Research Article

The Twisting Bifurcations of Double Homoclinic Loops with Resonant Eigenvalues

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Received 19 February 2013; Accepted 22 April 2013

Academic Editor: Maoan Han

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The twisting bifurcations of double homoclinic loops with resonant eigenvalues are investigated in four-dimensional systems. The coexistence or noncoexistence of large 1-homoclinic orbit and large 1-periodic orbit near double homoclinic loops is given. The existence or nonexistence of saddle-node bifurcation surfaces is obtained. Finally, the complete bifurcation diagrams and bifurcation curves are also given under different cases. Moreover, the methods adopted in this paper can be extended to a higher dimensional system.

1. Introduction and Setting of the Problem

In recent years, there is a large literature concerning the bifurcation problems of homoclinic and heteroclinic loops in dynamical systems (see [1–23] and the references therein). However, to the best of the authors’ knowledge, less attention has been devoted to the bifurcation of double homoclinic loops. Han and Bi [24] investigated the existence of homoclinic bifurcation curves and small and large limit cycles bifurcated from a double homoclinic loop under multiple parameter perturbations for general planar systems. Han and Chen [25] gave the number of limit cycles near double homoclinic loops under perturbations in planar Hamiltonian systems. Homburg and Knobloch [26] considered the existence of two homoclinic orbits in the bellows configuration, where the homoclinic orbits approach the equilibrium along the same direction for positive and negative times in conservative and reversible systems. Morales et al. [27, 28] presented contracting and expanding Lorenz attractors through resonant double homoclinic loops. Lu [29] obtained codimension 2 bifurcations of twisted double homoclinic loops in higher dimensional systems. Ragazzo [30] investigated the stability of sets that were generalizations of the simple pendulum double homoclinic loop. In our recent work [31, 32], codimension 2 bifurcations of double homoclinic loops and codimension 3 bifurcations of nontwisted double homoclinic loops with resonant eigenvalues were studied. Concerning this topic, a more extensive list of references can be found in the references mentioned earlier. Generally speaking, when studying the problem of single homoclinic or heteroclinic bifurcation connecting hyperbolic equilibrium, the bifurcation is more complicated as it is twisted. Moreover, it is known that double homoclinic loops have higher codimension than a single homoclinic loop under the same conditions. Therefore, it will be more challenging and difficult to analyze the twisting bifurcations of double homoclinic loops.

In this paper, on the one hand, using the method which was originally established in [22, 23] and then improved in [9, 17, 21], and so forth, we study the bifurcations of double homoclinic loops with resonant eigenvalues under twisted cases. Besides, the method is more applicable and bifurcation equations obtained in this paper are easier to compute. On the other hand, frequently, the too many equivalent terms in the bifurcation equation will make the bifurcation equation more complex so that it is very difficult
to analyze the bifurcation equation. Applying the method used by Homburg and Knobloch [26] to analyze the center-stable and center-unstable tangent bundles, we cannot only get a smooth coordinate transformation in the neighborhood of $\Gamma$ small enough, but also make the bifurcation equation definite under an additional condition. Such strategy in dealing with the problems of bifurcations from homoclinic and heteroclinic loops is rarely used in the existing literatures. Therefore, a main feature in this paper is a combination of geometrical and analytical methods.

Motivated by these points, we will consider the following $C^r$ system and its unperturbed system:

$$\dot{z} = f(z) + g(z, \mu),$$

$$\dot{z} = f(z),$$

where $r$ is large enough, $z \in \mathbb{R}^4$, $\mu \in \mathbb{R}^l$, $l \geq 3$, $0 < |\mu| \ll 1$, $f(0) = 0$, $g(0, \mu) = g(z, \mu) = 0$.

We make the following assumptions, which are shown in Figure 1.

1. **The linearization $Df(0)$ has simple real eigenvalues at the equilibrium $0$: $-\rho_2, -\rho_1, \lambda_1, \lambda_2$ satisfying $-\rho_2 < -\rho_1 < 0 < \lambda_1 < \lambda_2$, $\rho_1 = \lambda_1$.**

2. **System (2) has double homoclinic loops $\Gamma = \Gamma_1 \cup \Gamma_2$, $\Gamma_1 = \{z = r(t) : t \in \mathbb{R}, r(t(\pm \infty)) = 0\}$ and $\dim(T\Gamma_1 W_i ^s \cap T\Gamma_1 W_i ^u) = 1$, $i = 1, 2$, where $W_i ^s$ and $W_i ^u$ are the stable and unstable manifolds of 0, respectively.**

3. **Let $e_{i}^{s} = \lim_{t \to \infty}(r(t)/|r(t)|)$, and $e_{i}^{u} = T_0 W_i ^u$ unit eigenvectors corresponding to $\lambda_1$ and $-\rho_1$, respectively, and satisfying $e_1 ^s = -e_2 ^u, e_1 ^u = -e_2 ^s$.**

4. **Span$[T\Gamma_1 W_i ^u, T\Gamma_1 W_i ^s, e_{i}^{s}] = \mathbb{R}^4$ as $t \to 1$, and Span$[T\Gamma_1 W_i ^u, T\Gamma_1 W_i ^s, e_{i}^{u}] = \mathbb{R}^4$ as $t \to -1, i = 1, 2$.**

As shown in Figure 1, under the hypotheses $(H_1)$-$($$H_4)$, we can see that the double homoclinic loops $\Gamma$ are of codimension 3.

The single homoclinic loop in high-dimensional systems has been investigated by many authors (see [1, 2, 4–8, 13–15, 17, 21, 22] and the references therein). In this paper, we only focus on bifurcations of the large loop; that is, the double loops $\Gamma = \Gamma_1 \cup \Gamma_2$.

A nondegenerate homoclinic orbit is called a nontwisted homoclinic orbit if the unstable manifold $W^u$ has an even number of half-twists along the homoclinic orbit, and is called a twisted homoclinic orbit if $W^u$ has an odd number of half-twists along the homoclinic orbit; see more details in Deng [4]. A characterization for a twisted homoclinic orbit is that it arises from and tends to the equilibrium point from different sides of the unstable manifold. However, a nontwisted homoclinic orbit does so from the same side of the manifold. For the double homoclinic loop, $\Gamma = \Gamma_1 \cup \Gamma_2$, it is called double twisted if both $\Gamma_1$ and $\Gamma_2$ are twisted, single twisted if and only if one of them is twisted, and nontwisted otherwise.

The rest of this paper is organized as follows. In Section 2, the normal form in a neighborhood of the equilibrium small enough is established and the bifurcation equations are given. In Section 3, by bifurcation analysis, the results of twisting bifurcations and complete bifurcation diagrams are obtained under different cases. We end the paper with a conclusion in Section 4.

### 2. Normal Form and Bifurcation Equations

From the hypothesis $(H_1)$, we can see that we confine ourselves to consider the resonance taking place between the two principal eigenvalues $\lambda_1$ and $-\rho_1$. Moreover, the corresponding eigenvectors are also the tangent directions of the homoclinic orbits. For simplicity, we may choose a new parameter $\mu = (\alpha, \nu)$ such that $\rho_1(\mu) = \dot{\lambda}_1(\nu) + \alpha \lambda_1(\nu)$, $-1 < \alpha < 1$.

