i})^2 \leq e^{2 \lambda_t u} , \tag{60}
\]
and thus
\[
\begin{align*}
\left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) g\left( \frac{z_0}{c_1} + c_1 c_2 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) \right) \\
\geq \frac{z_0}{c_1} e^{\lambda_t u} + m c_1 c_2 e^{2 \lambda_t u} - g \left( \frac{z_0}{c_1} \right) q e^{\eta \lambda_t i} . \tag{61}
\end{align*}
\]
Therefore,
\[
\begin{align*}
d_2 \int_{-\infty}^{\infty} f(y) e^{\eta \lambda_t i} dy - d_2 c_1 + g \left( \frac{z_0}{c_1} \right) - g \left( \frac{z_0}{c_1} \right) e^{\lambda_t u} \\
x + g \left( \frac{z_0}{c_1} - \phi (t) + c_2 \phi (t) \right) \\
\geq c_1 d_2 \int_{-\infty}^{\infty} f(y) \left[ e^{\lambda_t u} - q e^{\eta \lambda_t u} \right] dy - d_2 c_1 \\
x + (e^{\lambda_t u} - q e^{\eta \lambda_t i}) \left( \frac{z_0}{c_1} + c_1 c_2 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) \right) \\
\geq c_1 e^{\lambda_t u} \left[ d_2 \int_{-\infty}^{\infty} f(y) e^{\eta \lambda_t u} dy - d_2 c_1 + g \left( \frac{z_0}{c_1} \right) \right] \\
\geq -c_1 e^{\lambda_t u} \left[ d_2 \int_{-\infty}^{\infty} f(y) e^{\eta \lambda_t u} dy - d_2 c_1 + g \left( \frac{z_0}{c_1} \right) \right] - m c_1 c_2 e^{2 \eta \lambda_t i} . \tag{62}
\end{align*}
\]

### Lemma 9
Define
\[
\begin{align*}
\phi_* (t) = 0 , & \quad \quad \phi_+ (t) = \max \left\{ c_1 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right), 0 \right\} , \tag{53}
\end{align*}
\]
where \( q > 1 \) is a constant to be chosen later. Then \((\phi_*, \phi_+)\) is a lower solution of (12). Furthermore,
\[
\left( \phi_0 (t), \phi_0 (t) : = \left( Q_1 \left( \phi_0 (t), \phi_0 (t) \right), Q_2 \left( \phi_0 (t), \phi_0 (t) \right) \right) \right) \tag{54}
\]
is a lower solution of (12) satisfying
\[
\left( \phi_0 (t), \phi_0 (t) \right) \geq (0, 0) \quad \text{for } t \in \mathbb{R} . \tag{55}
\]

Proof. Let \( t_3 \) be such that \( c_1 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) = 0 \), it follows that
\[
t_3 = \frac{1}{\eta - 1} \frac{1}{\lambda_1} \ln \frac{1}{q} < 0 . \tag{56}
\]
If \( t < t_3 < 0 , \phi_* (t) = 0 , \phi_+ (t) = c_1 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) \), and \( \phi_0 (t) \geq c_1 \left( e^{\lambda_t u} - q e^{\eta \lambda_t i} \right) \) for \( t \in \mathbb{R} , \) we have
\[
\begin{align*}
d_1 \int_{-\infty}^{t} f(y) \phi_0 (y) dy - d_1 \phi_0 (t) - c_1 \phi_0 (t) \\
+ \phi_0 (t) + \frac{z_0}{c_1} f \left( \frac{z_0}{c_1} - c_1 \phi_0 (t) + \phi_0 (t) \right) \tag{57}
\end{align*}
\]
\[
= \frac{z_0}{c_1} f \left( \frac{z_0}{c_1} + \phi_0 (t) \right) \geq - \frac{z_0}{c_1} f \left( \frac{z_0}{c_1} \right) = 0 .
\]
Let \( q > 1 \) sufficiently large; we can have
\[
q \left[ d_2 \int_{-\infty}^{t'} f(y) e^{\beta_1 y} dy - d_2 - c\eta \lambda_1 \right] + g \left( \frac{c_1 \eta_1}{c_{12}} \right) = m c_{11} c_{22} < 0,
\]
(hence,
\[
d_2 \int_{-\infty}^{t'} f(y - t) \phi_1(y) dy - d_2 \phi_1(t) - c \phi_{1}'(t)
+ \phi_1(t) g \left( \frac{c_1 \eta_1}{c_{12}} \right) \right) \geq 0.
\]
If \( t > t_3, \phi_1(t) = 0, \phi_2(t) = 0 \), and \( \phi_1(t) \geq 0 \) for \( t \in \mathbb{R} \), we have
\[
d_1 \int_{-\infty}^{t'} f(y - t) \phi_1(y) dy - d_1 \phi_1(t) - c \phi_{1}'(t)
+ \left( \phi_1(t) - \frac{c_1 \eta_1}{c_{12}} \right) f \left( z_0 - c_{11} \phi_1(t) + \phi_1(t) \right) = 0.
\]

