

MA2341 - Advanced Mechanics 1
Michelmas Term - 2015-2016
Homework 4 - Due Nov. 3rd, 2015

1. It is often difficult to get non-conservative forces into the Lagrangian formalism. However, we may always simply add a non-conservative component to the generalized force term in the Euler-Lagrange equations. Consider a system where the Cartesian components of the force have both conservative and dissipative parts:

$$F_i = -\frac{\partial V}{\partial x_i} + F_i^{diss},$$

where F_i^{diss} is not derivable from a potential. Suppose we wish to describe the system using $N \leq 3$ scleronomic generalized coordinates q_r , $r = 1, \dots, N$, so that the Cartesian coordinates can be expressed as

$$x_i = x_i(q_r).$$

The Euler-Lagrange equations in the presence of this dissipative force now become:

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_r} - \frac{\partial L}{\partial q_r} = Q_r^{diss}, \quad Q_r^{diss} = F_i^{diss} \frac{\partial x_i}{\partial q_r}.$$

- (a) Consider *Rayleigh's dissipation function* $K(\dot{x}_i)$ defined as

$$F_i^{diss} = -\frac{\partial K}{\partial \dot{x}_i}.$$

Show that the Euler-Lagrange equations can be written as

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_r} - \frac{\partial L}{\partial q_r} + \frac{\partial K}{\partial \dot{q}_r} = 0.$$

- (b) Consider a simple pendulum moving in a viscous fluid such that the dissipative 'drag' force is

$$F_i^{diss} = -k\dot{x}_i.$$

Find the dissipation function $K(\dot{\theta})$ and the equation of motion.

2. Consider a spherical pendulum with mass m and length ℓ . A spherical pendulum is like a simple pendulum, except the motion is no longer restricted to a plane.

- (a) Find the lagrangian and equations of motion.
- (b) What (if any) quantities are conserved?
- (c) In what limit is the equation of motion for the ordinary plane pendulum recovered?

3. Consider the lagrangian for two degrees of freedom $\{q_1(t), q_2(t)\}$

$$L = \frac{m}{2}(a\dot{q}_1^2 + 2b\dot{q}_1\dot{q}_2 + c\dot{q}_2^2) - \frac{k}{2}(aq_1^2 + 2bq_1q_2 + cq_2^2)$$

where a, b , and c are arbitrary, but $b^2 - ac \neq 0$. Suppose q_1 and q_2 are sclerononomous generalized coordinates, so that the two-dimensional cartesian coordinates can be expressed as

$$x_i = x_i(q_1, q_2), \quad i = 1, 2.$$

- (a) Determine such a coordinate transformation so that the lagrangian expressed in terms of $x_1(t)$ and $x_2(t)$ can be ‘decoupled’, i.e. written as

$$L[x_1, x_2, \dot{x}_1, \dot{x}_2] = L_1[x_1, \dot{x}_1] + L_2[x_2, \dot{x}_2].$$

- (b) What physical system does this lagrangian describe? What is the purpose of the condition $b^2 - ac \neq 0$?