Let $U$ be a neighborhood of 0 small enough. By analyzing the center-stable and center-unstable tangent bundles, Homburg and Knobloch [26] obtained that there is a smooth coordinate transformation, such that in $U$ system (1) takes the following form:

$$\begin{align*}
\dot{x} &= \lambda_1(x) + o(1) + O(\nu) (O(y) + O(v)) , \\
\dot{y} &= y(-1 + \alpha) \lambda_1(y) + o(1) + O(\nu) (O(x) + O(u)) , \\
\dot{u} &= u(\lambda_2(x) + o(1)) + x^2 H_1(x, y, v) , \\
\dot{v} &= v(-\rho_2(y) + o(1)) + y^2 H_2(x, y, u) .
\end{align*}$$

For the definiteness of the bifurcation equation, we make an additional assumption as follows:

$$(H_5) \ H_1(x, 0, 0) = 0, H_2(0, y, 0) = 0; \text{that is,}$$

$$\begin{align*}
H_1(x, y, v) &= a_1 x^k y^k + a_2 x^k y^{k+1} + a_3 x^k y^{k+2} + y^{k+3} + h.o.t. , \\
H_2(x, y, u) &= b_1 y^i x^j + b_2 y^i u^j + b_3 x^i y^i u^j + h.o.t. ,
\end{align*}$$

where $k_i > \lambda_2 / \lambda_1$, $i = 1, 3, 5$, $k_2 \rho_2 / \lambda_1 > 2$, $k_3 \rho_2 / \lambda_1 > 2$, $(k_6 \rho_1 + k_7 \rho_2) / \lambda_1 > 2$, $l_i > \rho_2 / \rho_1$, $i = 1, 3, 5$, $l_2 \lambda_1 / \rho_1 > 2$, $l_4 \lambda_1 / \rho_2 > 2$, $(k_6 \lambda_1 + l_7 \lambda_2) / \rho_1 > 2$. 

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{fig1}
\caption{Double homoclinic loops $\Gamma = \Gamma_1 \cup \Gamma_2$.}
\end{figure}
By the same process as in [32], which is based on the
analysis of the Poincaré return map defined on some local
transversal section of the double homoclinic loop \( \Gamma \), we obtain the bifurcation equations as follows:

\[
\begin{align*}
    s_2 &= (w_1^{12})^{-1}s_1^{1+\alpha} - \delta^{-1}M_1^1 v + \text{h.o.t.}, \\
    s_1 &= (w_2^{12})^{-1}s_2^{1+\alpha} + \delta^{-1}M_2^1 v + \text{h.o.t.}
\end{align*}
\]

### 3. Bifurcation Analysis

Denote that \( w_1^{12} = \Delta |w_1^{12}| \). We say that \( \Gamma \) is nontwisted as \( \Delta_1 = \Delta_2 = 1 \) and twisted as \( \Delta_1 = \Delta_2 = -1 \) or \( \Delta_1 \Delta_2 = -1 \). In this paper, we focus on the twisted bifurcations. It is easy to see that \( |w_1^{12}| \) is the approximate expanding rate of the solution \( z_i(t) \) from \( T_i^1 \) to \( -T_i^1 \).

**Case 1** (\( \Delta_1 = \Delta_2 = -1 \) (i.e., double twisted)). For convenience and simplicity, we use the following notations throughout Case 1:

\[
\begin{align*}
    R_1 &= \{ v : M_1^1 v > 0, M_2^1 v < 0, |v| \ll 1 \}, \\
    R_1^\alpha &= \{ v : M_1^1 v < 0, M_2^1 v > 0, |M_2^1 v| = O(M_1^1 v), |v| \ll 1 \}, \\
    D_1 &= \left\{ v \in R_1 : \left( \delta^{-1}M_1^1 v \right)^{1+\alpha} - w_1^{12} \left( 2^{(1+\alpha)/2} - 1 \right) \\
    &\quad \times \delta^{-1}M_2^1 v > 0 \text{ for } \alpha > 0 \right\}, \\
    D_2 &= \left\{ v \in R_1 : \left( -\delta^{-1}M_2^1 v \right)^{1+\alpha} + w_1^{12} \left( 2^{(1+\alpha)/2} - 1 \right) \\
    &\quad \times \delta^{-1}M_1^1 v > 0 \text{ for } \alpha > 0 \right\}.
\end{align*}
\]

If (6) has solution \( s_1 = s_2 = 0 \), then we have

\[ M_1^1 v + \text{h.o.t.} = 0, \quad i = 1, 2. \tag{8} \]

If \( M_i^1 \neq 0 \), then there exists a codimension 1 surface \( \Sigma_i \) with a normal vector \( M_i^1 \) at \( v = 0 \), such that the \( i \)-th equation of (6) has solution \( s_1 = s_2 = 0 \) as \( v \in \Sigma_i \) and \( |v| \ll 1 \); that is, \( \Gamma_i \) is persistent. If \( \text{rank}(M_1^1, M_2^1) = 2 \), then \( \Sigma_1 \cap \Sigma_2 \) is a codimension 2 surface with a normal plane \( \text{span}(M_1^1, M_2^1) \) such that (6) has solution \( s_1 = s_2 = 0 \) as \( v \in \Sigma_1 \) and \( |v| \ll 1 \); equivalently, the large loop \( \Gamma = \Gamma_1 \cup \Gamma_2 \) is persistent.

Suppose that (6) has solution \( s_1 = 0, s_2 > 0 \). Then, we have

\[
\begin{align*}
    s_2 &= -\delta^{-1}M_1^1 v + \text{h.o.t.}, \\
    0 &= (w_2^{12})^{-1}s_2^{1+\alpha} + \delta^{-1}M_2^1 v + \text{h.o.t.}
\end{align*}
\]

Hence, we obtain the large 1-homoclinic orbit bifurcation surface equation

\[ H_2^1 : \delta^{-1}w_2^{12}M_1^1 v + \left( -\delta^{-1}M_1^1 v \right)^{1+\alpha} + \text{h.o.t.} = 0, \tag{10} \]

which is well defined at least in the region \( R_2^1 \) and has a normal vector \( M_2^1 \) as \( \alpha > 0 \) (resp., \( M_1^1 \) as \( \alpha < 0 \)) at \( v = 0 \) such that system (1) has a large 1-homoclinic loop \( \Gamma_2^1 \) near \( \Gamma \) as \( v \in H_2^1 \). It also means that \( H_2^1 \) is tangent to \( \Sigma_1 \) as \( \alpha > 0 \) (resp., \( \Sigma_2 \) as \( \alpha < 0 \)). When \( v \in H_2^1 \), \( \alpha > 0 \), \( s_1 = 0 \), and \( s_2 = -\delta^{-1}M_1^1 v + \text{h.o.t.} \) (6) indicates that

\[
\begin{align*}
    s_{2v} &= -\delta^{-1}M_1^1 + \text{h.o.t.}, \\
    s_{1v} &= (1 + \alpha)(w_2^{12})^{-1}\left( -\delta^{-1}M_1^1 v \right)^{\alpha} s_{2v} + \delta^{-1}M_1^1 v + \text{h.o.t.} \tag{11}
\end{align*}
\]

Using (II) \( \times (1 + \alpha) \left( w_2^{12} \right)^{-1}(-\delta^{-1}M_1^1 v)^\alpha + (12) \), we have

\[ s_1|_{H_2^1} = \delta^{-1}M_1^1 + O\left( |M_1^1 v|^\alpha \right). \tag{13} \]

So, \( s_1 = s_1(v) \) increases along the direction of the gradient \( M_1^1 \) for \( v \) near \( H_2^1 \).