From the previous arguments, we obtain that \((\phi_1(t), \phi_2(t))\) is a lower solution of (12). By Lemma 4, we can get that \((\phi_1(t), \phi_2(t))\) is also a lower solution. Furthermore, for \( t < t_3, \phi_2(t) > 0 \), by direct calculation, we have \( H_1(\phi_1, \phi_2)(t) > 0 \) for \( t < t_3 \). Therefore, \( \phi_1(t) = Q_2(\phi_1, \phi_2)(t) > 0 \) for \( t \in \mathbb{R} \). Similarly, we have \( \phi_2(t) > 0 \) for \( t \in \mathbb{R} \). The proof is complete. \( \square \)

**Theorem 10.** Assume that (A) and \( d_2 \geq d_1 \) hold. Then for any \( c \geq c^* \), the system (11) has a traveling wavefront with speed \( c \), which connects \((0, 0)\) and \((u^*, v^*)\).

**Proof.** The conclusion for \( c > c^* \) can be obtained from the previous discussions. We only need to establish the existence of wave fronts when \( c = c^* \).

Let \( c_k < (c^*, c^* + 1) \) with \( \lim_{k \to \infty} c_k = c^* \). For \( c_k > c^* \), (12) with \( c = c_k \) admits a nondecreasing solution \((\phi_k(t), \phi_k(t))\) such that
\[
\lim_{t \to -\infty} (\phi_k(t), \phi_k(t)) = (0, 0),
\]
\[
\lim_{t \to +\infty} (\phi_k(t), \phi_k(t)) = (u^*, v^*).
\]

Without loss of generality, we assume that \((\phi_k(0), \phi_k(0)) = (u^*/2, v^*/2)\). Obviously, \(|\phi_k(t)| \leq u^*, \phi_k(t)| \leq v^*\), and \( \phi_k(t), \phi_k(t) \) satisfy
\[
\phi_k(t) = \frac{1}{c_k} e^{-(\beta_1/c_k)} \int_{-\infty}^{t} e^{(\beta_1/c_k)s} H_1(\phi_k, \phi_k)(s) ds,
\]
\[
\phi_k(t) = \frac{1}{c_k} e^{-(\beta_1/c_k)} \int_{-\infty}^{t} e^{(\beta_1/c_k)s} H_2(\phi_k, \phi_k)(s) ds.
\]

As the same argument in Lemma 5, we can obtain that \((\phi_k(t), \phi_k(t))\) is uniformly bounded and equicontinuous on \( \mathbb{R} \); using Arzéla-Ascoli theorem and the standard diagonal method, we can obtain a subsequence of \((\phi_k(t), \phi_k(t))\), still denoted by \((\phi_k(t), \phi_k(t))\), such that \((\phi_k(t), \phi_k(t)) \to (\phi^*(t), \phi^*(t))\) uniformly for \( t \) in any bounded subset of \( \mathbb{R} \), as \( k \to \infty \). Clearly, \((\phi^*(t), \phi^*(t))\) is nondecreasing and \((\phi^*(0), \phi^*(0)) = (u^*/2, v^*/2)\).