Similarly, by setting \( s_2 = e^\tau z_2 \), we can derive that \( s_1(v) \) increases along the direction \( -M_2^1 \) for \( v \) near \( H_2^1 \) as \( \alpha < 0 \).

If (6) has solution \( s_1 > 0 \) and \( s_2 = 0 \), then we have

\[
\begin{align*}
    0 &= (w_1^{12})^{-1}s_1^{1+\alpha} - \delta^{-1}M_1^1 v + \text{h.o.t.}, \\
    s_1 &= -\delta^{-1}M_1^1 v + \text{h.o.t.}
\end{align*}
\]

Therefore, we obtain the existence of the other large 1-homoclinic orbit bifurcation surface equation

\[ H_1^1 : \delta^{-1}w_1^{12}M_1^1 v - \left( -\delta^{-1}M_2^1 v \right)^{1+\alpha} + \text{h.o.t.} = 0, \tag{15} \]

which is well defined at least in the region \( R_1^1 \) and has a normal vector \( M_1^1 \) as \( \alpha > 0 \) (resp., \( M_2^1 \) as \( \alpha < 0 \)) at \( v = 0 \) such that system (1) has a large 1-homoclinic loop \( \Gamma_1^1 \) near \( \Gamma \) as \( v \in H_1^1 \).

Thus, \( H_1^1 \) is also tangent to \( \Sigma_1 \) as \( \alpha > 0 \) (resp., \( \Sigma_2 \) as \( \alpha < 0 \)). For \( v \in H_1^1 \) and \( \alpha > 0 \), \( s_1 = -\delta^{-1}M_1^1 v + \text{h.o.t.}, s_2 = 0 \), it follows from (6) that

\[
\begin{align*}
    s_{2v} &= (1 + \alpha)(w_1^{12})^{-1}\left( -\delta^{-1}M_1^1 v \right)^{\alpha} s_{1v} - \delta^{-1}M_1^1 + \text{h.o.t.}, \\
    s_{1v} &= -\delta^{-1}M_2^1 + \text{h.o.t.} \tag{16}
\end{align*}
\]

Computing (17) \( \times (1 + \alpha)(w_1^{12})^{-1}(-\delta^{-1}M_1^1 v)^\alpha + (16) \), it leads to

\[ s_{2v}|_{H_1^1} = \delta^{-1}M_1^1 + O\left( |M_1^1 v|^\alpha \right). \tag{18} \]

So, \( s_2 = s_2(v) \) increases along the direction \( -M_1^1 \) for \( v \) close to \( H_1^1 \).

By a similar procedure, we can show that \( s_2(v) \) increases along the direction \( M_2^1 \) as \( v \) is in the neighborhood of \( H_1^1 \) and \( \alpha < 0 \).

Summing up the previous analysis, we have the following theorem.

**Theorem 1.** Suppose that \( (H_1)-(H_5) \) hold; then, the following conclusions are true.

(1) If \( M_i^1 \neq 0 \), then there exists a unique surface \( \Sigma_i \) with codimension 1 and normal vectors \( M_i^1 \) at \( v = 0 \), such that system (1) has a homoclinic loop near \( \Gamma_i \) if and only
if \( \nu \in \Sigma_1 \) and \( |\nu| \ll 1 \). If \( \text{rank} (M^1_1, M^1_2) = 2 \), then \( \Sigma_{12} = \Sigma_1 \cap \Sigma_2 \) is a codimension 2 surface and \( 0 \in \Sigma_{12} \) such that system (1) has a large loop consisting of two homoclinic orbits near \( \Gamma \) as \( \nu \in \Sigma_{12} \) and \( |\nu| \ll 1 \); that is, \( \Gamma \) is persistent.

2. In the region \( R^1_1 \), there exists a large 1-homoclinic orbit bifurcation surface \( H^1_1 \) which is tangent to \( \Sigma_2 \) (resp., \( \Sigma_1 \)) at \( \nu = 0 \) with the normal vector \( M^1_1 \) (resp., \( M^1_2 \)) as \( \alpha > 0 \) (resp., \( \alpha < 0 \)), and for \( \nu \in H^1_1 \), system (1) has a unique large 1-homoclinic orbit near \( \Gamma \). Furthermore, the unique large 1-homoclinic orbit near \( \Gamma \) becomes a large 1-periodic orbit when \( \nu \) moves along the direction \( M^1_2 \) (resp., \( -M^1_1 \)) and nearby \( H^1_1 \) as \( \alpha > 0 \) (resp., \( \alpha < 0 \)). Meanwhile, there exists another large 1-homoclinic orbit bifurcation surface \( H^1_1 \) which is tangent to \( \Sigma_2 \) (resp., \( \Sigma_1 \)) at \( \nu = 0 \) with the normal vector \( M^1_1 \) (resp., \( M^1_2 \)) as \( \alpha > 0 \) (resp., \( \alpha < 0 \)), and for \( \nu \in H^1_1 \), system (1) has another unique large 1-homoclinic orbit near \( \Gamma \). Furthermore, the unique large 1-homoclinic orbit near \( \Gamma \) changes into a large 1-periodic orbit when \( \nu \) shifts along the direction \( -M^1_1 \) (resp., \( M^1_2 \)) and near \( H^1_1 \) as \( \alpha > 0 \) (resp., \( \alpha < 0 \)).

**Lemma 2.** Suppose that hypotheses \((H_1)-(H_2)\) and \( 0 < \alpha \ll 1 \) are valid, then, in addition to the large 1-homoclinic loop \( L^1_2 \), system (1) has exactly one simple large 1-periodic orbit near \( \Gamma \) for \( \nu \in H^1_1 \cap D_2 \). Moreover, the large 1-periodic orbit is persistent as \( \nu \) changes in the neighborhood of \( H^1_1 \).

Proof. If \( \nu \in H^1_1 \) and \( |\nu| \ll 1 \), then we know that system (1) has one large 1-homoclinic loop \( L^1_2 \). Now, following (6), we have

\[
\left( \begin{array}{l}
(w^1_1)^{-1} s_1^{1+\alpha} - \delta^{-1} M^1_1 v + \text{h.o.t.} \\
\end{array} \right)^{1+\alpha} = w^1_2 s_1 - \delta^{-1} w^1_2 M^1_1 v + \text{h.o.t.}
\]

(19)

Let \( N_1(s_1) \) and \( L_1(s_1) \) be the left- and right-hand sides of (19), respectively. Then, by (10), we get \( N_1(0) = L_1(0) \) as \( \nu \in H^1_1 \). Moreover,

\[
N^1_1(s_1) = (1 + \alpha)^2 \left( \begin{array}{l}
(w^1_2)^{-1} s_1^{1+\alpha} - \delta^{-1} M^1_1 v + \text{h.o.t.} \\
\end{array} \right)^{1+\alpha},
\]

\[
L^1_1(s_1) = w^1_2 + \text{h.o.t.}
\]

(20)

Thus, \( 0 = N^1_1(s_1)|_{s_1=0} > L^1_1(s_1)|_{s_1=0} \). Therefore, there is an \( \bar{s}_1 \), \( 0 < \bar{s}_1 < 1 \), such that for \( 0 < s_1 < \bar{s}_1 \), \( N_1(s_1) > L_1(s_1) \). Let \( \bar{s}_1 = -\delta^{-1} M^1_1 v \). Then,

\[
N_1(\bar{s}_1) = \left( \begin{array}{l}
(w^1_2)^{-1} (\delta^{-1} M^1_2 v)^{1+\alpha} - \delta^{-1} M^1_1 v + \text{h.o.t.} \\
\end{array} \right)^{1+\alpha},
\]

\[
L_1(\bar{s}_1) = w^1_2 (\delta^{-1} M^1_2 v) - \delta^{-1} w^1_2 M^1_1 v + \text{h.o.t.}
\]

\[
= 2(\delta^{-1} M^1_1 v)^{1+\alpha} + \text{h.o.t.}
\]

(21)

which means that \( N_1(\bar{s}_1) < L_1(\bar{s}_1) \) as \( \nu \in H^1_1 \cap D_2 \). Then, it follows from \( N^1_1(s_1) < 0 \) that \( N_1(s_1) = L_1(s_1) \) has a unique solution \( s_1^* \) satisfying \( 0 < s_1^* < \bar{s}_1 \) < 1, which is shown in Figure 2. That is, system (1) has a unique large 1-periodic loop near \( \Gamma \) for \( \nu \in H^1_1 \cap D_2 \) and \( 0 < |\nu| \ll 1 \). The proof is complete.

\[ \square \]

**Lemma 3.** Suppose that hypotheses \((H_3)-(H_2)\) and \( 0 < \alpha \ll 1 \) hold. Then, system (1) has a saddle-node bifurcation surface of large 1-periodic orbit in the region \( R^1_2 \cap \{ |M^1_1| = \alpha(|M^1_2|) \} \) as follows:

\[
SN^2: -\delta^{-1} w^1_2 M^1_1 v
\]

\[
= \left( \begin{array}{l}
\left( w^1_2 \right)^{-1} \left( \frac{w^1_2 M^1_1 v}{(1 + \alpha^2 M^2_2 v)} - \delta^{-1} M^1_1 v \right)^{1+\alpha} \\
\end{array} \right) + \text{h.o.t.}
\]

(22)

\[
-\omega^2 \left( \frac{w^1_2 M^1_1 v}{(1 + \alpha^2 M^2_2 v)} \right)^{1+\alpha} + \text{h.o.t.}
\]

Proof. It is easy to see that \( h = N_1(s_1) \) is tangent to \( h = L_1(s_1) \) at some point \( s_1 \), as shown in Figure 3; if

\[
N_1(s_1) = L_1(s_1),
\]

(23)

then

\[
\left( \begin{array}{l}
\left( w^1_2 \right)^{-1} s_1^{1+\alpha} - \delta^{-1} M^1_1 v + \text{h.o.t.} \\
\end{array} \right)^{1+\alpha} = w^1_2 s_1 - \delta^{-1} w^1_2 M^1_2 v + \text{h.o.t.},
\]

(24)

\[
(1 + \alpha^2) \left( w^1_2 \right)^{-1} s_1^{1+\alpha} - \delta^{-1} M^1_1 v + \text{h.o.t.}\]

(25)

\[
= w^1_2 + \text{h.o.t.}
\]

It is not difficult to see that (24) and (25) have a unique small positive solution

\[
s_1 = \left( \frac{w^1_2 M^1_1 v}{(1 + \alpha^2 M^2_2 v)} \right)^{1+\alpha} + \text{h.o.t.}
\]

(26)

when \( \nu \in R^1_2 \) and \( |M^1_1| = \alpha(|M^1_2|) \). Substituting (26) into (24), we get the surface \( SN^2 \). It is easy to verify that the solution \( s_1 \) of (6) is positive as \( s_1 \) is given by (26) and \( \nu \in SN^2 \). Thus, the proof of the lemma is complete.

\[ \square \]

**Remark 4.** Due to \( N^1_1(s_1) \), we see that the line \( L_1(s_1) \) lies above the curve \( N_1(s_1) \) as \( \nu \in SN^2 \). Moreover, \( L_1(0) = -\delta^{-1} w^1_2 M^1_2 v + \text{h.o.t.} \) decreases as \( \text{rank} (M^1_1, M^1_2) = 2 \) and \( \nu \) moves along the direction \( -M^1_2 \); in this case, system (1) exhibits two large 1-periodic orbits. And as \( \nu \) leaves \( SN^2 \) along the opposite direction, there is no large 1-periodic orbit.

**Corollary 5.** The bifurcation surface \( \{ 0 < \alpha \ll 1 \} \times SN^2 \) and the region \( \{ 0 < \alpha \ll 1 \} \times R^1_2 \cap \{ (\alpha; \nu) : |M^1_1| = O(|M^1_2|^{|1+\alpha|}, \alpha \ln |M^1_2| \ll -1) \} \) have no intersection point.
Proof. Let \( w^{12}_1 | M_1^1 y | = -a^\alpha | M_2^1 y |^{1+\alpha} \), where \( 0 < a < \delta^{-1} e^2 \) is a given constant; then, in view of \( | M_2^1 y |^{\alpha} \ll 1 \) and \((1 + \alpha)^{1/\alpha} \to e\) as \( \alpha \to 0 \), we know the right side of the expression \( SN^2 \) as follows:

\[
\left[ \left( w^{12}_1 \right)^{-1} \left( \frac{w^{12}_1 M_1^1 y}{(1 + \alpha)^2 M_2^1 y} \right)^{(1+\alpha)/\alpha} - \delta^{-1} M_1^1 y \right]^{1+\alpha}
\]

\[
- w^{12}_2 \left( \frac{w^{12}_1 M_1^1 y}{(1 + \alpha)^2 M_2^1 y} \right)^{1/\alpha} + \text{h.o.t.}
\]

\[
< \left[ \frac{1}{4w^{12}_1 e^2 a^{1+\alpha} | M_1^1 y |^{1+\alpha}} - \frac{\delta^{-1} a^\alpha | M_1^1 y |^{1+\alpha}}{w^{12}_1 a^{\alpha} | M_2^1 y |^{1+\alpha}} \right]^{1+\alpha}
\]

\[
- w^{12}_2 \left( \frac{w^{12}_1 M_1^1 y}{(1 + \alpha)^2 M_2^1 y} \right)^{1/\alpha} + \text{h.o.t.}
\]

\[
= \left( 4w^{12}_1 e^2 \right)^{(1+\alpha)/\alpha} | M_1^1 y |^{(1+\alpha)/\alpha} \left( a^{1+\alpha} - 4\delta^{-1} e^2 a^\alpha \right)^{1+\alpha}
\]

\[
- w^{12}_2 \left( \frac{w^{12}_1 M_1^1 y}{(1 + \alpha)^2 M_2^1 y} \right)^{1/\alpha} + \text{h.o.t.}
\]

\[
= a^{a(1+\alpha)} \left( 4w^{12}_1 e^2 \right)^{(1+\alpha)/\alpha} | M_1^1 y |^{(1+\alpha)/\alpha} \left( a - 4\delta^{-1} e^2 \right)^{1+\alpha}
\]

\[
- w^{12}_2 \frac{a}{e^2} M_1^1 y + \text{h.o.t.}
\]

\[
< \delta^{-1} \left| w^{12}_2 \right| \left| M_1^1 y \right|
\]

and \( \delta^{-1} | w^{12}_2 | | M_1^1 y | \) is the left side of the expression \( SN^2 \). Hence, the proof is complete. \( \square \)

**Corollary 6.** As \( w^{12}_1 w^{12}_2 > 1 \), the bifurcation surface \( 0 < \alpha \ll 1 \times SN^2 \) and the region \((0 < \alpha \ll 1) \times \Gamma_1^1 \cap \{ (\alpha; y) : | M_1^1 y | = O(| M_2^1 y |^{1+\alpha}), -1 \leq \alpha \ln | M_2^1 y | < 0 \} \) have no intersection point.