By the dominated convergence theorem and (67), it follows that
\[
\phi^*(t) = \frac{1}{c^* e^{-(\beta_1/c^*) t}} \int_{-\infty}^{t} e^{(\beta_1/c^*)s} H_1(\phi^*, \phi^*)(s) ds,
\]
\[
\phi^*(t) = \frac{1}{c^* e^{-(\beta_1/c^*) t}} \int_{-\infty}^{t} e^{(\beta_1/c^*)s} H_2(\phi^*, \phi^*)(s) ds.
\]

Since \( \lim_{t \to +\infty} \phi^*(t) \) and \( \lim_{t \to -\infty} \phi^*(t) \) exist, using L'Hospital rule leads to
\[
\lim_{t \to -\infty} (\phi^*(t), \phi^*(t)) = (0, 0),
\[
\lim_{t \to +\infty} (\phi^*(t), \phi^*(t)) = (u^*, v^*).
\]

Thus, \((\phi^*(t), \phi^*(t))\) is a traveling wavefront of the system (11) connecting \((0, 0)\) and \((u^*, v^*)\). \( \square \)

**Remark 11.** We say that the \( c^* \) is the minimal wave speed in the sense that (11) has no traveling wavefront with \( c \in (0, c^*) \). We could briefly explain this in the following. In fact, the linearization of (12) at zero solution is (41), and the function \( F(\lambda, c) \) is obtained by substituting \( e^{\lambda t} \) in the second equation of (41). For \( 0 < c < c^* \), we know from (ii) of Lemma 7 that \( F(\lambda, c) > 0 \) for any \( \lambda \in \mathbb{R} \). We have from the second equation of (12) and the second equation of (41) that (12) cannot have a solution \((\phi(t), \psi(t))\) that satisfies \( \lim_{t \to -\infty} (\phi(t), \psi(t)) = (0, 0) \).

**Theorem 12.** Assume that (A) and \( d_2 \geq d_1 \) hold. Then for any \( c \geq c^* \), the system (6) has a traveling wavefront with speed \( c \), which connects \((z_0/c_{11}, 0)\) and \((u^*, v^*)\).

### 4. Asymptotic Behavior for Traveling Wavefronts

In this section, we discuss the asymptotic behavior for the traveling wavefronts obtained in the previous section as \( t \to -\infty \).

**Theorem 13.** Let \((\phi(t), \psi(t))\) be a traveling wavefront of (11) decided by Theorem 10; then
\[
\lim_{t \to -\infty} \left( \phi(t) e^{-\lambda_1 t}, \psi(t) e^{-\lambda_1 t} \right)
= \left( \frac{d_2 z_0 f'(z_0)}{c \lambda_1 (d_1 - d_2 - d_1 g(z_0/c_{11}) + d_2 z_0 f'(z_0/c_{11})\lambda_1),} \right),
\]
\[
\lim_{t \to -\infty} \left( \phi'(t) e^{-\lambda_1 t}, \psi'(t) e^{-\lambda_1 t} \right)
= \left( \frac{\lambda_1 d_2 z_0 f'(z_0)}{c \lambda_1 (d_1 - d_2 - d_1 g(z_0/c_{11}) + d_2 z_0 f'(z_0/c_{11})\lambda_1),} \right)
\]
where \( \lambda_1 \) is the smallest root of the characteristic equation (42).
Proof. Note that
\[ c_{11} \left( e^{\lambda_1 t} - q e^{\beta_1 t} \right) \leq \varphi(t) \leq c_{11} e^{\lambda_1 t} \quad \text{for } t \in \mathbb{R}. \tag{71} \]

Then we have
\[ \lim_{t \to -\infty} \left| \varphi(t) e^{-\lambda_1 t} - c_{11} \right| \leq \lim_{t \to -\infty} c_{11} q e^{(\eta - 1)\lambda_1 t} = 0, \tag{72} \]

which implies that
\[ \lim_{t \to -\infty} \varphi(t) e^{-\lambda_1 t} = c_{11}. \tag{73} \]