**Proof.** Still let \( w^{12}_1 | M_1^1 y | = -a^\alpha | M_2^1 y |^{1+\alpha} \), where \( 0 < a < \delta^{-1} e^2 \) is a given constant; then, due to \( | M_2^1 y |^\alpha = 1 + o(| M_2^1 y |) \), we know that

\[
L \equiv -\delta^{-1} w^{12}_1 w^{12}_2 M_2^1 y + w^{12}_1 w^{12}_2 \left( \frac{w^{12}_1 M_1^1 y}{(1 + \alpha)^2 M_2^1 y} \right)^{1/\alpha}
\]

\[
= w^{12}_1 w^{12}_2 | M_2^1 y | \left( -\delta^{-1} + o(1 + \alpha)^{-2/\alpha} \right),
\]

\[
R \equiv \left( w^{12}_1 \right)^{-\alpha} \left[ \left( \frac{w^{12}_1 M_1^1 y}{(1 + \alpha)^2 M_2^1 y} \right)^{(1+\alpha)/\alpha} - \delta^{-1} w^{12}_1 | M_1^1 y | \right]^{1+\alpha}
\]

\[
+ \text{h.o.t.}
\]

\[
= \left[ (1 + \alpha)^{-2(1+\alpha)/\alpha} a^{1+\alpha} | M_2^1 y |^{1+\alpha} - \delta^{-1} a^{\alpha} | M_1^1 y |^{1+\alpha} \right]^{1+\alpha}
\]

\[
+ \text{h.o.t.}
\]

\[
> a^{a(1+\alpha)} | M_2^1 y | \left[ \delta^{-1} + o(1 + \alpha)^{-2/\alpha} \right]^{1+\alpha} + \text{h.o.t.}
\]

As \( w^{12}_1 w^{12}_2 > 1 \), \( a > 0 \) is a constant, and \( \alpha > 0 \) is small enough, it is easy to see that \( R > L \). This contradicts the expression of \( SN^2 \). The proof is complete. \( \square \)

By a similar analysis as in Lemmas 2 and 3, we can obtain the following results.

**Lemma 7.** Suppose that hypotheses (H1)–(H2) and \( 0 < \alpha \ll 1 \) are valid; then, in addition to the large 1-homoclinic loop \( \Gamma_1^1 \), system (1) has exactly one single large 1-periodic orbit near \( \Gamma \) for \( y \in H_1^1 \cap D_1 \). Moreover, the large 1-periodic orbit is persistent as \( y \) changes in the neighborhood of \( H_1^1 \).

**Lemma 8.** Suppose that hypotheses (H1)–(H2) and \( 0 < \alpha \ll 1 \) hold. Then, system (1) has a saddle-node bifurcation surface of
large 1-periodic orbit in the region \( R_1^1 \cap \{ v : |M^1_2|v = o(|M^2_2|v) \} \) as follows:

\[
SN^1 : \delta^{-1} w_1^{12} M_1^1 v = \left( \frac{\delta^{-1} M_2^1 v (1 + \alpha)^2}{(1 + \alpha)^2 - 1} \right)^{1 + \alpha} - w_1^{12} \left( \frac{\delta^{-1} w_2^{12} M_1^1 v}{(1 + \alpha)^2 - 1} \right)^{1/(1 + \alpha)} + \text{h.o.t.}
\]

Remark 9. Let \( N_2(s_2) = \left\{ (w_2^{12}, s_2) : \delta^{-1} M_2^1 v + \text{h.o.t.} \right\}^{1 + \alpha} \) and \( L_2(s_2) = w_1^{12} s_2 + \delta^{-1} w_1^{12} M_1^1 v + \text{h.o.t.} \). Due to \( N_2(s_2) > 0 \) and \( L_2(0) = \delta^{-1} w_1^{12} M_1^1 v + \text{h.o.t.} \), we claim that the line \( L_2(s_2) \) lies above the curve \( N_2(s_2) \) as \( v \in SN^1 \), and when \( \text{rank}(M_1^1, M_2^1) = 2 \) and \( v \) leaves \( SN^1 \) along the direction \( M_1^1 \), \( L_2(0) \) decreases; hence, system (1) has two large 1-periodic orbits, and when \( v \) moves along the direction \( -N_1^1 \), there is no large 1-periodic orbit.

Corollary 10. The bifurcation surface \( \{ 0 < \alpha < 1 \} \times SN^1 \) and the region \( \{ 0 < \alpha < 1 \} \times R_2^1 \cap \{ (\alpha; v) : |M^1_2|v = O(|M^2_2|v)^{1 + \alpha} \} \) have no intersection point.

Corollary 11. As \( w_1^{12} w_2^{12} > 1 \), the bifurcation surface \( \{ 0 < \alpha < 1 \} \times SN^1 \) and the region \( \{ 0 < \alpha < 1 \} \times R_2^1 \cap \{ (\alpha; v) : |M^1_2|v = O(|M^2_2|v)^{1 + \alpha} \} , -1 < \alpha \ln |M^2_2|v < 0 \) have no intersection point.

In the following we define open regions in the neighborhood of the origin of the \( v \)-space, which are shown in Figures 4 and 5.

\( (R_1^1)_{0.0} \) is bounded by \( SN^1 \) and \( SN^2 \), \( (R_1^1)_1 \) is bounded by \( \Sigma_2 \) and \( H_2^1 \), \( (R_2^1)_0 \) is bounded by \( H_2^2 \) and \( SN^2 \), \( (R_2^1)_1 \) is bounded by \( SN^1 \) and \( SN^2 \), \( (R_3^1)_0 \) is bounded by \( SN^1 \) and \( H_1^1 \), \( R_3^1 \) is bounded by \( \Sigma_1 \) and \( \Sigma_2 \), and \( (R_3^1)_1 \) is bounded by \( H_2^1 \) and \( H_1^1 \).

Now, the previous analysis is summarized in the following three theorems, as shown in Figures 4 and 5.

**Theorem 12.** Suppose that hypotheses (H1)-(H3) hold, \( 0 < \alpha < 1 \), and \( -1 < \alpha \ln |M^2_2|v < 0 \). Then, system (1)

1. has exactly one simple large 1-periodic orbit near \( \Gamma \) as \( v \in (R_1^1)_1 \); (8)
2. has a unique double large 1-periodic orbit near \( \Gamma \) as \( v \in SN^2 \); (9)
3. has exactly two simple large 1-periodic orbits near \( \Gamma \) as \( v \in (R_1^1)_2 \); (10)
4. has exactly one simple large 1-periodic orbit and one large 1-homoclinic loop near \( \Gamma \) as \( v \in H_2^1 \cap D_2 \); (11)
5. does not have any large 1-periodic and large 1-homoclinic loop near \( \Gamma \) as \( v \in (R_1^1)_0 \); (12)
6. has exactly one simple large 1-periodic orbit near \( \Gamma \) as \( v \in (R_1^1)_1 \); (13)
7. has a unique double large 1-periodic orbit near \( \Gamma \) as \( v \in SN^1 \); (14)
8. has exactly two simple large 1-periodic orbits near \( \Gamma \) as \( v \in (R_1^1)_2 \); (15)
9. has exactly one simple large 1-periodic orbit and one large 1-homoclinic loop near \( \Gamma \) as \( v \in H_1^1 \cap D_1 \). (16)

**Theorem 13.** Suppose that hypotheses (H1)-(H3) hold, \( 0 < \alpha < 1 \), and \( -1 < \alpha \ln |M^2_2|v < 0 \). Then, system (1)

1. has exactly one simple large 1-periodic orbit near \( \Gamma \) as \( v \in (R_1^1)_1 \); (17)
2. has exactly one simple large 1-periodic orbit and one large 1-homoclinic loop near \( \Gamma \) as \( v \in H_2^1 \cap D_2 \); (18)
3. has exactly two simple large 1-periodic orbits near \( \Gamma \) as \( v \in (R_1^1)_2 \); (19)
4. has exactly one simple large 1-periodic orbit and one large 1-homoclinic loop near \( \Gamma \) as \( v \in H_1^1 \cap D_1 \).
Remark 14. Suppose that hypotheses \((H_1)-(H_3)\) hold, \(0 < \alpha \ll 1, \alpha \ln |M_1^2| \ll -1, \nu \in R^1_\nu\); then the conclusions of Theorem 13 are still true, and the bifurcation diagram is the same as Figure 5.

Denote by \(D^2_i\) the open region with boundaries \(\Sigma_1\) and \(\Sigma_2\), such that \(D^2_1 \cap \{v : M^2_1 v > 0, M^2_2 v > 0, |v| \ll 1\} \neq \emptyset\). \(D^2_2\) is the open region with boundaries \(\Sigma_2\) and \(\Sigma_1\), such that \(D^2_1 \cap \{v : M^2_1 v < 0, M^2_2 v < 0, |v| \ll 1\} \neq \emptyset\).

From the bifurcation equations (6), we have the following theorem.

Theorem 15. Suppose that hypotheses \((H_1)-(H_3)\) hold, and \(0 < \alpha \ll 1\). Then, system (1)

1. does not have any large 1-periodic orbit near \(\Gamma\) as \(v \in D^2_1\);
2. does not have any large 1-periodic orbit near \(\Gamma\) as \(v \in D^2_2\);
3. does not have any large 1-periodic orbit near \(\Gamma\) as \(v \in R^1_\nu\).

Remark 16. For \(-1 \ll \alpha < 0\), by the same analysis, we can obtain the analogous results as those in Theorems 12-15. In fact, in the case we can reverse the time \(t\) and change \((x, y, u, v)\) to \((y, x, v, u)\), and then we still get \(0 < \alpha \ll 1\).

At last, we consider the case \(\alpha = 0\). By a similar process to that of Section 3, we obtain the bifurcation equations

\[
-\left(w^{12}_1\right)^{-1}s_1 + s_2 + \delta^{-1}M^1_1 v + \text{h.o.t.} = 0, \\
\left(w^{12}_2\right)^{-1}s_2 - s_1 + \delta^{-1}M^1_2 v + \text{h.o.t.} = 0.
\]

For the same reason as before, we have the following theorem.

Theorem 17. Suppose that \((H_1)-(H_5), \alpha = 0, \text{ and rank } (M^1_1, M^1_2) = 2\) hold; then,

1. as \(v \in R^1_\nu\), system (1) not only has a large 1-homoclinic orbit bifurcation surface

\[
w^{12}_2 M^1_1 v - M^1_1 v + \text{ h.o.t.} = 0,
\]

with a normal vector \((w^{12}_2 M^1_1 - M^1_1)\) at \(v = 0\), but also has another large 1-homoclinic orbit bifurcation surface

\[
w^{12}_1 M^1_1 v - M^1_2 v + \text{ h.o.t.} = 0;
\]

with a normal vector \((w^{12}_1 M^1_1 - M^1_2)\) at \(v = 0\),

2. as either \(w^{12}_1 w^{12}_2 < 1, M^1_1 v > w^{12}_1 M^1_1 v, \text{ and } w^{12}_1 M^1_2 v > M^1_2 v\) or \(w^{12}_1 w^{12}_2 > 1, M^1_1 v < w^{12}_1 M^1_1 v, \text{ and } w^{12}_1 M^1_2 v < M^1_2 v\), system (1) has a unique large 1-periodic orbit near \(\Gamma\).

Case 2 (\(\Delta_1 = -1, \Delta_2 = 1\) (i.e., single twisted)). Similar to Case 1, for convenience and simplicity, we use the following notations:

\[
\overrightarrow{R^1_1} = \{v : M^1_1 v < 0, M^1_2 v > 0, |M^1_1 v| = O(\{|M^1_1 v|\}, |v| \ll 1\}, \\
\overrightarrow{R^2_2} = \{v : M^1_1 v < 0, M^1_2 v > 0, |M^1_1 v| = O(\{|M^1_2 v|\}, |v| \ll 1\}, \\
\overrightarrow{D^2_1} = \{v : M^1_1 v > 0, M^1_2 v > 0, |v| \ll 1\}, \\
\overrightarrow{D^2_2} = \{v : M^1_1 v > 0, M^1_2 v < 0, |v| \ll 1\}.
\]

If (6) has a solution \(s_1 = s_2 = 0\), then we have

\[
M^1_i v + \text{h.o.t.} = 0, \quad i = 1, 2.
\]

If \(M^1_2 \neq 0\), then there exists a codimension 1 surface \(\Sigma_2\) with a normal vector \(M^1_1\) at \(v = 0\), such that the ith equation of (6) has solution \(s_1 = s_2 = 0\) as \(v \in \Sigma_2\) and \(|v| \ll 1\); that is, \(\Gamma_1\) is persistent. If \(\text{rank}(M^1_1, M^1_2) = 2\), then \(\Sigma_1 = \Sigma_2 \cap \Sigma_1\) is a codimension 2 surface with a normal plane \(\text{span}(M^1_1, M^1_2)\) such that (6) has solution \(s_1 = s_2 = 0\) as \(v \in \Sigma_1 \cup \Sigma_2\) and \(|v| \ll 1\); equivalently, the large loop \(\Gamma = \Gamma_1 \cup \Gamma_2\) is persistent.

Suppose that (6) has solution \(s_1 = s_2 > 0\). Then, we have

\[
s_2 = -\delta^{-1}M^1_1 v + \text{h.o.t.}, \\
0 = (w^{12}_2)^{-1}s_2 + \delta^{-1}M^1_2 v + \text{h.o.t.}
\]

Hence, we get the large 1-homoclinic orbit bifurcation surface equation

\[
\overrightarrow{H^2_2} : \delta^{-1}w^{12}_2 M^1_2 v + (-\delta^{-1}M^1_1 v)^{1+\alpha} + \text{h.o.t.} = 0,
\]

which is well defined at least in the region \(\overrightarrow{H^2_2}\) and has a normal vector \(M^1_2\) as \(\alpha > 0\) (resp., \(M^1_1\) as \(\alpha < 0\)) at \(v = 0\) such that the system (1) has a large 1-homoclinic loop \(\Gamma_2\) near \(\Gamma\) as \(v \in \overrightarrow{H^2_2}\).