Note that we have from \(0 \leq \varphi(t)e^{-\lambda_1 t} \leq c_{11}\) and (A1) that
\[ e^{-\lambda_1 t} \int_{-\infty}^{+\infty} I(y-t) \varphi(y) dy \]
\[ =\int_{-\infty}^{+\infty} e^{\lambda_1 y} \varphi(y + t) e^{-\lambda_1 (y + t)} dy < \infty, \tag{74} \]

which is uniformly on \(t\). By the second equation of (12), we have from (73), \( F(\lambda_1, c) = 0 \) and convergence theorem that
\[ \lim_{t \to -\infty} \varphi'(t) e^{-\lambda_1 t} \]
\[ = \frac{1}{c} \left[ c_{11} \left( g \left( \frac{z_0}{c_{11}} \right) - d_2 \right) + d_2 \lim_{t \to -\infty} e^{-\lambda_1 t} \int_{-\infty}^{+\infty} I(y-t) \varphi(y) dy \right] \]
\[ = \frac{1}{c} \left[ c_{11} \left( g \left( \frac{z_0}{c_{11}} \right) - d_2 \right) + d_2 \int_{-\infty}^{+\infty} e^{\lambda_1 y} \lim_{t \to -\infty} \varphi(y + t) e^{-\lambda_1 (y + t)} dy \right] \]
\[ = \frac{1}{c} \left[ c_{11} \left( g \left( \frac{z_0}{c_{11}} \right) - d_2 \right) + c_{11} \left( d_2 + c \lambda_1 - g \left( \frac{z_0}{c_{11}} \right) \right) \right] \]
\[ = c_{11} \lambda_1. \tag{75} \]

Since \( \varphi(t) = Q_1(\phi, \varphi)(t) \), by (17), we know that
\[ \phi(t) = \frac{1}{c} e^{-(\beta_1/\lambda_1)t} \int_{-\infty}^{t} e^{(\beta_1/\lambda_1)s} \phi_1(\phi, \varphi)(s) ds. \tag{76} \]

On the other hand, by (76), (15), (42), and (75), noting \( f(z_0) = 0 \) and using L'Hôpital's rule, we get
\[ \lim_{t \to -\infty} \phi(t) e^{-\lambda_1 t} = \frac{1}{c} \lim_{t \to -\infty} e^{-(\lambda_1 + \beta_1/\lambda_1)t} \int_{-\infty}^{t} e^{(\beta_1/\lambda_1)s} H_1(\phi, \varphi)(s) ds \]
\[ = \frac{1}{c} \lim_{t \to -\infty} e^{(\beta_1/\lambda_1)t} H_1(\phi, \varphi)(t) \]
\[ = \frac{1}{c(\lambda_1 + \beta)} \left( d_1 \lim_{t \to -\infty} e^{-\lambda_1 t} \int_{-\infty}^{+\infty} I(y-t) \phi(y) dy - \frac{z_0}{c_{11}} \lim_{t \to -\infty} f \left( z_0 - c_{11} \phi(t) + \varphi(t) \right) e^{\lambda_1 t} \right) \]
\[ + b_1 \lim_{t \to -\infty} \phi(t) e^{-\lambda_1 t} \]
\[ = \frac{1}{c(\lambda_1 + \beta)} \left[ \left( b_1 + d_1 + c \lambda_1 \right) \int_{-\infty}^{+\infty} f \left( z_0 - c_{11} \phi(t) + \varphi(t) \right) e^{\lambda_1 t} \right] \]
\[ + \lim_{t \to -\infty} \phi(t) e^{-\lambda_1 t} - z_0 f'(z_0). \tag{77} \]