It also means that \(\overrightarrow{H^2_1}\) is tangent to \(\Sigma_2\) as \(\alpha > 0\) (resp., \(\Sigma_1\) as \(\alpha < 0\)). When \(v \in \overrightarrow{H^2_2}\), \(\alpha > 0, s_1 = 0, \text{ and } s_2 = -\delta^{-1}M^1_1 v + \text{h.o.t.}\), (6) implies that

\[
s_{2v} = -\delta^{-1}M^1_1 \text{ v} + \text{h.o.t.},
\]

\[
s_{1v} = (1 + \alpha) (w^{12}_2)^{-1}(-\delta^{-1}M^1_1 v)^{\alpha} s_{2v} + \delta^{-1}M^1_2 v + \text{h.o.t.}
\]

Using (37) \(\times (1 + \alpha)(w^{12}_2)^{-1}(-\delta^{-1}M^1_1 v)^{\alpha}\) (38), we get

\[
s_{1v|_{\overrightarrow{H^2_2}}} = \delta^{-1}M^1_2 + O(|M^1_1 v|^{\alpha}).
\]

So, \(s_1 = s_1(v)\) increases along the direction of the gradient \(M^1_2\) for \(v\) near \(\overrightarrow{H^2_2}\).

Similarly, by setting \(\xi_{k} = e^{-\gamma_{k} t_{k}}\), we can derive that \(s_1(v)\) increases along the direction \(-M^1_1\) for near \(\overrightarrow{H^2_2}\) as \(\alpha > 0\).
If (6) has solution $s_1 > 0$ and $s_2 = 0$, then we get
\[
0 = (w_1^{12})^{-1}s_1^{1+\alpha} - \delta^{-1}M_1^1v + \text{h.o.t.},
\]
\[
s_1 = \delta^{-1}M_1^1v + \text{h.o.t.}
\] (40)

Therefore, we obtain the existence of the other large 1-homoclinic orbit bifurcation surface equation
\[
\mathcal{H}_1^1 : \delta^{-1}w_1^{12}M_1^1v + (\delta^{-1}M_1^1)^{1+\alpha} + \text{h.o.t.} = 0,
\] (41)

which is well defined at least in the region $\mathcal{R}_1^1$ and has a normal vector $M_1^1$ as $\alpha > 0$ (resp., $M_1^2$ as $\alpha < 0$) at $v = 0$ such that the system (1) has a large 1-homoclinic loop $\Gamma^1_1$ near $\Gamma$ as $v \in \mathcal{H}_1^1$. Thus, $\mathcal{H}_1^1$ is also tangent to $\Sigma_1$ as $\alpha > 0$ (resp., $\Sigma_2$ as $\alpha < 0$).

For $v \in \mathcal{H}_1^1$ and $\alpha > 0$, $s_1 = \delta^{-1}M_1^1v + \text{h.o.t.}$, $s_2 = 0$, it follows from (6) that
\[
s_2 = (1+\alpha)(w_1^{12})^{-1}(\delta^{-1}M_1^1)^{1+\alpha} s_1 - \delta^{-1}M_1^1 + \text{h.o.t.},
\]
\[
s_1 = -\delta^{-1}M_1^2 + \text{h.o.t.}
\] (42)
\[\textit{Computing (43) × (1 + \alpha)(w_1^{12})^{-1}(\delta^{-1}M_1^1)^{1+\alpha} + (42), leads to}
\]
\[
s_2|_{\mathcal{H}_1^1} = -\delta^{-1}M_1^1 + O\left(M_1^1|w_1^{12}|^{-1}\right).
\] (44)

So, $s_2 = s_2(v)$ increases along the direction $-M_1^1$ for $v$ close to $\mathcal{H}_1^1$.

By a similar procedure, we can show that $s_2(v)$ increases along the direction $M_1^2$ as $v$ is in the neighborhood of $\mathcal{H}_1^1$ and $\alpha < 0$.

Summarizing the previous analysis, we have the following theorem.

**Theorem 18.** Suppose that $(H_1)$–$(H_5)$ hold; then, the following conclusions are true.

(1) If $M_1^1 \neq 0$, then there exists a unique surface $\Sigma_1$ with codimension 1 and normal vectors $M_1^1$ at $v = 0$, such that system (1) has a homoclinic loop near $\Gamma$ if and only if $v \in \Sigma_1$ and $|v| < 1$. If rank $(M_1^1, M_1^2) = 2$, then $\Sigma_1 \cap \Sigma_2$ is a codimension 2 surface and $0 \in \Sigma_1$ such that system (1) has a large loop consisting of two homoclinic orbits near $\Gamma$ as $v \in \Sigma_1$ and $|v| < 1$; that is, $\Gamma$ is persistent.

(2) In the region $\mathcal{R}_1^1$, there exists a unique large 1-homoclinic orbit bifurcation surface $\mathcal{H}_1^1$, which is tangent to $\Sigma_1$ (resp., $\Sigma_2$) at $v = 0$ with the normal vector $M_1^1$ (resp., $M_1^2$) as $\alpha > 0$ (resp., $\alpha < 0$), and for $v \in \mathcal{H}_1^1$, system (1) has a unique large 1-homoclinic orbit near $\Gamma$. Furthermore, the unique large 1-homoclinic orbit near $\Gamma$ becomes a large 1-periodic orbit when $v$ moves along the direction $M_1^1$ (resp., $-M_1^2$) and nearby $\mathcal{H}_1^1$ as $\alpha > 0$ (resp., $\alpha < 0$). In the region $\mathcal{R}_1^1$, there exists another unique large 1-homoclinic orbit bifurcation surface $\mathcal{H}_1^2$ which is tangent to $\Sigma_1$ (resp., $\Sigma_2$) at $v = 0$ with the normal $M_1^2$ (resp., $M_1^1$) as $\alpha > 0$ (resp., $\alpha < 0$), and for $v \in \mathcal{H}_1^2$, system (1) has another unique large 1-homoclinic orbit near $\Gamma$.

**Lemma 19.** Suppose that hypotheses $(H_1)$–$(H_5)$ and $0 < \alpha \ll 1$ are valid; system (1) has only a unique large 1-homoclinic orbit $\Gamma_1^1$ near $\Gamma$ for $v \in \mathcal{H}_1^2$ and $0 < |v| < 1$.

**Proof.** If $v \in \mathcal{H}_1^2$ and $|v| < 1$, from Theorem 18, we know that system (1) has only one large 1-homoclinic loop $\Gamma_2^1$. Now, following (6), we have
\[
\left[(w_1^{12})^{-1} s_1^{1+\alpha} - \delta^{-1}M_1^1v + \text{h.o.t.}\right]^{1+\alpha} = w_2^{12} s_1 - \delta^{-1}w_2^{12}M_1^1v + \text{h.o.t.}
\] (45)

Let $N_1(s_1)$ and $L_1(s_1)$ be the left- and right-hand sides of (45), respectively. Then, by (36), we get $N_1(0) = L_1(0)$ as $v \in \mathcal{H}_1^2$. Moreover,
\[
N_1'(s_1) = (1 + \alpha)^2\left((w_1^{12})^{-1}\left[(w_1^{12})^{-1}s_1^{1+\alpha} - \delta^{-1}M_1^1v + \text{h.o.t.}\right]^{1+\alpha}\right) s_1,
\]
\[
L_1'(s_1) = w_2^{12} + \text{h.o.t.}
\] (46)

Thus, $N_1'(s_1) \leq 0 < L_1'(s_1)$, and $N_1''(s_1) < 0$. Therefore, $N_1(s_1) < L_1(s_1)$ for $s_1 \neq 0$, as shown in Figure 6.

Therefore, system (1) has only a unique large 1-homoclinic orbit near $\Gamma$ for $v \in \mathcal{H}_1^2$ and $0 < |v| < 1$.

**Remark 20.** Due to $N_1''(s_1) < 0$, we can see that the line $N_1(s_1)$ lies under the curve $L_1(s_1)$ as $v \in \mathcal{H}_1^2$. Moreover, $L_1(0) = -\delta^{-1}w_2^{12}M_1^1v + \text{h.o.t.}$ decreases as rank($M_1^1, M_1^2) = 2$ and $v$ moves along the direction $M_1^2$; in this case, system (1) has a unique large 1-periodic orbit. And as $v$ leaves $\mathcal{H}_1^2$ along the opposite direction, there is no large 1-periodic orbit.

By a similar analysis as in Lemma 19, we can obtain the following results.

**Lemma 21.** Suppose that hypotheses $(H_1)$–$(H_5)$ and $0 < \alpha \ll 1$ are valid; system (1) has only a unique large 1-homoclinic orbit $\Gamma_1^1$ near $\Gamma$ for $v \in \mathcal{H}_1^1$ and $0 < |v| < 1$.

**Remark 22.** Let $N_2(s_2) = [(w_1^{12})^{-1}s_2^{1+\alpha} + \delta^{-1}M_1^1v + \text{h.o.t.}]^{1+\alpha}$ and $L_2(s_2) = w_1^{12}s_2 + \delta^{-1}w_1^{12}M_1^1v + \text{h.o.t.}$ Due to $N_2''(s_2) > 0$ and $L_2(0) = -\delta^{-1}w_1^{12}M_1^1v + \text{h.o.t.}$, we claim that the line
Theorem 23. Suppose that hypotheses \((H_1)-(H_5)\) hold, \(0 < \alpha < 1\), \(\nu \in R_2^1\). Then, system (1)

1. does not have any large 1-periodic orbit and large 1-homoclinic loop near \(\Gamma\) as \(\nu \in (\overline{R}_2^1)_0\);
2. has a unique large 1-homoclinic loop near \(\Gamma\) as \(\nu \in \overline{H}_1^1\);
3. has a unique large 1-periodic orbit near \(\Gamma\) as \(\nu \in (\overline{R}_2^1)_1\).

Theorem 24. Suppose that hypotheses \((H_1)-(H_5)\) hold, \(0 < \alpha < 1\), \(\nu \in \overline{R}_1^1\). Then, system (1)

1. has no large 1-periodic orbit and large 1-homoclinic loop near \(\Gamma\) as \(\nu \in (\overline{R}_1^1)_0\);
2. has a unique large 1-homoclinic loop near \(\Gamma\) as \(\nu \in \overline{H}_1^1\);
3. has a unique large 1-periodic orbit near \(\Gamma\) as \(\nu \in (\overline{R}_1^1)_1\).

From the bifurcation equations, we have the following theorem easily.

Theorem 25. Suppose that hypotheses \((H_1)-(H_5)\) hold, and \(0 < \alpha < 1\). Then, system (1)

1. has no large 1-periodic orbit near \(\Gamma\) as \(\nu \in D_2^2\);
2. has no large 1-periodic orbit near \(\Gamma\) as \(\nu \in \overline{D}_2^1\).

Remark 26. For \(-1 < \alpha < 0\), by the same analysis, we can obtain the analogous results as those in Theorems 23–25. In fact, in the case we can reverse the time \(t\) and change \((x, y, u, \nu)\) to \((y, x, \nu, u)\), and then we still get \(0 < \alpha < 1\).

At last, we consider the case \(\alpha = 0\). By a similar process to that of Section 3, we obtain the bifurcation equations

\[(\omega_1^{12})^{-1}s_1 + s_2 + \delta^{-1}M_1^1\nu + \text{h.o.t.} = 0, \quad (\omega_2^{12})^{-1}s_2 - s_1 + \delta^{-1}M_2^1\nu + \text{h.o.t.} = 0.\]  

(47)

For the same reason as before, we have the following theorem.

Theorem 27. Suppose that \((H_1)-(H_5), \alpha = 0,\) and rank\((M_1^1, M_2^1) = 2\) hold; then,

1. as \(\nu \in \overline{R}_2^1\), system (1) has a unique large 1-homoclinic orbit bifurcation surface

\[w_1^{12}M_1^1\nu - M_2^1\nu + \text{h.o.t.} = 0,\]  

(48)

with a normal vector \((w_1^{12}M_1^1 - M_2^1)\) at \(\nu = 0\);
2. as \(\nu \in \overline{R}_1^1\), system (1) also has a unique large 1-homoclinic orbit bifurcation surface

\[w_1^{12}M_1^1\nu - M_2^1\nu + \text{h.o.t.} = 0,\]  

(49)

with a normal vector \((w_1^{12}M_1^1 - M_2^1)\) at \(\nu = 0\);
3. as \(M_1^1\nu < w_1^{12}M_1^1\nu\) and \(w_1^{12}M_1^1\nu > M_2^1\nu\), system (1) has a unique large 1-periodic orbit near \(\Gamma\).

Remark 28. As \(\Gamma_1\) is nontwisted and \(\Gamma_2\) is twisted, we can obtain similar conclusions as shown in Case 2.
4. Conclusion

This paper is devoted to investigating the twisting bifurcations of double homoclinic loops with resonant eigenvalues in 4-dimensional systems. We give asymptotic expressions of the bifurcation surfaces and their relative positions, describe the existence regions of large 1-periodic orbits near $\Gamma$ in Lemmas 3 and 8, and obtain the sufficient conditions for the existence or nonexistence of saddle-node bifurcation surfaces in Lemmas 3 and 8. More importantly, the complete bifurcation diagrams are given under different cases in Figures 4, 5, and 7. According to our analysis, when $\Gamma$ is double twisted, in Theorems 12–15, we obtain one bifurcation diagram with saddle-node bifurcation surfaces of large 1-periodic orbit when $w_1^{12}w_2^{12} < 1$ and the other bifurcation diagram without saddle-node bifurcation surfaces when $w_1^{12}w_2^{12} > 1$. When $\Gamma$ is single twisted, in Theorems 23–25, we obtain another bifurcation diagram. Compared with the nontwisted cases in Zhang et al. [32], our paper shows completely different results and bifurcation diagrams. It is worthy to be mentioned that the restriction on the dimension is not essential, the method used in this paper can be extended to higher dimensional systems without any difficulty, and the same conclusions can be deduced under the same hypotheses. Furthermore, we mention some problems for future study. (1) $W^s$ or $W^u$ is inclination flip on one of the double homoclinic loops. (2) Both $W^s$ and $W^u$ are inclination flips on the double homoclinic loops and so on. But the difficulty of these problems will increase with adding codimension of the double homoclinic loops.

Acknowledgments

The research was supported by National Natural Science Foundation of China (nos. 11001041, 1101170, 11202192, 11271065 and 10926105), SRFDP (no. 200802001008), and the State Scholarship Fund of the China Scholarship Council (nos. 2011662521, and 2011842509).

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