By the first equation of (12), we have from (75) and \( F(\lambda_1, c) = 0 \) that
\[ c \lim_{t \to -\infty} \phi'(t) e^{-\lambda_1 t} \]
\[ = d_1 \lim_{t \to -\infty} e^{-\lambda_1 t} \int_{-\infty}^{+\infty} I(y-t) \phi(y) dy - d_1 \]
\[ \times \lim_{t \to -\infty} \phi(t) e^{-\lambda_1 t} - \frac{z_0}{c_{11}} \lim_{t \to -\infty} f \left( z_0 - c_{11} \phi(t) + \varphi(t) \right) e^{\lambda_1 t} \]
\[ = \frac{d_1}{d_2} \left( d_2 + c \lambda_1 - g \left( \frac{z_0}{c_{11}} \right) \right) \lim_{t \to -\infty} \phi(t) e^{-\lambda_1 t} \]
\[ - d_1 \lim_{t \to -\infty} \phi(t) e^{-\lambda_1 t} - z_0 f'(z_0) \]
\[ \times \lim_{t \to -\infty} \phi'(t) e^{-\lambda_1 t} - z_0 f'(z_0). \]
Theorem 14. Let \((\xi(t), \eta(t))\) be a traveling wavefront of \((6)\) decided by Theorem 12, then
\[
\lim_{t \to -\infty} \left( (\xi(t), \eta(t)) = (\zeta, \zeta), \phi(t) = \phi(t) \right) = (\zeta, \zeta),
\]

where \(\lambda_1\) is the smallest root of the characteristic equation (42).

5. Concluding Discussions

We have considered a reaction model with nonlocal diffusion for competing pioneer-climax species. Some recent works (see Brown et al. \[4\], Yuan and Zou \[6\]) showed that the model with local diffusion (expressed by Laplacian operator) supports traveling wavefronts connecting two boundary equilibria or one boundary equilibrium and the coexisting equilibrium under some restrictions on the parameters. In Yuan and Zou \[6\], the sufficient condition for \(2\) to have the traveling wavefront connecting \((z_0/c_{11}, 0)\) and \((u^*, v^*)\) is \(d_2/d_1 \geq 1/2\), but ours for \(6\) with nonlocal diffusion is \(d_2/d_1 \geq 1\). For a fixed \(d_2\), to shift \(d_2/d_1 \geq 1/2\) to \(d_2/d_1 \geq 1\), one needs a smaller \(d_1\). But for a fixed \(d_1\), to shift \(d_2/d_1 \geq 1/2\) to \(d_2/d_1 \geq 1\), one needs a larger \(d_1\). These facts imply that the nonlocal diffusion of the pioneer species accelerates the mild wave propagation, while the nonlocal diffusion of the climax species defers the mild wave propagation. That is to say, the nonlocal diffusion did affect the wave propagation of these two competitive species.

The generalized boundary conditions,
\[
\lim_{t \to -\infty} \left( \begin{array}{c}
\frac{z_0}{c_{11}} - \phi(t), \eta(t) = \left( \frac{z_0}{c_{11}}, 0 \right) \\text{if} \phi(t) < \phi_c(t),
\frac{z_0}{c_{11}} - \phi(t), \eta(t) = \left( u^*, v^* \right),
\end{array} \right)
\]

lead to an explanation that the climax species starts its invasion after that the pioneer species has achieved its steady state, and also the competition between the two species was not intense; they can achieve a coexistence state finally. See \[19\] for the significance of biological invasion.

We believe that this is the first time that the dynamics of the pioneer-climax competition model with nonlocal diffusion are studied. This model has complicated equilibrium structure, and we only considered one possible case about the traveling wavefront connecting one boundary equilibrium and the coexisting equilibrium. Some other situations about the species invasions and propagation of waves would be of great interest for further research.

Acknowledgments

The authors are very grateful to the anonymous referees for careful reading and helpful suggestions which led to an improvement of their original paper. Research is supported by the Natural Science Foundation of China (11171120), the Doctoral Program of Higher Education of China (20094407110001), and the Natural Science Foundation of Guangdong Province (1015106310100003).

References


Submit your manuscripts at
http://www.hindawi.com